# Entropy stable schemes for initial-boundary-value conservation laws 

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# Entropy stable schemes for initial-boundary-value conservation laws 

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#### Abstract

We consider initial boundary value problems for systems of conservation laws and design entropy stable finite difference schemes to approximate them. The schemes are shown to be entropy stable for a large class of systems that are equipped with a symmetric splitting, derived from the entropy formulation. Numerical examples for the Euler equations of gas dynamics are presented to illustrate the robust performance of the proposed method.


Keywords: finite difference schemes; conservation laws; boundary conditions

## 1 Introduction

We consider systems of conservation laws in one space dimension:

$$
\begin{align*}
u_{t}+f(u)_{x} & =0, \quad x \in(0,1)  \tag{1}\\
u(x, 0) & =u^{0}(x), \\
L_{b}(u) & =\left(g_{l}(t), g_{r}(t)\right)^{\top} .
\end{align*}
$$

Here $u=\left(u_{1}, \ldots, u_{n}\right)^{\top}$ is the vector of unknowns and the fluxes $f=\left(f_{1}, f_{2}, \cdots, f_{n}\right)^{\top}$ are Lipshitz continuous functions of $u$. The expression $L_{b}$ is an operator that enforces boundary conditions (weakly) at $x=0,1$ using data $g_{l, r}(t)$. The precise action of this operator will be specified later.

A prototypical example for the system of conservation laws (1) is provided by the Euler equations of gas dynamics:

$$
\begin{array}{r}
u_{t}+f(u)_{x}=0  \tag{2}\\
u=(\rho, m, E)^{T} \\
f(u)=\left(m, \rho q^{2}+P,(E+P) q\right)^{T} \\
P=(\gamma-1)\left(E-\frac{1}{2} \rho q^{2}\right) .
\end{array}
$$

[^1]$\rho, q, P$ and $E$ are the density, velocity, pressure and total energy of a gas. The momentum is denoted as $m=\rho q$ and $\gamma$ the ratio of the specific heats.

Solutions to (1) generally have to be interpreted in a weak sense. A weak solution of the conservation law (1) is defined below.

Definition A locally integrable function $u$ is defined as a weak solution to (1) if it satisfies the following integral identity for all $\varphi \in C_{0}^{\infty}\left((0,1) \times R_{+}\right)$,

$$
\begin{equation*}
\int_{R_{+}} \int_{0}^{1} u \cdot \varphi_{t}+f(u) \cdot \varphi_{x} d x d t+\int_{0}^{1} u_{0}(x) \cdot \varphi(x, 0) d x=0 \tag{3}
\end{equation*}
$$

Weak solutions are not unique and to single out the physically relevant solution, an extra, so-called entropy condition, is necessary. We will use the following form of the entropy condition,

Definition Let $(E, F)$ be any pair of smooth functions such that $E$ is strictly convex and $F_{u}=E_{u} f_{u}$. Such a pair of functions is defined as an entropy-entropy flux pair. Then, $u \in L_{\mathrm{loc}}^{1}\left((0,1) \times R_{+}\right)$is an entropy solution of (1) if for all entropy-entropy flux pairs, $(E, F)$, and for all $0 \leq \varphi \in C_{0}^{\infty}\left((0,1) \times R_{+}\right)$, the following inequality holds,

$$
\begin{equation*}
\int_{R_{+}} \int_{0}^{1} E(u) \varphi_{t}+F(u) \varphi_{x} d x d t \geq 0 \tag{4}
\end{equation*}
$$

Stability and convergence of numerical approximations to (systems of) conservation laws has been the subject of intensive study for decades but generally applicable results for systems remain elusive. From the numerical perspective, stability (in a sufficiently strong sense) is the single most important aspect for the reliability of numerical results. Stability is also the key to prove convergence of numerical solutions.

For Cauchy problems, there are several successful schemes that guarantee convergence of scalar conservation laws. They include the so called E-schemes for scalar conservation laws (see for example [Tad06]). The stability of Eschemes for scalar conservation laws, originates from a locally satisfied entropy inequality, valid for all possible entropy pairs. Scalar conservation laws are equipped with an inifinite number of entropy pairs which can be used to prove a sufficiently strong stability result such that convergence follows. Systems, however, generally lack this richness of entropies and the E-scheme requirement is less natural. Nevertheless, there have been efforts to generalize E-schemes to systems of conservation laws, [Bar06].

A less restrictive way to construct schemes, for scalar equations or systems, is to make them satisfy a local entropy inequality for one particular entropy. Such schemes are termed entropy stable. (See [Tad06].) For the canonical example, the Euler equations of gas dynamics (2), entropy stability implies an $L^{2}$ bounds on the solution as long as the density $\rho$ remains positive.

Most rigorous results on the stability and convergence of numerical schemes for conservation laws are available for the Cauchy problem. For the initial boundary value problem corresponding to (1), stability and convergence results for monotone (first-order) numerical schemes approximating scalar conservation laws in several space dimensions was obtained by Coquel, Cockburn and LeFloch in [CCL95]. The authors heavily used the monotonicity of the corresponding
solution operator in their analysis. Our aim in this paper is to obtain stability results for a system of conservation laws. As the solution operator is not necessarily monotone, the arguments of [CCL95] are no longer applicable. Before describing stable numerical schemes for the initial boundary value problem for systems, we discuss some theoretical results below.

In DuBois and Le Floch [BF88], the continuous problem (1) was studied and, under sufficiently strong stability assumptions, the following boundary entropy inequality was obtained.

$$
\begin{equation*}
F\left(u_{0}\right)-F(g)-E_{u}(g)\left(f\left(u_{0}\right)-f(g)\right) \leq 0 \tag{5}
\end{equation*}
$$

where $g$ is the boundary data at $x=0$ and $u_{0}$ the solution at the same point. Any numerical scheme devised for the initial-boundary-value problem should converge to a solution satisfying this inequality. However, this result sheds no light on how such a solution can be generated.

In Olsson and Oliger [OO94], the initial-boundary-value problem was analyzed. They used the so called canonical splitting (later termed entropy splitting) in order to obtain energy estimates (or global entropy estimates), but at the expense of sacrificing the conservative form. To this end, they demand the flux function to satisfy a so called cone condition, which can be verified in certain important cases. For scalar conservation laws this technique resulted in standard $L^{p}$ estimates for the solution variable. For systems, however, the estimate requires the assumption that the signal speeds of the in-going characteristics are bounded by data. It is difficult to see that this assumption is valid in general. Another slight drawback is that the entropies they adopt do not symmetrize the heat flux in the Navier-Stokes equations. In a series of papers, Olsson and Gerritsen use this form, discretized with Summation-by-parts finite difference schemes and a boundary projection method for imposing boundary conditions. As a result they obtain stable schemes for the Euler equations including the boundaries, although not on conservative form. (See [Ols95a, Ols95b, GO96, GO98].)

