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SELF-ADJOINT **curl** OPERATORS

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Abstract. We study the exterior derivative as a symmetric unbounded operator on square integrable 1-forms on a 3D bounded domain D . We aim to identify boundary conditions that render this operator self-adjoint. By the symplectic version of the Glazman-Krein-Naimark theorem this amounts to identifying complete Lagrangian subspaces of the trace space of $\mathbf{H}(\mathbf{curl}, D)$ equipped with a symplectic pairing arising from the \wedge -product of 1-forms on ∂D . Substantially generalizing earlier results, we characterize Lagrangian subspaces associated with closed and co-closed traces. In the case of non-trivial topology of the domain, different contributions from co-homology spaces also distinguish different self-adjoint extension. Finally, all self-adjoint extensions discussed in the paper are shown to possess a discrete point spectrum, and their relationship with $\mathbf{curl curl}$ -operators is discussed.

Key words. \mathbf{curl} operator, self-adjoint extension, complex symplectic space, Glazman-Krein-Naimark theorem, co-homology spaces, spectral properties of \mathbf{curl}

AMS subject classifications. 47F05, 46N20

1. Introduction. The \mathbf{curl} operator is pervasive in field models, in particular in electromagnetics, but hardly ever occurs in isolation. Most often we encounter a $\mathbf{curl curl}$ operator and its properties are starkly different from those of the \mathbf{curl} alone. We devote the final section of this article to investigation of their relationship.

The notable exception, starring a sovereign \mathbf{curl} , is the question of stable force-free magnetic fields in plasma physics. They are solutions of the eigenvalue problem

$$\alpha \in \mathbb{R} \setminus \{0\} : \quad \mathbf{curl} \mathbf{H} = \alpha \mathbf{H} , \tag{1.1}$$

posed on a suitable domain, see [11, 20, 26, 33]. A solution theory for (1.1) must scrutinize the spectral properties of the \mathbf{curl} operator. The mature theory of unbounded operators in Hilbert spaces is a powerful tool. This approach was pioneered by R. Picard [31, 34, 35], see also [39].

The main thrust of research was to convert \mathbf{curl} into a self-adjoint operator by a suitable choice of domains of definition. This is suggested by the following Green's formula for the \mathbf{curl} operator:

$$\int_D \mathbf{curl} \mathbf{u} \cdot \mathbf{v} - \mathbf{curl} \mathbf{v} \cdot \mathbf{u} \, dx = \int_{\partial D} (\mathbf{u} \times \mathbf{v}) \cdot \mathbf{n} \, dS , \tag{1.2}$$

for any domain $D \subset \mathbb{R}^3$ with sufficiently regular boundary ∂D and $\mathbf{u}, \mathbf{v} \in C^1(\overline{D})$. This reveals that the \mathbf{curl} operator is truly symmetric, for instance, when acting on vector fields with vanishing tangential components on ∂D .

On bounded domains D several instances of what qualifies as a self-adjoint \mathbf{curl} operators were found. Invariably, their domains were defined through judiciously chosen boundary conditions. It also became clear that the topological properties of D have to be taken into account carefully, see [34, Thm. 2.4] and [39, Sect. 4].

In this paper we carry these developments further with quite a few novel twists: we try to give a rather systematic treatment of different options to obtain self-adjoint

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curl operators. It is known that the **curl** operator is an incarnation of the exterior derivative of 1-forms. Thus, to elucidate structure, we will mainly adopt the perspective of differential forms.

Further, we base our considerations on recent discoveries linking symplectic algebra and self-adjoint extensions of symmetric operators, see [16] for a survey. In the context of ordinary differential equations, this connection was intensively studied by Markus and Everitt during the past few years [14]. They also extended their investigations to partial differential operators like Δ [15]. We are going to apply these powerful tools to the special case of **curl** operators. Here, the crucial symplectic space is a Hilbert space of 1-forms on ∂D equipped with the pairing

$$[\omega, \eta]_{\partial D} := \int_{\partial D} \omega \wedge \eta .$$

We find out, that it is the Hodge decomposition of the trace space for 1-forms on D that allows a classification of self-adjoint extensions of **curl**: the main distinction is between boundary conditions that impose closed and co-closed traces. Moreover, further constraints are necessary in the form of vanishing circulation along certain fundamental cycles of ∂D . This emerges from an analysis of the space of harmonic 1-forms on ∂D as a finite-dimensional symplectic space. For all these self-adjoint **curls** we show that they possess a complete orthonormal system of eigenfunctions.

In detail, the outline of the article is as follows: The next section reviews the connection between vector analysis and differential forms in 3D and 2D. Then, in the third section, we introduce basic concepts of symplectic algebra. Then we summarize how those can be used to characterize self-adjoint extensions through complete Lagrangian subspaces of certain factor spaces. The fourth section applies these abstract results to trace spaces for 1-forms and the corresponding exterior derivative, that is, the **curl** operator. The following section describes important complete Lagrangian subspaces spawned by the Hodge decomposition of 1-forms on surfaces. The role of co-homology spaces comes under scrutiny. In the sixth section we elaborate concrete boundary conditions for self-adjoint **curl** operators induced by the complete Lagrangian subspaces discussed before. The two final sections examine the spectral properties of the classes of self-adjoint **curls** examined before and explore their relationships with **curl curl** operators. Frequently used notations are listed in an appendix.

2. The curl operator and differential forms. In classical vector analysis the operator **curl** is introduced as first order partial differential operator acting on vector fields with three components. Thus, given a domain $D \subset \mathbb{R}^3$ we may formally consider $\mathbf{curl} : \mathbf{C}_0^\infty(D) \mapsto \mathbf{C}_0^\infty(D)$ as an unbounded operator on $\mathbf{L}^2(D)$. Integration by parts according to (1.2) shows that this basic **curl** operator is symmetric, hence closable [38, Ch. 5]. Its closure is given by the *minimal curl operator*

$$\mathbf{curl}_{\min} : \mathbf{H}_0(\mathbf{curl}, D) \mapsto \mathbf{L}^2(D) . \quad (2.1)$$

Its adjoint is the *maximal curl operator*, see [34, Sect. 0],

$$\mathbf{curl}_{\max} := \mathbf{curl}_{\min}^* : \mathbf{H}(\mathbf{curl}, D) \mapsto \mathbf{L}^2(D) . \quad (2.2)$$

Note, that \mathbf{curl}_{\max} is no longer symmetric, and neither operator is self-adjoint. This motivates the search for self-adjoint extensions $\mathbf{curl}_s : \mathcal{D}(\mathbf{curl}_s) \subset \mathbf{L}^2(D) \mapsto \mathbf{L}^2(D)$ of \mathbf{curl}_{\min} . If they exist, they will satisfy, *c.f.* [16, Example 1.13],

$$\mathbf{curl}_{\min} \subset \mathbf{curl}_s \subset \mathbf{curl}_{\max} . \quad (2.3)$$

Remark 1. The classical route in the study of self-adjoint extensions of symmetric operators is via the famous Stone-von Neumann extension theory, see [38, Ch. 6]. It suggests that, after complexification, we examine the deficiency spaces

$$N^\pm := \mathcal{N}(\mathbf{curl}_{\max} \pm \iota \cdot \text{Id}) \subset \mathcal{D}(\mathbf{curl}_{\max}) . \quad (2.4)$$

LEMMA 2.1. *The deficiency spaces from (2.4) satisfy $\dim N^\pm = \infty$.*

Proof. Let $\mathbf{G}^\pm : \mathbb{R}^3 \setminus \{0\} \mapsto \mathbb{C}^{3,3}$ be a fundamental solution (dyad) of $\mathbf{curl} \pm \iota$, that is, $\mathbf{G} = (\mathbf{curl} \mp \iota)(-1 - \nabla^T \nabla) \mathbf{I} \Phi$, where $\Phi(\mathbf{x}) = \exp(-|\mathbf{x}|)/(4\pi|\mathbf{x}|)$ is the fundamental solution of $-\Delta + 1$, and $\nabla := (\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_3})$. Then, for any $\varphi \in \mathbf{C}^\infty(\mathbb{R}^3)|_{\partial D}$,

$$\mathbf{u}(\mathbf{x}) := \int_{\partial D} \mathbf{G}(\mathbf{x} - \mathbf{y}) \cdot \varphi(\mathbf{y}) \, dS(\mathbf{y}) , \quad \mathbf{x} \in D ,$$

satisfies $\mathbf{u} \in \mathbf{H}(\mathbf{curl}, D)$ and $\mathbf{curl} \mathbf{u} \pm \iota \mathbf{u} = 0$. \square

From Lemma 2.1 we learn that N^\pm reveal little about the structure governing self-adjoint extensions of \mathbf{curl} . Yet the relationship of \mathbf{curl} and differential forms suggests that there is rich structure underlying self-adjoint extensions of \mathbf{curl}_{\min} .

2.1. Differential forms. The \mathbf{curl} operator owes its significance to its close link with the exterior derivative operator in the calculus of differential forms. We briefly recall its basic notions and denote by M an m -dimensional compact orientable manifold with boundary ∂M . If M is of class C^1 it can be endowed with a space of differential forms of degree k , $0 \leq k \leq m$:

DEFINITION 2.2 (Differential k -form). *A differential form of degree k (in short, a k -form) and class C^l , $l \in \mathbb{N}_0$, is a C^l -mapping assigning to each $x \in M$ an alternating k -multilinear form on the tangent space $T_x(M)$. We write $\Lambda^{k,l}(M)$ for the vector space of k -forms of class C^l on M , $\Lambda^{k,l}(M) = \{0\}$ for $k < 0$ or $k > m$.*

Below, we will usually drop the smoothness index l , tacitly assuming that the forms are ‘‘sufficiently smooth’’ to allow the respective operations.

The alternating exterior product of multilinear forms gives rise to the exterior product $\wedge : \Lambda^k(M) \times \Lambda^j(M) \mapsto \Lambda^{k+j}(M)$ by pointwise definition. We note the graded commutativity rule $\omega \wedge \eta = (-1)^{kj} \eta \wedge \omega$ for $\omega \in \Lambda^k$, $\eta \in \Lambda^j$. Further, on any piecewise smooth orientable k -dimensional sub-manifold of M we can evaluate the *integral* $\int_\Sigma \omega$ of a k -form ω over a k -dimensional sub-manifold Σ of M [10, Sect. 4].

This connects to the integral view of k -forms as entities that describe additive and continuous (w.r.t. to a suitable deformation topology) mappings from orientable sub-manifolds of M into the real numbers. This generalized differential forms are sometimes called currents and are studied in geometric integration theory [13, 17]. From this point of view differential forms also make sense for non-smooth manifolds.

From the integral perspective the transformation (pullback) $\Phi^* \omega$ of a k -form under a sufficiently smooth mapping $\Phi : \widehat{M} \mapsto M$ appears natural: $\Phi^* \omega$ is a k -form on \widehat{M} that fulfills

$$\int_{\widehat{\Sigma}} \Phi^* \omega = \int_\Sigma \omega \quad (2.5)$$

for all k -dimensional orientable sub-manifolds $\widehat{\Sigma}$ of \widehat{M} . We remark that pullbacks commute with the exterior product.

If $i : \partial M \mapsto M$ stands for the inclusion map, then the natural trace of a k -form $\omega \in \Lambda^k(M)$ on ∂M is defined as $i^*\omega$. It satisfies the following commutation relations

$$i^*(\omega \wedge \eta) = (i^*\omega) \wedge (i^*\eta) \quad \text{and} \quad \mathbf{d}(i^*\omega) = i^*(\mathbf{d}\omega). \quad (2.6)$$

The key operation on differential form is the *exterior derivative*

$$\mathbf{d} : \Lambda^k(M) \rightarrow \Lambda^{k+1}(M), \quad (2.7)$$

which is connected with integration through the generalized Stokes theorem

$$\int_{\Sigma} \mathbf{d}\omega = \int_{\partial\Sigma} \omega \quad \forall \omega \in \Lambda^{k,0}(M) \quad (2.8)$$

and all orientable piecewise smooth sub-manifolds of M . In fact, (2.8) can be used to *define* the exterior derivative in the context of geometric integration theory. This has the benefit of dispensing with any smoothness requirement stipulated by the classical definition of \mathbf{d} . We have $\mathbf{d}^2 = 0$ and, obviously, (2.8) and (2.7) imply $\Phi^* \circ \mathbf{d} = \mathbf{d} \circ \Phi^*$.

Since one has the graded Leibnitz formula

$$\mathbf{d}(\omega \wedge \eta) = \mathbf{d}\omega \wedge \eta + (-1)^k \omega \wedge \mathbf{d}\eta \quad \forall \omega \in \Lambda^k(M), \eta \in \Lambda^j(M) \quad (2.9)$$

exterior derivative and exterior product enter the crucial integration by parts formula

$$\int_{\Sigma} \mathbf{d}\omega \wedge \eta + (-1)^k \int_{\Sigma} \omega \wedge \mathbf{d}\eta = \int_{\partial\Sigma} i^*\omega \wedge i^*\eta \quad \forall \omega \in \Lambda^k(M), \eta \in \Lambda^j(M), \quad (2.10)$$

where Σ is an orientable sub-manifold of M with dimension $k + j + 1$ and canonical inclusion $i : \Sigma \mapsto \partial\Sigma$.

2.2. Metric concepts. A metric g defined on the manifold M permits us to introduce the *Hodge operator* $\star_g : \Lambda^k(M) \mapsto \Lambda^{m-k}(M)$. It gives rise to the inner product on $\Lambda^k(M)$

$$(\omega, \eta)_{k,M} := \int_M \omega \wedge \star_g \eta, \quad \omega, \eta \in \Lambda^k(M). \quad (2.11)$$

Thus, we obtain an L^2 -type norm $\|\cdot\|$ on $\Lambda^k(M)$. Completion of smooth k -forms with respect to this norm yields the Hilbert space $L^2(\Lambda^k(M))$ of square integrable (w.r.t. g) k -forms on M . Its elements are equivalence classes of k -forms defined almost everywhere on M . Since Lipschitz manifolds possess a tangent space almost everywhere, for them $L^2(\Lambda^k(M))$ remains meaningful. As straightforward is the introduction of ‘‘Sobolev spaces’’ of differential forms, see [1, Sect. 1],

$$W^k(\mathbf{d}, M) := \{\omega \in L^2(\Lambda^k(M)) : \mathbf{d}\omega \in L^2(\Lambda^k(M))\}, \quad (2.12)$$

which are Hilbert spaces with the graph norm. The completion of the subset of smooth k -forms with compact support in $W^k(\mathbf{d}, M)$ is denoted by $W_0^k(\mathbf{d}, M)$.