The entropy splitting used by the above authors introduces a non-conservative term which causes problem when discontinuous solutions are sought. In Hou and Le Floch [HF94], it was shown that a non-conservative term generates a Borel measure source term at discontinuities. This source term produces an error that grows linearly in time and causes the shock location to drift (independent of the grid resolution).

Our aim is to design a conservative scheme and prove a global entropy bound including the boundaries. We will also require that local entropy inequalities are satisfied and that the converged limit solution satisfies Du Bois and Le Floch's boundary entropy inequality. To achieve this, we start with the results by Olsson and Oliger since these are the only global stability results available for an initial-boundary-value problem for systems of conservation laws. In Section 3, we will derive a suitable weak imposition of boundary conditions, including both characteristic type and no-penetration wall conditions, and show that a bound on the entropy is achieved without the cone condition or any assumption on the signal speed. The key to these proofs is to utilize the specific entropy pair introduced in [OO94, GO98].

Our main result is the derivation of a conservative entropy stable scheme on a bounded domain. We exploit the specific entropy-pair from [OO94, GO98] and show that the diffusion needed for entropy stability in the Cauchy case, is
sufficient to obtain a global bound. Furthermore, we prove that the numerical solution satisfies local entropy inequalities and test numerically that Du Bois and Le Floch's boundary entropy inequality is satisfied.

To the best of our knowledge, these are the first stability results for a numerical scheme approximating systems of conservation laws on a bounded domain.

## 2 The entropy pair

The key to obtain a global estimate, as observed in [OO94] is the use of a specific entropy pair and in this section we will introduce this entropy and derive a few auxiliary relations.

Mock [Moc80] showed that a conservation law can be symmetrized by its entropy pair. The conservation law

$$
\begin{equation*}
u_{t}+f(u)_{x}=0 \tag{6}
\end{equation*}
$$

turns into

$$
\begin{equation*}
u_{w} w_{t}+G(w)_{x}=0 \tag{7}
\end{equation*}
$$

where $u_{w}$ is symmetric positive definite and $G_{w}(w)$ is symmetric. We will use entropy (canonical) splitting proposed in [OO94], which is based on a well-known one-thirds rule for Burgers' equation.

We begin by stating standard results for entropy solutions. For the entropypair $(E, F)$ we have that $E_{t}=E_{u}^{T} u_{t}$ and $E_{u}^{T} f_{u}=F_{u}$ by definition. Furthermore, the entropy variables are defined as $E_{u}=w$ and $f(u)=G(w)$ such that $G_{w}$ is symmetric. Hence, we multiply (6), or equivalently (7), by $E_{u}^{T}=w^{T}$ such that

$$
\begin{equation*}
E_{t}+w^{T} G(w)_{x}=0 \tag{8}
\end{equation*}
$$

Here, we use the idea put forward in [OO94]. $G_{w}$ is symmetric and we can define

$$
\begin{equation*}
\mathcal{G}(w)=\int_{0}^{1} G(\theta w) d \theta \tag{9}
\end{equation*}
$$

which satisfies

$$
\begin{equation*}
G_{x}=(G-\mathcal{G})_{x}+\mathcal{G}_{x}=\left(\mathcal{G}_{w} w\right)_{x}+\mathcal{G}_{w} w_{x} \tag{10}
\end{equation*}
$$

which they term the "canonical splitting". The symmetry of $G^{\prime}$ implies symmetry of $\mathcal{G}^{\prime}$. Furthermore, for any flux that flux satisfies $G^{\prime}=G^{\prime T}$ and

$$
\begin{equation*}
G^{\prime} w=p G, \quad p \in \mathbf{R} \tag{11}
\end{equation*}
$$

the following relations hold:

$$
\begin{equation*}
\mathcal{G}=\frac{1}{p+1} G, \quad \mathcal{G}^{\prime}=\frac{1}{p+1} G^{\prime} \tag{12}
\end{equation*}
$$

Unfortunately, the above does not hold for the Euler equations (2) unless very specific entropy variables are used. (See [Ger96] and for completeness we include their results in Appendix I.) In addition to the above relations, this particular entropy pair also implies

$$
\begin{equation*}
u_{w} w=p u \tag{13}
\end{equation*}
$$

### 2.1 Auxiliary relations

From now on, we will only consider entropy pairs that satisfy (11) and (13). In particular, we will assume that $p=1$ although this requirement is strictly not necessary.

Lemma 2.1 Let $F(w)$ denote the entropy flux and $w$ the entropy variables that make the flux function $G(w)$ homogeneous of order 1 (i.e. (11) with $p=1$ ). Then

$$
F(b)-F(a)=\left.\frac{1}{2} w^{T} G_{w} w\right|_{a} ^{b}
$$

Proof By the definition of an entropy flux, $F_{x}=w^{T} G_{x}$, but $w^{T} G_{x}=w^{T}\left(\mathcal{G}_{w} w\right)_{x}+$ $w^{T} \mathcal{G}_{w} w_{x}$. Then

$$
\begin{aligned}
\int_{a}^{b} F_{x} d x & =\int_{a}^{b} w^{T}\left(\mathcal{G}_{w} w\right)_{x}+w^{T} \mathcal{G}_{w} w_{x} d x \\
F(b)-F(a) & =\left.w^{T} \mathcal{G}_{w} w\right|_{a} ^{b}=\left.\frac{1}{2} w^{T} G_{w} w\right|_{a} ^{b}
\end{aligned}
$$

Lemma 2.2 Let $F(w)$ denote the entropy flux, $\Psi(w)=\langle w, f\rangle-F(w)$ the entropy potential and $w$ the entropy variables that make the flux function $G(w)$ homogeneous of order 1. Then

$$
\begin{aligned}
& \Psi(w)=\frac{1}{2} w^{T} G_{w}(w) w \\
& F(w)=\frac{1}{2} w^{T} G_{w}(w) w
\end{aligned}
$$

Proof

$$
\begin{aligned}
\Psi(a) & = \\
\Psi(a)-(\Psi(b)-\Psi(b)) & = \\
\Psi(a)-\left(w^{T}(b) G_{w}(b) w(b)-F(b)-\Psi(b)\right) & = \\
w^{T}(a) G_{w}(a) w(a)-F(a)-\left(w^{T}(b) G_{w}(b) w(b)-F(b)-\Psi(b)\right) & = \\
\left.\frac{1}{2}\left(w^{T}(a) G_{w}(a) w(a)-w^{T}(b) G_{w}(b) w(b)\right)+\Psi(b)\right) &
\end{aligned}
$$

In the last equality we use Lemma 2.1. The final expressions is a sum of two functions. One only depending on $a$ and the other only on $b$. Hence we are forced to conclude that,

$$
\begin{array}{r}
\Psi(a)=\frac{1}{2} w^{T}(a) G(a) w(a) \\
-\frac{1}{2} w^{T}(b) G_{w}(b) w(b)+\Psi(b)=0
\end{array}
$$

which proves the first relation in the lemma. The second part follows directly from the identity $\Psi=w^{T} G-F$.