By construction, the Hodge star operator satisfies

$$\star\star = (-1)^{(m-k)k} \text{Id}. \quad (2.13)$$

Now, let us assume $\partial M = \emptyset$. Based on the inner product (2.11) we can introduce the adjoint $\mathbf{d}^* : W^{k+1}(\mathbf{d}, M) \mapsto W^k(\mathbf{d}, M)$ of the exterior derivative operator by

$$(\mathbf{d}\omega, \eta)_{k+1,M} = (\omega, \mathbf{d}^*\eta)_{k,M} \quad \forall \omega \in W^{k+1}(\mathbf{d}, M), \eta \in W_0^k(\mathbf{d}, M), \quad (2.14)$$

and an explicit calculation shows that

$$\mathbf{d}^* = (-1)^{(mk+1)} \star \mathbf{d} \star : \Lambda^{k+1} \rightarrow \Lambda^k . \quad (2.15)$$

Furthermore, $\mathbf{d}^2 = 0$ implies $(\mathbf{d}^*)^2 = 0$. Eventually, the Laplace-Beltrami operator is defined as

$$\Delta_M = \mathbf{d} \mathbf{d}^* + \mathbf{d}^* \mathbf{d} : \Lambda^k \longrightarrow \Lambda^k . \quad (2.16)$$

2.3. Vector proxies. Let us zero in on the three-dimensional “manifold” D . Choosing bases for the spaces of alternating k -multilinear forms, differential k -forms can be identified with vector fields with $\binom{3}{k}$ components, their so-called “vector proxies” [1, Sect. 1]. The usual association of “Euclidean vector proxies” in three-dimensional space is summarized in Table 2.1. The terminology honours the fact that the Hodge operators $\star : \Lambda^1(D) \mapsto \Lambda^2(D)$ and $\Lambda^0(D) \mapsto \Lambda^3(D)$ connected with the Euclidean metric of 3-space leave the vector proxies invariant (this is not true in 2D since $\star^2 = -1$ on 1-forms). In addition the exterior product of forms is converted into the pointwise Euclidean inner product of vector fields. Thus, the inner product $(\cdot, \cdot)_{k,D}$ of k -forms on D becomes the conventional $L^2(D)$ inner product of the vector proxies. Further, the spaces $W^k(\mathbf{d}, D)$ boil down to the standard Sobolev spaces $H^1(D)$ (for $k = 0$), $\mathbf{H}(\mathbf{curl}, D)$ (for $k = 1$), $\mathbf{H}(\mathbf{div}, D)$ (for $k = 2$), and $L^2(D)$ (for $k = 3$).

Differential form ω	Related function u or vector field \mathbf{u}
$\mathbf{x} \mapsto \omega(\mathbf{x})$	$u(\mathbf{x}) := \omega(\mathbf{x})$
$\mathbf{x} \mapsto \{\mathbf{v} \mapsto \omega(\mathbf{x})(\mathbf{v})\}$	$\mathbf{u}(\mathbf{x}) \cdot \mathbf{v} := \omega(\mathbf{x})(\mathbf{v})$
$\mathbf{x} \mapsto \{(\mathbf{v}_1, \mathbf{v}_2) \mapsto \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2)\}$	$\mathbf{u}(\mathbf{x}) \cdot (\mathbf{v}_1 \times \mathbf{v}_2) := \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2)$
$\mathbf{x} \mapsto \{(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3) \mapsto \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)\}$	$u(\mathbf{x}) \det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3) := \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$

TABLE 2.1

The standard choice of vector proxy u, \mathbf{u} for a differential form ω in \mathbb{R}^3 . Here, \cdot denotes the Euclidean inner product of vectors in \mathbb{R}^3 , whereas \times designates the cross product.

Using Euclidean vector proxies, the **curl** operator turns out to be an incarnation of the *exterior derivative* for 1-forms. More generally, the key first order differential operators of vector analysis arise from exterior derivative operators, see Figure 2.1. Please note that, since the Hodge operator is invisible on the vector proxy side, **curl** can as well stand for the operator

$$\mathbf{curl} \longleftrightarrow \star \mathbf{d} : \Lambda^1(D) \mapsto \Lambda^1(D) , \quad (2.17)$$

which is naturally viewed as an unbounded operator on $L^2(\Lambda^1(D))$. Thus, (2.17) puts the formal **curl** operator introduced above in the framework of differential forms on D .

Translated into the language of differential forms, the Green’s formula (1.2) becomes a special version of (2.10) for $k = j = 1$. However, due to (2.13), (1.2) can also be stated as

$$(\star \mathbf{d} \omega, \eta)_{1,D} - (\omega, \star \mathbf{d} \eta)_{1,D} = \int_{\partial D} i^* \omega \wedge i^* \eta , \quad \omega, \eta \in W^1(\mathbf{d}, D) . \quad (2.18)$$

A metric on \mathbb{R}^3 induces a metric on the embedded 2-dimensional manifold ∂D . Thus, the Euclidean inner product on local tangent spaces becomes a meaningful

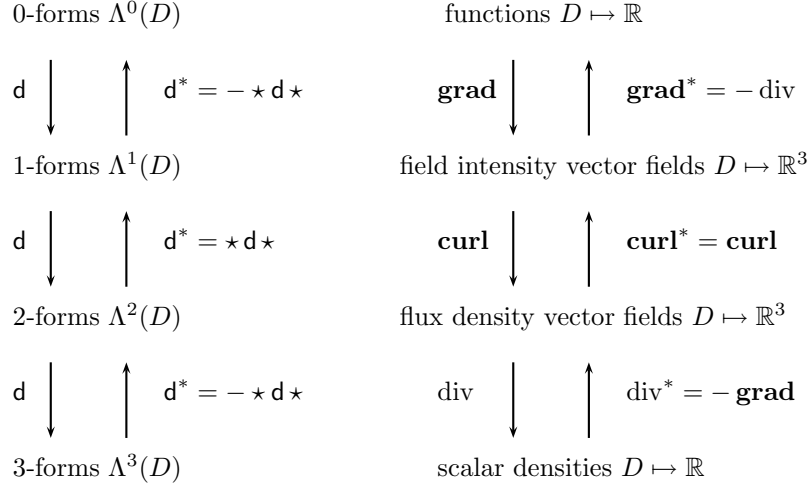


FIG. 2.1. Differential operators and their relationship with exterior derivatives

Differential forms	Related function u or vector field \mathbf{u}
$\mathbf{x} \mapsto \omega(\mathbf{x})$	$u(\mathbf{x}) := \omega(\mathbf{x})$
$\mathbf{x} \mapsto \{\mathbf{v} \mapsto \omega(\mathbf{x})(\mathbf{v})\}$	$\mathbf{u}(\mathbf{x}) \cdot \mathbf{v} := \omega(\mathbf{x})(\mathbf{v})$
$\mathbf{x} \mapsto \{(\mathbf{v}_1, \mathbf{v}_2) \mapsto \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2)\}$	$u(\mathbf{x}) \det(\mathbf{v}_1, \mathbf{v}_2, \mathbf{n}(\mathbf{x})) := \omega(\mathbf{x})(\mathbf{v}_1, \mathbf{v}_2)$

TABLE 2.2

Euclidean vector proxies for differential forms on ∂D . Note that the test vectors $\mathbf{v}, \mathbf{v}_1, \mathbf{v}_2$ have to be chosen from the tangent space $T_{\mathbf{x}}(\partial D)$.

concept and Euclidean vector proxies for k -forms on ∂D , $k = 0, 1, 2$, can be defined as in Table 2.1, see Table 2.2.

This choice of vector proxies leads to convenient vector analytic expressions for the trace operator i^* :

$$\left\{ \begin{array}{ll} \omega \in \Lambda^0(D) : i^* \omega \longleftrightarrow \gamma u(\mathbf{x}) & := u(\mathbf{x}), & \mathbf{u} : D \mapsto \mathbb{R}, \\ \omega \in \Lambda^1(D) : i^* \omega \longleftrightarrow \gamma_t \mathbf{u}(\mathbf{x}) & := \mathbf{u}(\mathbf{x}) - (\mathbf{u}(\mathbf{x}) \cdot \mathbf{n}(\mathbf{x})) \mathbf{n}(\mathbf{x}), & \mathbf{u} : D \mapsto \mathbb{R}^3, \\ \omega \in \Lambda^2(D) : i^* \omega \longleftrightarrow \gamma_n \mathbf{u}(\mathbf{x}) & := \mathbf{u}(\mathbf{x}) \cdot \mathbf{n}(\mathbf{x}), & \mathbf{u} : D \mapsto \mathbb{R}^3, \\ \omega \in \Lambda^3(D) : i^* \omega \longleftrightarrow & 0, \end{array} \right.$$

where $\mathbf{x} \in \partial D$. Further, the customary vector analytic surface differential operators realize the exterior derivative for vector proxies, see Figure 2.2.