## 3 Stable boundary conditions

Equipped with the particular entropy-pair described above we will derive a formal global entropy estimate for smooth solutions where the skew-symmetric splitting can be used. The purpose of this analysis is to derive a stable form of boundary conditions for a non-linear conservation law.

Since the solution is assumed to be smooth, we may use (10) in (8), which yields

$$
\begin{align*}
& \int_{0}^{1} E_{t} d x=-\int_{0}^{1} w^{T}\left(\left(\mathcal{G}_{w} w\right)_{x}+\mathcal{G}_{w} w_{x}\right) d x= \\
- & \int_{0}^{1} w^{T}\left(\left(\mathcal{G}_{w} w\right)_{x}+\mathcal{G}_{w} w_{x}\right) d x=-\left.w^{T} \mathcal{G}_{w} w\right|_{0} ^{1}=-\left.\frac{1}{2} w^{T} G_{w} w\right|_{0} ^{1} \tag{14}
\end{align*}
$$

To obtain a bound on the boundary terms, we must introduce the boundary conditions appropriately. To this end, we introduce $G_{w}=A=R^{T} \Lambda R$, where $\Lambda$ is the diagonal eigenvalue matrix, with $\lambda_{i} \in \mathbf{R}$ and $R^{T} R=I$ due to the symmetry of $G_{w}$. Furthermore, we denote $A^{+}=R^{T} \Lambda^{+} R$ where $\Lambda^{+}$contains only the positive entries of $\Lambda$. We will also use the notation $|A|=R^{T}|\Lambda| R$ and the specific case $G_{w}(g)=A_{g}=R_{g}^{T} \Lambda_{g} R_{g}$.

For simplicity, we focus on the quarter-plane problem and ignore the right boundary by considering the following modification of (1):

$$
\begin{equation*}
u_{t}+f_{x}=\sigma \delta_{0}(x) A^{+}(w)\left(w-w_{g}\right) \quad 0 \leq x<\infty \tag{15}
\end{equation*}
$$

where $\delta_{0}$ denotes the Dirac delta function with its mass at $x=0$ and $w_{g}=w(g)$ is the entropy variables with respect to the boundary data $g(t)$ at $x=0$.

We remark that the addition of a measure source term at the boundary is a way to weakly impose the boundary condition in (1) at the left boundary. We also assume that the initial conditions have compact support.

Theorem 3.1 If $u$ is a continuously differentiable solution, then equation (15) satifies a global entropy estimate with $\sigma=-1$. Moreover, the correct number of boundary conditions, as dictated by the linearized equation, are enforced.

Proof Changing variables to the entropy form, multiplying by $w^{T}$, utilizing the canonical splitting and $\sigma=-1$, we arrive at

$$
\int_{0}^{\infty} E_{t} d x-\left.\frac{1}{2} w^{T} G_{w} w\right|_{0}=-\left.w^{T} \tilde{A}^{+}\left(w-w_{g}\right)\right|_{0}
$$

Dropping the index since all boundary terms are at $x=0$, we need to prove that

$$
\begin{equation*}
\widehat{B T}=\frac{1}{2} w^{T} G_{w} w-w^{T} A_{0}^{+}\left(w-w_{g}\right) \tag{16}
\end{equation*}
$$

is bounded. We use the notation $G_{w}(w(0, t))=A_{0}$. Rewriting (16),

$$
\begin{array}{r}
\widehat{B T}=\frac{1}{2} w^{T} A_{0} w-w^{T} A_{0}^{+}\left(w-w_{g}\right)= \\
\frac{1}{2} w^{T} A_{0}^{-} w-\frac{1}{2} w^{T} A_{0}^{+} w+w^{T} A_{0}^{+} w_{g}= \\
\frac{1}{2} w^{T} A_{0}^{-} w-\frac{1}{2}\left(w-w_{g}\right)^{T} A_{0}^{+}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} A_{0}^{+} w_{g} \tag{17}
\end{array}
$$

In the last expression, the first two terms are negative and do not imply a growth of $w_{0}$. The requirement for stability is that $B T$ has an upper bound. Before, treating the general case, we note that in 3 cases a bound on $B T$, and hence stability, follows immediately. 1) If $A_{0}^{+}$is bounded (as in the linear case), the last term implies a finite growth (which is acceptable). 2) A bound is also readily obtained for a non-linear system, if $w_{g}=0$. 3) In the scalar case, a direct calculation shows that

$$
\begin{equation*}
-\frac{1}{2}\left(w-w_{g}\right)^{T} A_{0}^{+}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} A_{0}^{+} w_{g}<\text { Constant } \tag{18}
\end{equation*}
$$

for all $|w|$ large enough.
Next, we prove the result in the general case of a system of conservation laws. We need to show that there is a constant $C>0$ such that for all $w$ with $|w|>C$, there exists a constant $\widehat{C}=\widehat{C}\left(C, w_{g}\right)$ such that

$$
\begin{equation*}
B T\left(w, w_{g}\right)=-\frac{1}{2}\left(w-w_{g}\right)^{T} A^{+}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} A^{+} w_{g}<\widehat{C} \tag{19}
\end{equation*}
$$

Here, we have suppressed the subscript 0 for the matrices for notational convenience.

Recall that $A=R \Lambda R^{T}$ is an orthogonal eigendecomposition of the symmetric matrix $A=G_{w}\left(w_{0}\right)$ with $\Lambda=\operatorname{diag}\left(\lambda_{1}, \cdots, \lambda_{n}\right)$ and $R=\left[r_{1}|\cdots| r_{n}\right]$ with $\lambda_{i}$ and $r_{i}$ being the $i$-th eigenvalue and eigenvector, respectively.

Without loss of generality, let $\lambda_{1}$ be the growing eigenvalue i.e,

$$
\left|\lambda_{1}(w)\right| \rightarrow \infty \quad \text { as } \quad|w| \rightarrow \infty
$$

Furthermore, we assume that other eigenvalues are bounded. The argument below is easy to generalize to the case where some or all the eigenvalues satisfy the above growth condition.

Denote

$$
\Lambda_{1}=\operatorname{diag}\left(\lambda_{1}, 0, \cdots, 0\right)
$$

We decompose $A$ as $A=\tilde{A}+A_{1}$ with $A_{1}=R \Lambda_{1} R^{T}$ and denote,

$$
\begin{aligned}
B T_{1} & =-\frac{1}{2}\left(w-w_{g}\right)^{T} A_{1}^{+}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} A_{1}^{+} w_{g} \\
\tilde{B T} & =-\frac{1}{2}\left(w-w_{g}\right)^{T} \tilde{A}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} \tilde{A} w_{g}
\end{aligned}
$$

From (19), we obtain that $B T=B T_{1}+\tilde{B T}$.
From our assumptions $\tilde{A}$ is bounded as $|w| \rightarrow \infty$. Therefore, it is easy to check that there exists a constant $\tilde{C}$ such that

$$
\begin{equation*}
\tilde{B T}<\tilde{C}, \tag{20}
\end{equation*}
$$

for all $w$ such that $|w|>C$. The estimate (20) follows as the negative term in $\tilde{B T}$ grows quadratically where as the positive term is bounded.

Next, we consider the term $B T_{1}$. A direct calculation with the definitions of $A_{1}$ shows that

$$
\begin{aligned}
B T_{1} & =-\frac{1}{2}\left(w-w_{g}\right)^{T} A_{1}^{+}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} A_{1}^{+} w_{g} \\
& =-\frac{1}{2}\left(w-w_{g}\right)^{T} R \Lambda_{1} R^{T}\left(w-w_{g}\right)+\frac{1}{2} w_{g}^{T} R \Lambda_{1} R^{T} w_{g}
\end{aligned}
$$

Therefore, if $B T_{1} \rightarrow \infty$, then the condition

$$
\begin{equation*}
\left|r_{1}^{T}\left(w-w_{g}\right)\right|<\left|r_{1}^{T} w_{g}\right| . \tag{21}
\end{equation*}
$$

must be satisfied. As the eigenvectors are normalized, $r_{1}$ is bounded. Hence, the condition (21) is violated when $|w|$ grows such that $\left|r_{1}^{T} w\right| \rightarrow \infty$ as the left hand side in (21) grows linearly whereas the right hand side is bounded. In this case, we conclude that $B T_{1}$ is bounded. A growth in any other direction than $r_{1}$ is bounded by (20). In summary, we conlcude that (19) is satisfied.

The above argument can be easily iterated when more than one of the eigenvalues of $A$ grows by including more eigenpairs in $B T_{1}$.

Finally, we note that the boundary conditions for the ingoing characteristics are enforced, which is consistent with linear theory for well-posedness.

Most existing codes for the Euler equations use the conservative variables as opposed to the entropy variables. Hence, we will connect the two forms and state the scheme in the conservative form.

$$
\begin{equation*}
u_{t}+f_{x}=\sigma \delta_{0}(x) \mathbb{A}^{+}(u-g) \quad 0 \leq x<\infty \tag{22}
\end{equation*}
$$

where $\mathbb{A}$ is the Jacobian matrix for the conservative variables and $\mathbb{A}^{+}$its positive part determined from the eigenvalues.

Theorem 3.2 Under the same conditions as in Theorem 3.1, (22) satisfies a global entropy bound (with the correct number of boundary conditions).

Proof First a few auxiliary relations found in [Tad06]. Denote, $u_{w}=H, f_{u}=\mathbb{A}$ and $\mathbb{B}=G_{w}$ such that $G_{w}=\mathbb{B}=\mathbb{A} H=f_{u} u_{w}$. With our particular entropypair, we have $H^{-1} u=w$. Since $B$ and $H$ are symmetric it follows that

$$
\begin{equation*}
H^{-1 / 2} \mathbb{A} H^{1 / 2}=H^{-1 / 2} \mathbb{B} H^{-1 / 2} \tag{23}
\end{equation*}
$$

is symmetric.
Furthermore, denote by $\lambda_{k}$ the $k$ th eigenvalue of $A$ and $r_{k}$ its eigenvector, such that $A r_{k}=\lambda_{k} r_{k}$. Clearly, the following holds

$$
\begin{equation*}
H^{-1 / 2} \mathbb{A} H^{1 / 2}\left(H^{-1 / 2} r_{k}\right)=\lambda_{k} H^{-1 / 2} r_{k} \tag{24}
\end{equation*}
$$

such that after normalization $\left(\lambda_{k}, H^{-1 / 2} r_{k}\right)$ becomes the eigensystem of $H^{-1 / 2} \mathbb{A} H^{1 / 2}$.
Next, we turn to (22) and multiply by $w^{T}$. Jumping a few steps similar to the previous proof, we must bound

$$
\begin{aligned}
\mathbb{K}=w^{T} G_{w} w-2 w^{T} \mathbb{A}^{+}(u-g) & = \\
w^{T} G_{w} w-2 w^{T} \mathbb{A}^{+} H H^{-1}(u-g) & = \\
\left.w^{T} G_{w} w-2 w^{T} \mathbb{A}^{+} H^{1 / 2} H^{1 / 2}\left(w-H^{-1} g\right)\right) &
\end{aligned}
$$

We introduce $\tilde{w}=H^{1 / 2} w$ and $\tilde{g}=H^{-1 / 2} g$, we recall that $H^{-1 / 2}=H^{-1 / 2}\left(w_{0}\right)$. Furthermore, $u, w$ and $\tilde{w}$ represent solution values at $x=0$. Further manipulations yield,

$$
\left.\mathbb{K}=w^{T} H^{1 / 2} H^{-1 / 2} \mathbb{B} H^{-1 / 2} H^{1 / 2} w-2 w^{T} H^{1 / 2} H^{-1 / 2} \mathbb{A}^{+} H^{1 / 2}(\tilde{w}-\tilde{g})\right)
$$

Introduce $Z=H^{-1 / 2} \mathbb{A} H^{1 / 2}$ and and by (24) the eigenvalues of $\mathbb{A}$ and $Z$ coincide (up to a normalization) such that $H^{-1 / 2} \mathbb{A}^{+} H^{1 / 2}=Z^{+}$follows. Hence,

$$
\begin{equation*}
\mathbb{K}=\tilde{w}^{T} Z \tilde{w}-2 \tilde{w}^{T} Z^{+}(\tilde{w}-\tilde{g}) \tag{25}
\end{equation*}
$$

The expression (25) has the same form as (16) and the rest of the proof is identical.