Remark 2. Vector proxies offer an isomorphic model for the calculus of differential forms. However, one must be aware that the choice of bases and, therefore, the description of a differential form by a vector proxy, is somewhat arbitrary. In particular, a change of metric of space suggests a different choice of vector proxies for which the Hodge operators reduce to the identity. Thus, metric and topological aspects are hard to disentangle from a vector analysis point of view. This made us prefer the differential forms point of view in the remainder of the article.

3. Self-adjoint extensions and Lagrangian subspaces. First, we would like to recall some definitions of symplectic geometry. Then, we will build a symplectic

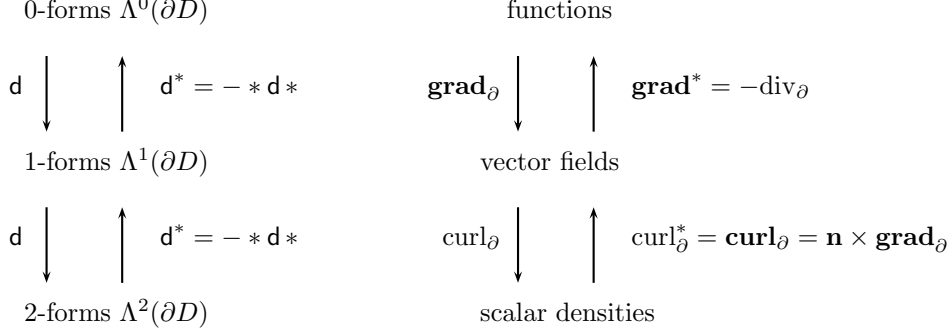


FIG. 2.2. Exterior derivative for Euclidean vector proxies on 2-manifolds

space associated to a closed symmetric operator. The reader can refer to [15,16] for a more detailed treatment.

3.1. Concepts from symplectic geometry. Symplectic geometry offers an abstract framework to deal with self-adjoint extensions of symmetric operators in Hilbert spaces. Here we briefly review some results. More information is available from [28].

DEFINITION 3.1 (Symplectic space). *A real symplectic space S is a real linear space equipped with a symplectic pairing $[\cdot, \cdot]$ (symplectic bilinear form, symplectic product)*

$$\left\{ \begin{array}{l} [\cdot, \cdot] : S \times S \longrightarrow \mathbb{R}, \\ [\alpha_1 u_1 + \alpha_2 u_2, v] = \alpha_1 [u_1, v] + \alpha_2 [u_2, v], \quad (\text{linearity}) \\ [u, v] = -[v, u], \quad (\text{skew symmetry}) \\ [u, S] = 0 \implies u = 0 \quad (\text{non-degeneracy}) \end{array} \right. \quad (3.1)$$

DEFINITION 3.2. *Let L be a linear subspace of the symplectic space S*

- (i) *The symplectic orthogonal of L is $L^\sharp = \{u \in S : [u, L] = 0\}$;*
- (ii) *L is a Lagrangian subspace, if $L \subset L^\sharp$ i. e. $[u, v] = 0$ for all u and v in L ;*
- (iii) *A Lagrangian subspace L is complete, if $L^\sharp = L$.*

In the case of finite dimensional symplectic spaces, symplectic bases offer a convenient way to build complete Lagrangian subspaces, see [14, Example 2].

DEFINITION 3.3. *Let $(S, [\cdot, \cdot])$ be a real symplectic space with dimension $2n$ (the dimension has to be even so that the pairing $[\cdot, \cdot]$ can be non degenerate). A symplectic basis $\{u_i\}_{i=1}^{2n}$ of S is a basis of S satisfying*

$$[u_i, u_j] = \mathbf{J}_{i,j} \quad \text{with } \mathbf{J} = \begin{bmatrix} 0_{n \times n} & \mathbf{I}_{n \times n} \\ -\mathbf{I}_{n \times n} & 0_{n \times n} \end{bmatrix} \quad (3.2)$$

Simple linear algebra proves the existence of such bases:

LEMMA 3.4. *For any symplectic space with finite dimension $2n$, there exists a (non unique) symplectic basis.*

Remark 3. As soon as we have found a symplectic basis $\{u_i\}_{i=1}^{2n}$, it provides many complete Lagrangian subspaces

- the n first vectors $\{u_i\}_{i=1}^n$ of a symplectic basis span a complete Lagrangian subspace.

- the n last vectors $\{u_i\}_{i=n+1}^{2n}$ of a symplectic basis span a complete Lagrangian subspace.
- for any $\sigma : \llbracket 1, n \rrbracket \mapsto \llbracket 0, 1 \rrbracket$, $\{u_{i+\sigma(i)}\}_{i=1}^n$ is a complete Lagrangian subspace.

We recall some more facts about finite dimensional symplectic spaces

LEMMA 3.5. *Every complete Lagrangian subspace of a finite dimensional symplectic space S of dimension $2n$ is n -dimensional. Moreover, it possesses a basis that can be extended to a symplectic basis of S .*

3.2. Application to self-adjoint extensions of a symmetric operator.

Let H be a real Hilbert space and \mathbb{T} a closed symmetric linear operator with dense domain $\mathcal{D}(\mathbb{T}) \subset H$. We denote by \mathbb{T}^* its adjoint. Let us first recall, see [38], that each self-adjoint extension of \mathbb{T} is a restriction of \mathbb{T}^* , which is classically written as

$$\mathbb{T} \subset \mathbb{T}^s \subset \mathbb{T}^*. \quad (3.3)$$

Next, introduce a degenerate symplectic pairing on $\mathcal{D}(\mathbb{T}^*)$ by

$$[\cdot, \cdot] : \mathcal{D}(\mathbb{T}^*) \times \mathcal{D}(\mathbb{T}^*) \longrightarrow \mathbb{R} \quad \text{such that} \quad [u, v] = (\mathbb{T}^*u, v) - (u, \mathbb{T}^*v). \quad (3.4)$$

From the definition of \mathbb{T}^* , the symmetry of \mathbb{T} , and the fact $\mathbb{T}^{**} = \mathbb{T}$, we infer that, see [14, Appendix],

$$\begin{cases} [u + u_0, v + v_0] = [u, v], & \forall u_0, v_0 \in \mathcal{D}(\mathbb{T}), \forall u, v \in \mathcal{D}(\mathbb{T}^*), \\ u \in \mathcal{D}(\mathbb{T}^*), [u, v] = 0, & \forall v \in \mathcal{D}(\mathbb{T}^*), \implies u \in \mathcal{D}(\mathbb{T}). \end{cases} \quad (3.5)$$

As a consequence, we obtain a symplectic factor space, see Appendix of [14],

LEMMA 3.6. *The space $S = \left(\mathcal{D}(\mathbb{T}^*) / \mathcal{D}(\mathbb{T}), [\cdot, \cdot] \right)$ is a symplectic space. The graph norm on $\mathcal{D}(\mathbb{T}^*)$ induces a factor norm on S and, due to (3.5), the symplectic pairing $[\cdot, \cdot]$ is continuous with respect to this norm*

$$|[u, v]|^2 \leq (\|u\|^2 + \|\mathbb{T}^*u\|^2) \cdot (\|v\|^2 + \|\mathbb{T}^*v\|^2) \quad \forall u \in \mathcal{D}(\mathbb{T}^*), v \in \mathcal{D}(\mathbb{T}^*),$$

Let $L \oplus \mathcal{D}(\mathbb{T})$ denotes the pre-image of L under the factor map $\mathcal{D}(\mathbb{T}^*) \mapsto S$.

COROLLARY 3.7. *The symplectic orthogonal V^\sharp of any subspace V of S is closed (in the factor space topology). Any linear subspace L of S defines an extension \mathbb{T}_L of \mathbb{T} through*

$$\mathbb{T} \subset \mathbb{T}_L := \mathbb{T}^*|_{L \oplus \mathcal{D}(\mathbb{T})} \subset \mathbb{T}^*. \quad (3.6)$$

This relationship allows to characterize self-adjoint extensions of \mathbb{T} by means of the symplectic properties of the associated subspaces L . This statement is made precise in the Glazman-Krein-Naimark Theorem, see Theorem 1 of [14, Appendix].

THEOREM 3.8 (Glazman-Krein-Naimark Theorem symplectic version). *The mapping $L \mapsto \mathbb{T}_L$ is a bijection between the space of complete Lagrangian subspaces of S and the space of self-adjoint extensions of \mathbb{T} . The inverse mapping is given by*

$$L = \mathcal{D}(\mathbb{T}_L) / \mathcal{D}(\mathbb{T}). \quad (3.7)$$

4. Symplectic space for curl. Evidently, the unbounded **curl** operators introduced in Section 2 (resorting to the vector proxy point of view) fits the framework of the preceding section and Theorem 3.8 can be applied. To begin with, from (2.1) and (2.2) we arrive at the symplectic space

$$S_{\mathbf{curl}} := \mathbf{H}(\mathbf{curl}, D) / \mathbf{H}_0(\mathbf{curl}, D) . \quad (4.1)$$

By (1.2) it can be equipped with a symplectic pairing that can formally be written as

$$[\mathbf{u}, \mathbf{v}]_{\partial D} := \int_{\partial D} (\mathbf{u}(\mathbf{y}) \times \mathbf{v}(\mathbf{y})) \cdot \mathbf{n}(\mathbf{y}) \, dS(\mathbf{y}) , \quad (4.2)$$

for any representatives of the equivalence classes of $S_{\mathbf{curl}}$. From (4.1) it is immediate that S is algebraically and topologically isomorphic to the natural trace space of $\mathbf{H}(\mathbf{curl}, D)$.

By now this trace space is well understood, see the seminal work of Paquet [30] and [6–9] for the extension to generic Lipschitz domains. To begin with, the topology of $S_{\mathbf{curl}}$ is intrinsic, that is, with $D' := \mathbb{R}^3 \setminus \overline{D}$, the norm of

$$S_{\mathbf{curl}}^c := \mathbf{H}(\mathbf{curl}, D') / \mathbf{H}_0(\mathbf{curl}, D') \quad (4.3)$$

is equivalent to that of $S_{\mathbf{curl}}$; both spaces are isomorphic algebraically and topologically. This can be proved appealing to an extension theorem for $\mathbf{H}(\mathbf{curl}, D)$. Moreover, the pairing $[\cdot, \cdot]_{\partial D}$ identifies $S_{\mathbf{curl}}$ with its dual $S'_{\mathbf{curl}}$:

LEMMA 4.1. *The mapping $S_{\mathbf{curl}} \mapsto S'_{\mathbf{curl}}, \mathbf{u} \mapsto \{\mathbf{v} \mapsto [\mathbf{u}, \mathbf{v}]_{\partial D}\}$ is an isomorphism.*

Proof. Given $\mathbf{u} \in S_{\mathbf{curl}}$, let $\mathbf{u} \in \mathbf{H}(\mathbf{curl}, D)$ solve

$$\mathbf{curl} \, \mathbf{curl} \, \mathbf{u} + \mathbf{u} = 0 \quad \text{in } D , \quad \gamma_t \mathbf{u} = \mathbf{u} \quad \text{on } \partial D . \quad (4.4)$$

Set $\mathbf{v} := \mathbf{curl} \, \mathbf{u} \in \mathbf{H}(\mathbf{curl}, D)$ and $\mathbf{v} := \gamma_t \mathbf{v} \in S_{\mathbf{curl}}$. By (1.2)

$$\begin{aligned} [\mathbf{u}, \mathbf{v}]_{\partial D} &= \int_D \mathbf{curl} \, \mathbf{u} \cdot \mathbf{v} - \mathbf{curl} \, \mathbf{v} \cdot \mathbf{u} \, dx \\ &= \int_D |\mathbf{curl} \, \mathbf{u}|^2 + |\mathbf{u}|^2 \, dx = \|\mathbf{v}\|_{\mathbf{H}(\mathbf{curl}, D)} \|\mathbf{u}\|_{\mathbf{H}(\mathbf{curl}, D)} \geq \|\mathbf{v}\|_{S_{\mathbf{curl}}} \|\mathbf{u}\|_{S_{\mathbf{curl}}} , \end{aligned}$$

as $\|\mathbf{v}\|_{\mathbf{H}(\mathbf{curl}, D)} = \|\mathbf{u}\|_{\mathbf{H}(\mathbf{curl}, D)}$. We immediately conclude

$$\sup_{\mathbf{v} \in S_{\mathbf{curl}}} \frac{|[\mathbf{u}, \mathbf{v}]|}{\|\mathbf{v}\|_{S_{\mathbf{curl}}}} \geq \|\mathbf{u}\|_{S_{\mathbf{curl}}} .$$

□

The trace space also allows a characterization via surface differential operators. It relies on the space $\mathbf{H}_t^{\frac{1}{2}}(\partial D)$ of tangential surface traces of vector fields in $(H^1(D))^3$ and its dual $\mathbf{H}_t^{-\frac{1}{2}}(\partial D) := (\mathbf{H}_t^{\frac{1}{2}}(\partial D))'$. Then one finds that, algebraically and topologically, $S_{\mathbf{curl}}$ is isomorphic to

$$S_{\mathbf{curl}} \cong \mathbf{H}^{-\frac{1}{2}}(\mathbf{curl}_{\partial}, \partial D) := \{\mathbf{v} \in \mathbf{H}_t^{-\frac{1}{2}}(\partial D) : \mathbf{curl}_{\partial} \mathbf{v} \in H^{-\frac{1}{2}}(\partial D)\} . \quad (4.5)$$

The intricate details and the proper definition of \mathbf{curl}_{∂} can be found in [9].

When we adopt the perspective of differential forms, the domain of \mathbf{curl}_{\max} is the Sobolev space $H^1(d, D)$ of 1-forms. Thus, $S_{\mathbf{curl}}$ has to be viewed as a trace space

of 1-forms, that is, a space of 1-forms (more precisely, 1-currents) on ∂D . In analogy to (2.12) and (4.5) we adopt the notation

$$S_{\mathbf{curl}} \cong W^{-\frac{1}{2},1}(\mathbf{d}, \partial D). \quad (4.6)$$

Please observe, that the corresponding symbol for the trace space of $H^0(\mathbf{d}, D)$ will be $W^{-\frac{1}{2},0}(\mathbf{d}, \partial D)$ (and not $W^{\frac{1}{2},0}(\mathbf{d}, D)$) as readers accustomed to the conventions used with Sobolev spaces might expect.

In light of (2.18), the symplectic pairing on $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ can be expressed as

$$[\omega, \eta]_{\partial D} := \int_{\partial D} \omega \wedge \eta, \quad \omega, \eta \in W^{-\frac{1}{2},1}(\mathbf{d}, \partial D). \quad (4.7)$$

Whenever, $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ is treated as a real symplectic space, the pairing (4.7) is assumed. The most important observation about (4.7) is that the pairing $[\cdot, \cdot]$ is utterly metric-free!