## 4 The conservative scheme

Throughout this article, we assume that $G(w)$ is homogeneous of order 1, i.e., $p=1$ in (11), in order not to clutter the article with excessive notation, but the theory is readily extended to flux functions homogeneous of a different order.

Discretize the interval [ 0,1$]$ with $N+1$ equidistant points and $h=1 / N$. We will use the standard second-order accurate Summation-by-parts (SBP) operator.

$$
D=\frac{1}{2 h}\left(\begin{array}{cccccc}
-2 & 2 & 0 & \ldots & &  \tag{26}\\
-1 & 0 & 1 & 0 & & \\
& & \ddots & & & \\
& & & \ddots & & \\
& & & -1 & 0 & 1 \\
& & \ldots & 0 & -2 & 2
\end{array}\right)
$$

with the property that

$$
\begin{equation*}
P D=Q, \quad Q+Q^{T}=\operatorname{diag}(-1, \ldots, 1)=B \tag{27}
\end{equation*}
$$

when $P=h \cdot \operatorname{diag}\left(\frac{1}{2}, 1, \ldots, 1, \frac{1}{2}\right)$. We will also use the row-vector $\bar{p}$ with components $(\bar{p})_{i}=p_{i}=[P]_{i i}$. We arrange the unknowns as $u^{T}=\left(u_{0}, u_{1}, \ldots, u_{N}\right)$ and similarly for $f$. For notational convenience we will carry out the analysis for a scalar equation.

Denote $G_{w}\left(w_{i}\right)=a_{i}$ and note that $G_{i}=G\left(w_{i}\right)=a_{i} w_{i}$. Furthermore, let $A=\operatorname{diag}\left(a_{0}, \ldots a_{N}\right)$.

Next, we will state the key result that will enable us to prove stability. We will need the undivided difference operator.

$$
D_{-}=\left(\begin{array}{cccc}
0 & 0 & 0 & \\
-1 & 1 & 0 & \\
0 & -1 & 1 & \\
& & & \ddots
\end{array}\right)
$$

Let $F(w)$ denote the entropy flux, $\Psi(w)$ the entropy potential, and $f_{i}=f\left(u_{i}\right)$. Define the following consistent numerical fluxes

$$
\begin{align*}
& f_{i+1 / 2}=\frac{f_{i+1}+f_{i}}{2} \\
& g_{i+1 / 2}^{*}=f_{i+1 / 2}-D_{i+1 / 2}^{*}\left(w_{i+1}-w_{i}\right) \tag{28}
\end{align*}
$$

$g_{i+1 / 2}^{*}$ is the entropy conservative flux that satisfies

$$
\begin{equation*}
\frac{1}{2}\left(\left(w_{i+1}-w_{i}\right) g_{i+1 / 2}^{*}-\left(\Psi_{i+1}-\Psi_{i}\right)\right)=0 \tag{29}
\end{equation*}
$$

where $\Psi_{i}=\Psi\left(w_{i}\right)$. Furthermore, $D_{i+1 / 2}^{*}$ is a diffusion coefficient specifically chosen such that (29) holds. (It need not be positive.) Furthermore, the numerical entropy flux associated with the entropy conservative flux is:

$$
\begin{equation*}
F_{j+1 / 2}^{*}=\frac{1}{2}\left(w_{i+1}+w_{i}\right) g_{i+1 / 2}^{*}-\frac{1}{2}\left(\Psi_{i+1}+\Psi_{i}\right) \tag{30}
\end{equation*}
$$

(See [Tad06] for more details and also the proof of the lemma below.)
Lemma 4.1 Let $w$ the entropy variables that make the flux function $G(w)$ homogeneous of order 1. Denote by $P^{-1} Q$ the second-order central SBP operator defined in (26). Then

$$
\begin{equation*}
w^{T} Q f=\frac{1}{2} w^{T} B f+\frac{1}{2} w^{T} D_{-}^{T} A D_{-} w \tag{31}
\end{equation*}
$$

where $A=\operatorname{diag}\left(0, D_{1 / 2}^{*}, D_{3 / 2}^{*}, \ldots, D_{N+1 / 2}^{*}\right)$.
Proof Consider

$$
\begin{equation*}
u_{t}+P^{-1} Q f=0 \tag{32}
\end{equation*}
$$

We begin by rephrasing (32) to flux form. For a grid with $N+1$ points, we obtain

$$
\begin{align*}
\left(u_{0}\right)_{t}+\frac{f_{1 / 2}-f_{0}}{h / 2} & =0 \\
\left(u_{i}\right)_{t}+\frac{f_{i+1 / 2}-f_{i-1 / 2}}{h} & =0, \quad i=1 \ldots, N-1  \tag{33}\\
\left(u_{N}\right)_{t}+\frac{f_{N}-f_{N-1 / 2}}{h / 2} & =0
\end{align*}
$$

Next, we note that by (28), the following identity holds,

$$
\begin{equation*}
f_{i+1 / 2}=g_{i+1 / 2}^{*}+D_{i+1 / 2}^{*}\left(w_{i+1}-w_{i}\right) \tag{34}
\end{equation*}
$$

Then consider the following scheme

$$
\begin{align*}
\left(u_{0}\right)_{t}+\frac{g_{1 / 2}^{*}-g_{-1 / 2}^{*}}{h / 2} & =0 \\
\left(u_{i}\right)_{t}+\frac{g_{i+1 / 2}^{*}-g_{i-1 / 2}^{*}}{h} & =0, \quad i=1 \ldots, N-1  \tag{35}\\
\left(u_{N}\right)_{t}+\frac{g_{N+1 / 2}^{*}-g_{N-1 / 2}^{*}}{h / 2} & =0
\end{align*}
$$

which, by (34) is equivalent to

$$
\begin{equation*}
u_{t}+P^{-1} Q f=P^{-1} D_{-}^{T} A D_{-} w \tag{36}
\end{equation*}
$$

We will proceed and analyze (35). To this end, we will carry out the operations corresponding to multilplying (36) by $w^{T} P$ on the component form (35). Recalling the $p_{0}=p_{N}=h / 2$ and all other $p_{i}=h$, we multiply the sedond line by $w_{i} h$.