Now we can specialize Theorem 3.8 to the **curl** operator. We give two equivalent versions, one for Euclidean vector proxies, the second for 1-forms:

THEOREM 4.2 (GKN-theorem for **curl**, vector proxy version). *The mapping which associates to $L \subset \mathbf{H}^{-\frac{1}{2}}(\mathbf{curl}_{\partial}, \partial D)$ the **curl** operator with domain*

$$\mathcal{D}(\mathbf{curl}_L) := \{\mathbf{v} \in \mathbf{H}(\mathbf{curl}, D) : \gamma_t(\mathbf{v}) \in L\}$$

is a bijection between the set of complete Lagrangian subspaces of $\mathbf{H}^{-\frac{1}{2}}(\mathbf{curl}_{\partial}, \partial D)$ and the self-adjoint extensions of \mathbf{curl}_{\min} .

THEOREM 4.3 (GKN-theorem for **curl**, version for 1-forms). *The mapping which associates to $L \subset W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ the $\star \mathbf{d}$ operator with domain*

$$\mathcal{D}(\star \mathbf{d}_L) := \{\eta \in W^1(\mathbf{d}, D) : i^* \eta \in L\}$$

is a bijection between the set of complete Lagrangian subspaces of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ and the self-adjoint extensions of $\star \mathbf{d}$ defined on $W_0^1(\mathbf{d}, D)$.

We point out that the constraint $i^* \eta \in L$ on traces amounts to imposing linear *boundary conditions*. In other words, the above theorems tell us, that self-adjoint extensions of \mathbf{curl}_{\min} will be characterized by demanding particular boundary conditions for their argument vector fields, cf. [34].

Remark 4. Thanks to (2.6) the symplectic pairing on $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ commutes with the pullback. Thus, if $D, \widehat{D} \subset \mathbb{R}^3$ are connected by a Lipschitz homomorphism $\Phi : \widehat{D} \mapsto D$, we find that $\Phi^* : \Lambda^1(\partial D) \mapsto \Lambda^1(\partial \widehat{D})$ provides a bijective mapping between the complete Lagrangian subspaces of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ and of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial \widehat{D})$. Thus, pulling back the domain of a self-adjoint extension of \mathbf{curl}_{\min} on D to \widehat{D} will give a valid domain for a self-adjoint extension of \mathbf{curl}_{\min} on \widehat{D} . In short, self-adjoint extensions of \mathbf{curl}_{\min} are invariant under bijective continuous transformations. This is a very special feature of **curl**, not shared, for instance, by the Laplacian $-\Delta$.

5. Hodge theory and consequences. Now we study particular subspaces of the trace space $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$. We will take for granted a metric on ∂D that induces a Hodge operator \star .

5.1. The Hodge decomposition. Let us first recall the well-known Hodge decomposition of spaces of square-integrable differential 1-forms on ∂D . For a more general exposition we refer to [29]:

LEMMA 5.1. *We have the following decomposition, which is orthogonal w.r.t. the inner product of $L^2(\Lambda^1(\partial D))$:*

$$L^2(\Lambda^1(\partial D)) = dW^0(d, \partial D) \oplus \star dW^0(d, \partial D) \oplus \mathcal{H}^1(\partial D) .$$

Here, $\mathcal{H}^1(\partial D)$ designates the finite-dimensional space of harmonic 1-forms on ∂D :

$$\mathcal{H}^1(\partial D) := \{\omega \in L^2(\Lambda^1(\partial D)) : \mathbf{d}\omega = 0 \text{ and } \mathbf{d}\star\omega = 0\} . \quad (5.1)$$

In terms of Euclidean vector proxies, the space $L^2(\Lambda^1(\partial D))$ is modelled by the space $\mathbf{L}_t^2(\partial D)$ of square integrable tangential vector fields on ∂D . Then, the decomposition of Lemma 5.1 reads

$$\begin{aligned} \mathbf{L}_t^2(\partial D) &= \mathbf{grad}_\partial H^1(\partial D) \oplus \mathbf{curl}_\partial H^1(\partial D) \oplus \mathcal{H}^1(\partial D) , \\ \mathcal{H}^1(\partial D) &:= \{\mathbf{v} \in \mathbf{L}_t^2(\partial D) : \mathbf{curl}_\partial \mathbf{v} = 0 \text{ and } \mathbf{div}_\partial \mathbf{v} = 0\} . \end{aligned}$$

The Hodge decomposition can be extended to $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ on Lipschitz domains, as was demonstrated in [9, Sect. 5] and [5]. There the authors showed that, with a suitable extension of the surface differential operators, that

$$\mathbf{H}^{-\frac{1}{2}}(\mathbf{curl}_\partial, \partial D) = \mathbf{grad}_\partial H^{\frac{1}{2}}(\partial D) \oplus \mathbf{curl}_\partial H^{\frac{3}{2}}(\partial D) \oplus \mathcal{H}^1(\partial D) , \quad (5.2)$$

where, formally,

$$H^{\frac{3}{2}}(\partial D) := \Delta_{\partial D}^{-1} H_*^{-\frac{1}{2}}(\partial D) , \quad H_*^{-\frac{1}{2}}(\partial D) := \left\{ v \in H^{-\frac{1}{2}}(\partial D) : \int_{\partial D_i} v \, dS = 0 \right\} . \quad (5.3)$$

with ∂D_i the connected components of ∂D .

For C^1 -boundaries this space agrees with the trace space of $H^2(D)$.

The result (5.2) can be rephrased in the calculus of differential forms:

THEOREM 5.2 (Hodge decomposition of trace space). *We have the following orthogonal decomposition*

$$W^{-\frac{1}{2},1}(\mathbf{d}, \partial D) = dW^{-\frac{1}{2},0}(\mathbf{d}, \partial D) \oplus \star dW^{\frac{3}{2},0}(\partial D) \oplus \mathcal{H}^1(\partial D) , \quad (5.4)$$

with

$$W^{\frac{3}{2},0}(\partial D) := \Delta_{\partial D}^{-1} \left\{ \varphi \in W^{-\frac{1}{2},0}(\partial D) : \langle \varphi, \mathbf{1} \rangle_{\partial D_i} = 0 \right\} . \quad (5.5)$$

with ∂D_i the connected components of ∂D .

The first subspace in the decomposition of Theorem 5.2 comprises only closed 1-forms, because

$$\mathbf{d}(dW^{-\frac{1}{2},0}(\mathbf{d}, \partial D)) = 0 . \quad (5.6)$$

The second subspace contains only co-closed 1-forms, since

$$\mathbf{d}^*(\star dW^{\frac{3}{2},0}) = 0 . \quad (5.7)$$

The Hodge decomposition hinges on the choice of the Hodge operator \star . Consequently, it depends on the underlying metric on ∂D .

5.2. Lagrangian properties of the Hodge decomposition. We find that the subspaces contributing to the Hodge decomposition of Theorem 5.2 can be used a building blocks for (complete) Lagrangian subspaces of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$.