$$
\begin{align*}
\left(E_{i}\right)_{t}+\frac{F_{i+1 / 2}^{*}-F_{i-1 / 2}^{*}}{h}= & \frac{1}{2}\left(\left(w_{i+1}-w_{i}\right) g_{i+1 / 2}^{*}-\left(\Psi_{i+1}-\Psi_{i}\right)\right) \\
& +\frac{1}{2}\left(\left(w_{i}-w_{i-1}\right) g_{i-1 / 2}^{*}-\left(\Psi_{i}-\Psi_{i-1}\right)\right)=0 \tag{37}
\end{align*}
$$

(See [Tad06] for details.) The right-hand side equals 0 due to the entropy conservative relation (29). Next, we derive the corresponding expressions for the boundary scheme.

$$
\left(u_{0}\right)_{t}+\frac{g_{1 / 2}^{*}-g_{-1 / 2}^{*}}{h / 2}=0
$$

Here $g_{1 / 2}^{*}=g^{*}\left(u_{0}, u_{1}\right)$ is defined as above and we let $g_{-1 / 2}^{*}=f_{0}$. Multiply the boundary scheme in (35) by $w_{0} h / 2$.

$$
\frac{h}{2}\left(E_{i}\right)_{t}+w_{i}\left(g_{1 / 2}^{*}-g_{-1 / 2}^{*}\right)=0
$$

Then the boundary scheme can be transformed into

$$
\begin{equation*}
\frac{h}{2}\left(E_{0}\right)_{t}+\frac{F_{1 / 2}^{*}-F_{-1 / 2}^{*}}{h}=\frac{1}{2}\left(\left(w_{1}-w_{0}\right) g_{1 / 2}^{*}-\left(\Psi_{1}-\Psi_{0}\right)\right) \tag{38}
\end{equation*}
$$

with

$$
F_{-1 / 2}^{*}=w_{0} f_{0}-\Psi_{0}
$$

Both numerical entropy fluxes above are consistent and with our particular entropy-pair. By Lemma 2.2, we can deduce that

$$
\begin{equation*}
F_{-1 / 2}^{*}=\frac{1}{2} w_{0} f_{0} \tag{40}
\end{equation*}
$$

For the boundary at $x_{N}$, we obtain in a similar way

$$
\begin{align*}
F_{N+1 / 2}^{*} & =\frac{1}{2} w_{N} f_{N} \\
\frac{h}{2}\left(E_{N}\right)_{t}+\frac{F_{N+1 / 2}^{*}-F_{N-1 / 2}^{*}}{h} & =0 \tag{41}
\end{align*}
$$

Summing (38), (41) and (37) over $i$ results in

$$
\begin{equation*}
\bar{p} E_{t}-F_{-1 / 2}^{*}+F_{N+1 / 2}^{*}=0 \tag{42}
\end{equation*}
$$

Using (36), we can write (42) as

$$
w^{T} P u_{t}+w^{T} Q f-w^{T} D_{-}^{T} A D_{-} w=-F_{-1 / 2}^{*}+F_{N+1 / 2}^{*}=\frac{1}{2} w^{T} B f
$$

and the Lemma follows.

Next, consider the conservative scheme,

$$
\begin{align*}
u_{t}+P^{-1} Q f= & P^{-1} D_{-}^{T} \Lambda D_{-} w  \tag{43}\\
& +\sigma_{0} P^{-1} A^{+}\left(w_{0}-g_{0}\right) \\
& +\sigma_{N} P^{-1} A^{-}\left(w_{N}-g_{N}\right)
\end{align*}
$$

or, equivalently on component form

$$
\begin{align*}
\left(u_{0}\right)_{t}+\frac{f_{1 / 2}-f_{0}}{h / 2} & =\mathbb{S}_{0} \\
\left(u_{i}\right)_{t}+\frac{f_{i+1 / 2}-f_{i-1 / 2}}{h} & =0, \quad i=1, \ldots, N-1  \tag{44}\\
\left(u_{N}\right)_{t}+\frac{f_{N}-f_{N-1 / 2}}{h / 2} & =\mathbb{S}_{N}
\end{align*}
$$

with

$$
\begin{equation*}
f_{i+1 / 2}=\frac{f_{i+1}+f_{i}}{2}-\frac{\lambda_{i+1 / 2}}{2}\left(w_{i+1}-w_{i}\right) \tag{45}
\end{equation*}
$$

and

$$
\begin{align*}
\mathbb{S}_{0} & =-\left[P^{-1}\right]_{0} A^{+}\left(w_{0}-g_{0}\right)  \tag{46}\\
\mathbb{S}_{N} & =\left[P^{-1}\right]_{N} A^{-}\left(w_{N}-g_{N}\right)
\end{align*}
$$

Next, we will introduce the notion strong entropy stability.
Definition The scheme is called strongly entropy stable, if it satisfies a local entropy inequality (corresponding to the definition of entropy stable schemes in [Tad06]) for all cells but the boundary cells, along with a global $L^{1}$ entropy estimate for non-homogeneous boundary data.
Now we will state the main result of this paper.
Theorem 4.2 The scheme (43) approximating (22) satisfies a global entropy estimate if $\lambda_{i+1 / 2} \geq\left|D_{i+1 / 2}^{*}\right|$. Furthermore, the scheme also satisfies the local entropy inequalities,

$$
\begin{equation*}
\left(E_{t}\right)_{i}+\frac{\mathbb{F}_{i+1 / 2}-\mathbb{F}_{i-1 / 2}}{p_{i}} \leq 0, \quad i=1 \ldots N-1 \tag{47}
\end{equation*}
$$

where $C$ is a constant, and hence the scheme is strongly entropy stable.
Proof Multiply (43) by $w^{T} P$. Using Lemma 4.1, we obtain

$$
\begin{aligned}
w^{T} P u_{t}+w^{T} Q f-\frac{1}{2} w^{T} B f= & w^{T} D_{-}^{T}(A+\Lambda) D_{-} w+ \\
& \sigma_{0} w_{0}^{T} A_{0}^{+}\left(w_{0}-g_{0}\right)+ \\
& \sigma_{N} w_{0}^{T} A_{N}^{-}\left(w_{N}-g_{N}\right)
\end{aligned}
$$

The quadratic diffusion is indefinite and can be bounded by chosing $\lambda_{i+1 / 2} \geq$ $\left|D_{i+1 / 2}^{*}\right|$. The boundary terms are bounded by the the RHS source terms and
the proof is the same as in (17) (extended to cover both the left and right boundaries).

The condition $\lambda_{i+1 / 2} \geq\left|D_{i+1 / 2}^{*}\right|$ is coincides exactly with the condition for entropy stability as defined in [Tad06], which in turn implies that a local entropy estimate is satisfied. (This also follows from (38).)