PROPOSITION 5.3. *The linear space $dW^{-\frac{1}{2},0}(\mathbf{d}, \partial D)$ is a Lagrangian subspace of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ (w.r.t. the symplectic pairing $[\cdot, \cdot]_{\partial D}$)*

Proof. We have to show that

$$[\mathbf{d}\omega, \mathbf{d}\eta]_{\partial D} = 0 \quad \forall \omega, \eta \in W^{-\frac{1}{2},0}(\mathbf{d}, \partial D). \quad (5.8)$$

By density, we need merely consider ω, η in $W^0(\mathbf{d}, \partial D)$. In this case, it is immediate from Stokes' Theorem (∂D has no boundary)

$$[\mathbf{d}\omega, \mathbf{d}\eta]_{\partial D} = \int_{\partial D} \mathbf{d}\omega \wedge \mathbf{d}\eta = \int_{\partial D} \omega \wedge \mathbf{d}^2\eta = 0. \quad (5.9)$$

□

PROPOSITION 5.4. *The linear space $\star dW^{\frac{3}{2},0}(\partial D)$ is a Lagrangian subspace of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$.*

Proof. The proof is the same as above, except that one has to use that \star is an isometry with respect to the inner product induced by it:

$$[\star \mathbf{d}\omega, \star \mathbf{d}\eta]_{\partial D} = \int_{\partial D} \star \mathbf{d}\omega \wedge \star \mathbf{d}\eta = - \int_{\partial D} \mathbf{d}\omega \wedge \mathbf{d}\eta = - \int_{\partial D} \omega \wedge \mathbf{d}^2\eta = 0. \quad (5.10)$$

□

In a similar way we prove the next proposition.

PROPOSITION 5.5. *The space of harmonic 1-forms $\mathcal{H}^1(\partial D)$ is symplectically orthogonal to $dW^{-\frac{1}{2},0}(\mathbf{d}, \partial D)$ and $\star dW^{\frac{3}{2},0}(\partial D)$.*

The Hodge decomposition of Theorem 5.2 offers a tool for the evaluation of the symplectic pairing $[\cdot, \cdot]_{\partial D}$. Below, tag the three components of the Hodge decomposition of Theorem 5.2 by subscripts 0, \perp and H : for $\omega, \eta \in W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$

$$\omega = \mathbf{d}\omega_0 + \star \mathbf{d}\omega_{\perp} + \omega_H \quad \text{and} \quad \eta = \mathbf{d}\eta_0 + \star \mathbf{d}\eta_{\perp} + \eta_H. \quad (5.11)$$

Note that the forms ω_0 and ω_{\perp} are not unique since the kernels of \mathbf{d} and $\star \mathbf{d}$ are not empty (they contain the piecewise constants on connected components of ∂D).

Taking into account the symplectic orthogonalities stated in Propositions 5.3, 5.4, and 5.5

$$\begin{cases} [\mathbf{d}\omega_0, \mathbf{d}\eta_0]_{\partial D} &= [\star \mathbf{d}\omega_{\perp}, \star \mathbf{d}\eta_{\perp}]_{\partial D} &= [\mathbf{d}\omega_0, \eta_H]_{\partial D} &= [\star \mathbf{d}\omega_{\perp}, \eta_H]_{\partial D} \\ &= [\omega_H, \mathbf{d}\eta_0]_{\partial D} &= [\omega_H, \star \mathbf{d}\eta_{\perp}]_{\partial D} &= 0 \end{cases} \quad (5.12)$$

we see that we can compute the symplectic pairing on $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ according to

$$[\omega, \eta]_{\partial D} = [\mathbf{d}\omega_0, \star \mathbf{d}\eta_{\perp}]_{\partial D} + [\star \mathbf{d}\omega_{\perp}, \mathbf{d}\eta_0]_{\partial D} + [\omega_H, \eta_H]_{\partial D}. \quad (5.13)$$

It can also be expressed in terms of the L^2 -inner product (more precisely, its extension to duality pairing) as

$$[\omega, \eta]_{\partial D} = (\mathbf{d}\omega_0, \mathbf{d}\eta_{\perp})_{1, \partial D} - (\mathbf{d}\omega_{\perp}, \mathbf{d}\eta_0)_{1, \partial D} + [\omega_H, \eta_H]_{\partial D}. \quad (5.14)$$

5.3. The symplectic space $\mathcal{H}^1(\partial D)$. Let us recall that the space of harmonic 1-forms on ∂D (a 2 dimensional compact C^∞ -manifold without boundary) is a finite dimensional linear space with

$$\dim(\mathcal{H}^1(\partial D)) = 2g, \quad (5.15)$$

with g the genus of the boundary, that is, the first Betti number of D . The reader can refer to Theorem 5.1, Proposition 5.3.1 of [4] and Theorem 7.4.3 of [29].

Since the set of harmonic vector fields is stable with respect to the Hodge operator (note that $\star\star = -1$ for 1-forms on ∂D)

$$\left\{ \begin{array}{l} \eta \in \mathcal{H}^1(\partial D) \implies \eta \in L^2(\Lambda^1(\partial D)), \quad d\eta = 0, \quad d\star\eta = 0 \\ \implies \star\eta \in L^2(\Lambda^1(\partial D)), \quad d\star(\star\eta) = 0, \quad d(\star\eta) = 0 \\ \implies \star\eta \in \mathcal{H}^1(\partial D), \end{array} \right. \quad (5.16)$$

Thus we find that the pairing $[\cdot, \cdot]_{\partial D}$ is non-degenerate on $\mathcal{H}^1(\partial D)$:

$$\left([\omega_H, \eta_H]_{\partial D} = 0, \quad \forall \eta_H \in \mathcal{H}^1(D) \right) \implies [\omega_H, \star\omega_H]_{\partial D} = (\omega_H, \omega_H)_{1, \partial D} = 0. \quad (5.17)$$

LEMMA 5.6. *The space of harmonic 1-forms $\mathcal{H}^1(\partial D)$ is a symplectic space with finite dimension when equipped with the symplectic pairing $[\cdot, \cdot]_{\partial D}$. It is a finite-dimensional symplectic subspace of $W^{-\frac{1}{2}, 1}(d, \partial D)$.*

6. Some examples of self-adjoint curl operators. Starting from the Hodge decomposition of Theorem 5.2, we now identify important classes of self-adjoint extensions of **curl**. We rely on a generic Riemannian metric on ∂D and the associated Hodge operator.

6.1. Self-adjoint curl associated with closed traces. In this section we aim to characterize the complete Lagrangian subspaces L of $W^{-\frac{1}{2}, 1}(d, \partial D)$ (equipped with $[\cdot, \cdot]_{\partial D}$) which contain only closed forms:

$$L \subset Z^{-\frac{1}{2}, 1}(\partial D) := \{\eta \in W^{-\frac{1}{2}, 1}(d, \partial D) : d\eta = 0\}. \quad (6.1)$$

Hodge theory (see Theorem 5.2) provides the tools to study these Lagrangian subspaces, since we have the following result:

LEMMA 6.1. *The set of closed 1-forms in $W^{-\frac{1}{2}, 1}(d, \partial D)$ admits the following direct (orthogonal) decomposition*

$$Z^{-\frac{1}{2}, 1}(\partial D) = dW^{-\frac{1}{2}, 0}(d, \partial D) \oplus \mathcal{H}^1(\partial D). \quad (6.2)$$

Proof. For $\omega \in Z^{-\frac{1}{2}, 1}(\partial D)$, $\star d\omega_\perp$ of (5.11) satisfies

$$d(\star d\omega_\perp) = 0, \quad d\star(\star d\omega_\perp) = 0, \quad (\star d\omega_\perp)_H = 0 \quad (6.3)$$

which implies that $\star d\omega_\perp = 0$ and yields the assertion of the lemma. \square

The next result is important, as it states a necessary condition for the existence of Lagrangian subspaces included in $Z^{-\frac{1}{2}, 1}(\partial D)$.