As a remark, we stress that although the derivations are carried out for a scalar conservation law it is merely a matter of notation to generalize it to the case of a scheme. In fact, as stated in (44) above, $u$ and $f$ can be vectors and the scheme is strongly entropy stable.

Remark The above scheme is conservative and is well adapted to computing solutions with shocks. For smooth flows (like in subsonic flow situations with the Euler equations), we suggest a non-conservative scheme of the form,

$$
\begin{equation*}
u_{t}+\frac{1}{2}(D A+A D) w=\mathbb{S} \tag{48}
\end{equation*}
$$

where $\mathbb{S}$ is a source term that will contain the Simultaneous Approximation Terms (SAT) that enforce the boundary conditions. $\mathbb{S}_{0}$ and $\mathbb{S}_{N}$ are defined above and $\mathbb{S}_{i}=0$ for other $i$ 's, can be used. Analysis of this scheme is carried out in Appendix II. This scheme is highly desirable for approximating smooth flows as it can be easily extended to higher order of accuracy.

## 5 Computations

We will demonstrate the robustness of this scheme for a number of standard cases. In all test cases we will use the entropy-fixed Roe scheme for the internal diffusion. The diffusion will be localized with the limiter derived in [SM09] where it was shown to not interfere with the proofs of entropy stability. In these computations, however, we will also use the entropy stable boundary conditions implemented for the standard Jacobian matrix on conservative form. Hence, the scheme is stated entirely with the conservative variables and the entropy variables are not explicitly used. We also use the standard 4th-order RungeKutta scheme to march in time.

The governing equations in all the tests are the one-dimensional Euler equations for a polytropic gas.

$$
\begin{array}{r}
u_{t}+f(u)_{x}=0 \\
u=(\rho, m, E)^{T} \\
f(u)=q u+(0, P, q P)^{T} \\
P=(\gamma-1)\left(E-\frac{1}{2} \rho q^{2}\right)
\end{array}
$$

$\rho, q, P$ and $E$ are the density, velocity, pressure and total energy. $m=\rho q$ is the momentum and $\gamma$ the ratio of the specific heats. The eigenvalues of the Jacobian matrix $A(u)=\frac{\partial f}{\partial u}$ are, $q-c, q, q+c$, where $c=\sqrt{\gamma P / \rho}$ is the speed of sound.

### 5.0.1 Shock/entropy wave interaction

The first example is the one-dimensional prototype for shock-turbulence interaction proposed in [SO89]. It is an entropy wave interacting with a strong shock. The initial conditions used in [SO89] on the domain $-5 \leq x \leq 5$ are,

$$
\begin{array}{r}
(\rho, q, P)=(3.857143,2.629369,10.33333) \text { for } x<-4, \\
(\rho, q, P)=(1+\epsilon \sin (5 x), 0, P=1) \text { for } x \geq-4,
\end{array}
$$

with $\epsilon=0.2$.
The quality of the solution in the interior is as expected for a second-order scheme with localized diffusion. (See [SM09].) The focus of these experiments is mainly to test the robustness of the boundary conditions. Initially, the waves will travel towards the left boundary and a bad boundary implementation can cause the solution to explode.

As an example we tried to overwrite the solution with data at each time step (so-called injection), which is a commonly used technique in practice. The solution is a Mach 3 shock wave and hence all characteristics are in-going and the procedure do not over-specify the boundary. Indeed, the numerical solution explodes immediately. Possibly one could stabilize the solution with more diffusion but needless to say, any such effort would degrade the accuracy.

With our proposed technique, the solution stays bounded and the solution at $T=1.8,2.5,4.0$ computed with 200 grid points can be viewed in Fig. 1. The results are very similar to those reported in [SM09]. The initial disturbances hitting the left boundary do not cause any stability problems.


Figure 1: Plots of $\rho$ solution with 400 grid points.

We also note that the shock is leaving the domain and the boundary appears to be quite transparent. Furthemore, the boundary entropy inequality (5) was evaluated numerically and the maximal and minimal value of were found to be $(3.7512 e-05,-4.2864 e-15)$ (for 200 points and $(1.2260 e-05,-3.2642 e-15)$ for 400 points).

### 5.0.2 Shock tube

The next example found in [SO89] and originally in [Sod78], is the Euler equations with initial data,

$$
\begin{array}{r}
(\rho, q, P)=(1,0,1) x \leq 0 \\
(\rho, q, P)=(0.125,0,0.1) x \geq 0
\end{array}
$$

on the domain $-5 \leq x \leq 5$. These initial data will develop a rarefaction wave, a shock and a contact discontinuity.

In [SO89] 100 grid points were used and we will follow their example. The results at two different times are shown in Fig. 2 Again, we note that the discontinuities leave the domain smoothly. In this case maximum and minimum of (5) were ( $9.8608 e-32,-0.0088384$ ), respectively. (For 200 points the values are (1.9722e-31,-0.0064286).)

### 5.1 Woodward-Colella

In this case both boundaries are walls and shocks will impinge on them. A severe test of robustness. We construct boundary data $\left(g_{x=-5}(t)\right.$ and $\left.g_{x=5}(t)\right)$ by taking the solution $u(\{-5,5\}, t)$ and setting $q=0$. (Formally, the stability proof is not valid since $g_{x=-5,5}$ are not bounded functions but depend on the solution.)

The initial data is as follows for $0<x<0.1:(\rho, q, P)=(1,0,1000)$; for $0.1<$ $x<0.9(\rho, q, P)=(1,0,0.01)$; and for $0.9<x<1.0(\rho, q, P)=(1,0,0,100)$.

The solution was computed with 400 grid points and the boundary entropy $F_{0}-F_{g}-w_{g}\left(f_{0}-f_{g}\right)$ varied between $-2.1849 e-14$ and $6.2530 e-12$. (For 200 points: $(-2.9049 e-14,6.2539 e-12)$.) The solution at $\mathrm{T}=0.05$ and $\mathrm{T}=0.4$ is shown in Fig. 3

## 6 Conclusions

In this article, we have addressed the problem of imposing boundary conditions on systems of conservation laws. The most important tool in this endeavor was the specific entropy pair introduced in [OO94]. This allowed us to weakly impose characteristic-based boundary conditions and obtain a global entropy estimate.

Our main result, is an entropy stable conservative scheme on a bounded domain. Again, the key analytical tool was the specific entropy pair. Using this entropy pair, we showed that by augmenting the scheme with a numerical diffusion that guarantees entropy stability in the Cauchy case, it will retain a summation-by-parts property and we could use a weak enforcement of boundary conditions to derive a global bound on the entropy. Furthermore, we have shown that the numerical solution satisfies local entropy inequalities.


Figure 2: The solution is computed with 100 grid points. The $\rho$ solution with a rarefaction wave and two contact discontinuities.

Finally, we demonstrated the robustness of the numerical scheme in a series of examples for the Euler equations of gas dynamics. The first two used characteristic boundary conditions, which were shown to be transparent to non-linear waves and very robust. In the third case, the robustness of a wall boundary condition was tested. Furthermore, we evaluated the boundary entropy inequality (5) and in all cases, the maximal value was 0 , if not to round-off errors, so to well within the numerical accuracy. A strong indication that our proposed boundary scheme satisfies the boundary inequality as well.

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Figure 3: The solution is computed with 400 grid points. The momentum $\rho q$ is depicted.

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## APPENDIX

## I Homogeneity for the Euler equations

We will give a specific example from [Ger96]. (In particular, this is the case with $\alpha=1-2 \gamma$ and $\beta=1$.)

If $G(\theta w)=\theta^{\beta} g(w)$ then $G_{w} w=\beta w$ which is what we want. We will now list all the variables, fluxes and entropies for the case $\beta=1$. Beginning with
the entropy:

$$
\begin{aligned}
E(u) & =\rho h(S) \\
h(S) & =K \exp (\kappa S)=K\left(p \rho^{-\gamma}\right)^{\kappa} \\
\kappa & =\frac{1}{1-\gamma}
\end{aligned}
$$

where $K$ is an arbitrary constant. Furthermore,

$$
\begin{aligned}
p^{*} & =\frac{\gamma-1}{1-2 \gamma}\left(w_{1}-\frac{1}{2} \frac{w_{2}^{2}}{w_{3}}\right) \\
p & =(-K)^{-1}\left(\left(p^{*}\right)^{1-2 \gamma} w_{3}^{\gamma}\right)^{1 /(1-\gamma)}
\end{aligned}
$$

In the particular case of air, with $\gamma=7 / 5$, the following relations appear

$$
\begin{aligned}
& \frac{p^{*}}{p}=-K\left(\frac{p}{\rho}\right)^{-7 / 2} \\
& \frac{p}{p^{*}}=(-K)^{-1}\left(p^{*} / w_{3}\right)^{7 / 2}
\end{aligned}
$$

Returning to a general $\gamma$, the variables and fluxes are:

$$
\begin{aligned}
w^{T} & =\frac{p^{*}}{p}\left(u_{3}+\frac{-2 \gamma}{\gamma-1} p,-u_{2}, u_{1}\right)^{T} \\
u^{T} & =\frac{p}{p^{*}}\left(w_{3},-w_{2}, w_{1}-\frac{-2 \gamma}{\gamma-1} p^{*}\right)^{T} \\
g(w)^{T} & =\frac{p}{p^{*}}\left(-w_{2}, \frac{w_{2}^{2}}{w_{3}}+p^{*},-\frac{w_{2}}{w_{3}}\left(w_{1}+\frac{3 \gamma-1}{\gamma-1} p^{*}\right)\right)^{T}
\end{aligned}
$$

Finally, we have

$$
G_{w}=\left(\begin{array}{ccc}
a \rho u & a \rho u^{2}-p & u\left(\frac{a \rho u^{2}}{2}-b p\right)  \tag{49}\\
& u\left(a \rho u^{2}-3 p\right) & -\frac{b p^{2}}{\rho}+c p u^{2}+\frac{a \rho u^{4}}{2}-\frac{1}{2} p u^{2} \\
\text { symm } & & u\left(b c \frac{p^{2}}{\rho}+c p u^{2}+\frac{a}{4} \rho u^{4}\right)
\end{array}\right)
$$

where

$$
\begin{aligned}
a & =\gamma /(1-2 \gamma) \\
b & =\gamma /(\gamma-1) \\
c & =(1-2 \gamma) /(\gamma-1)
\end{aligned}
$$

## II A non-conservative scheme

In this section, we analyse the non-conservative scheme (48). We remark that this scheme is essentially the same as in Gerritsen and Olsson [GO96]. It differs only in the way boundary conditions are enforced.

Like in the continuous case we multiply (48) by the entropy variables scaled with the $P$ matrix to utilize the SBP property of the difference operators.

$$
\begin{equation*}
w^{T} P u_{t}+w^{T} P(D A+A D)=w^{T} P \mathbb{S} \tag{50}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{p} E_{t}+\frac{1}{2}\left(w^{T} Q A w+w^{T} A Q w\right)=w^{T} P \mathbb{S} \tag{51}
\end{equation*}
$$

Using $Q=B-Q^{T}$ and by the symmetry of $A$ we obtain

$$
\begin{equation*}
\bar{p} E_{t}+\frac{1}{2} w^{T} A B w=w^{T} P \mathbb{S} \tag{52}
\end{equation*}
$$

Definition A numerical scheme for the initial-boundary-value problem (1) with inhomogeneous boundary data, is said to be globally entropy stable, if $\bar{p} E_{t} \leq$ Constant.

To prove stability we must choose $\mathbb{S}$ suitably by utilizing the boundary conditions derived in the previous section. We must ensure

$$
\begin{equation*}
-\frac{1}{2} w^{T} A B w+w^{T} P \mathbb{S}<\text { Constant } \tag{53}
\end{equation*}
$$

and hence we choose the vector $\mathbb{S}$ as,

$$
\begin{align*}
\mathbb{S}_{0} & =-\left[P^{-1}\right]_{0} A^{+}\left(w_{0}-g_{0}\right)  \tag{54}\\
\mathbb{S}_{N} & =\left[P^{-1}\right]_{N} A^{-}\left(w_{N}-g_{N}\right)
\end{align*}
$$

and all other $\mathbb{S}_{i}=0$. The proof of stability is exactly the same as the proof of Theorem 3.1. We summarize the results in the following proposition.

Proposition II. 1 For a flux function $f$ and an entropy pair that makes $G(w)$ homogeneous of order 1, the approximation (48) of (22) with boundary conditions imposed by (54), is globally entropy stable.

Remark Since the equation is non-linear, Lax-Friedriechs' equivalence does not hold and solutions of a stable and consistent scheme (like (48)) does not necessarily converge. Nevertheless, stability will certainly be a necessary requirement in any convergence theory.

An important property of the scheme (48), is that it is trivially generalized to high-order accuracy, by exchanging the SBP-operator (26) with a high-order counterpart. It is straightforward to see that the stability proof still holds (keeping in mind that the $P$ matrix in (54) will also change). The important property for the stability proof is (27).

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