LEMMA 6.2. *The space $Z^{-\frac{1}{2}, 1}(\partial D)$ includes its symplectic orthogonal $dW^{-\frac{1}{2}, 0}(d, \partial D)$.*

Proof. Recall from Definition 3.2 that the symplectic orthogonal of $Z^{-\frac{1}{2},1}(\partial D)$ is defined as the set

$$\{\omega \in W^{-\frac{1}{2},1}(\mathbf{d}, \partial D) : [\omega, \eta]_{\partial D} = 0, \quad \forall \eta \in Z^{-\frac{1}{2},1}(\partial D)\}. \quad (6.4)$$

Using Theorem 5.2 for $\omega = \mathbf{d}\omega_0 + \star \mathbf{d}\omega_\perp + \omega_H$ and Lemma 6.1 for $\eta = \mathbf{d}\eta_0 + \eta_H$, we have with (5.13):

$$[\omega, \eta]_{\partial D} = [\star \mathbf{d}\omega_\perp, \mathbf{d}\eta_0]_{\partial D} + [\omega_H, \eta_H]_{\partial D}. \quad (6.5)$$

This implies with $\eta = \star \omega_H = \eta_H$ (here we use the stability of $\mathcal{H}^1(\partial D)$ with respect to the Hodge operator)

$$[\omega, \star \omega_H]_{\partial D} = [\omega_H, \star \omega_H]_{\partial D} = \int_{\partial D} \omega_H \wedge \star \omega_H = 0 \quad \implies \quad \omega_H = 0, \quad (6.6)$$

and, for $\eta = \mathbf{d}\eta_0$ with $\eta_0 = \omega_\perp \in W^{3/2,0}(\partial D)$

$$[\omega, \mathbf{d}\omega_\perp]_{\partial D} = [\star \mathbf{d}\omega_\perp, \mathbf{d}\omega_\perp]_{\partial D} = - \int_{\partial D} \mathbf{d}\omega_\perp \wedge \star \mathbf{d}\omega_\perp \quad \implies \quad \mathbf{d}\omega_\perp = 0. \quad (6.7)$$

Hence, we have $\omega = \mathbf{d}\omega_0$ (and $\omega_H = 0$). The converse holds due to (6.5). \square

Lemma 6.2 tells us that, when restricted to the subspace of closed forms, the bilinear pairing $[\cdot, \cdot]_{\partial D}$ becomes degenerate. More precisely, on the subset of closed forms, one can use the splitting (6.5) and evaluate $[\cdot, \cdot]_{\partial D}$ on $Z^{-\frac{1}{2},1}(\partial D)$ according to

$$[\omega, \eta]_{\partial D} = [\omega_H, \eta_H]_{\partial D}, \quad \forall \omega, \eta \in Z^{-\frac{1}{2},1}(\partial D). \quad (6.8)$$

Hence, this pairing depends only on the harmonic components. Thus another message of Lemma 6.2 is that $[\cdot, \cdot]_{\partial D}$ furnishes a well-defined non-degenerate symplectic pairing, when considered on the co-homology factor space

$$\mathbb{H}^1(\partial D, \mathbb{R}) = Z^{-\frac{1}{2},1}(\partial D) / \mathbf{d}W^{-\frac{1}{2},0}(\mathbf{d}, \partial D). \quad (6.9)$$

This space is algebraically, topologically and symplectically isomorphic to $\mathcal{H}^1(\partial D)$, the space of harmonic 1-forms, see Section 5.3.

This means that all the complete Lagrangian subspaces L of $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ contained in $Z^{-\frac{1}{2},1}(\partial D)$ are related to complete Lagrangian subspaces $L_{\mathcal{H}}$ of $\mathcal{H}^1(\partial D)$ (or equivalently to the complete Lagrangian subspace $L_{\mathbb{H}}$ of $\mathbb{H}^1(\partial D, \mathbb{R})$) by

$$L = \mathbf{d}W^{-\frac{1}{2},0}(\mathbf{d}, \partial D) \oplus L_{\mathcal{H}} \quad (\text{or, equivalently, } L_{\mathcal{H}} = L / \mathbf{d}W^{-\frac{1}{2},0}(\mathbf{d}, \partial D)). \quad (6.10)$$

Thus, we have proved the following lemma (the symplectic pairing $[\cdot, \cdot]_{\partial D}$ is used throughout)

LEMMA 6.3. *There is a one-to-one correspondance between the complete Lagrangian subspaces L of the symplectic space $W^{-\frac{1}{2},1}(\mathbf{d}, \partial D)$ satisfying*

$$L \subset Z^{-\frac{1}{2},1}(\partial D) \quad (6.11)$$

and the complete Lagrangian subspaces $L_{\mathcal{H}}$ of $\mathcal{H}^1(\partial D)$. The bijection is given by (6.10).

Theorem 4.3 and Lemma 6.3 lead to the characterization of the self-adjoint **curl** operators whose domains contain only functions with closed traces.

THEOREM 6.4. *There is a one-to-one correspondance between the set of all selfadjoint **curl** operators $\star d_S$ satisfying*

$$\mathcal{D}(\star d_S) \subset \left\{ \omega \in W^1(d, D) \mid i^* \omega \in Z^{-\frac{1}{2}, 1}(\partial D) \right\} \quad (6.12)$$

and the set of complete Lagrangian subspaces $L_{\mathcal{H}}$ of $\mathcal{H}^1(\partial D)$. They are related according to

$$\mathcal{D}(\star d_S) = \left\{ \omega \in W^1(d, D) \mid i^* \omega \in dW^{-\frac{1}{2}, 0}(d, \partial D) \oplus L_{\mathcal{H}} \right\}. \quad (6.13)$$

Obviously, the constraint

$$i^* \omega \in dW^{-\frac{1}{2}, 0}(d, \partial D) \oplus L_{\mathcal{H}} \quad (6.14)$$

is a boundary condition, since it involves only the boundary of the domain D . In addition, we point out that no metric concepts enter in (6.13), *cf.* Section 4.

Remark 5. Now, assume the domain D to feature trivial topology, that is, the genus of D is zero, and the space of harmonic forms is trivial. Theorem 6.4 reveals that there is only one self-adjoint $\star d$ with domain containing only forms with closed traces

$$\mathcal{D}(\star d_S) = \left\{ \omega \in W^1(d, D) \mid d(i^* \omega) = 0 \right\}. \quad (6.15)$$

In terms of vector proxies, this leads to the self-adjoint **curl** operator with domain

$$\mathcal{D}(\mathbf{curl}_S) = \left\{ u \in W^0(\mathbf{curl}, D) \mid \mathbf{curl}(u) \cdot \mathbf{n} = 0 \text{ on } \partial D \right\}, \quad (6.16)$$

which has been investigated in [35, 39]. In case D has non-trivial topology, then $\dim(\mathcal{H}^1(\partial D)) = 2g \neq 0$ and one has to examine the complete Lagrangian subspaces of $\mathcal{H}^1(\partial D)$, which is postponed to Section 6.3.

6.2. Self-adjoint curl based on co-closed traces. In this section we seek to characterize those Lagrangian subspaces L of $W^{-\frac{1}{2}, 1}(d, \partial D)$ that contain only co-closed forms, *ie.*

$$L \subset \left\{ \omega \in W^{-1/2, 1}(d, \partial D) : d \star \omega = 0 \right\}. \quad (6.17)$$

The developments are parallel to those of the previous section, because, as is illustrated by (5.13), from a symplectic point of view, the subspaces of closed and co-closed 1-forms occuring in the Hodge decomposition of Theorem 5.2, are symmetric. For the sake of completeness, we give the details, nevertheless.

LEMMA 6.5. *The subspace of co-closed 1-forms of $W^{-1/2, 1}(d, \partial D)$ admits the following orthogonal decomposition*

$$\left\{ \omega \in W^{-1/2, 1}(d, \partial D) : d \star \omega = 0 \right\} = \star dW^{3/2, 0}(\partial D) \oplus \mathcal{H}^1(\partial D). \quad (6.18)$$

Proof. For ω co-closed, $d\omega_0$ in (5.11) satisfies

$$d(d\omega_0) = 0, \quad d \star (d\omega_0) = 0, \quad (d\omega_0)_H = 0 \quad (6.19)$$

which implies that $d\omega_0 = 0$ and proves (6.18). \square

The next result is important as it states a necessary condition for the existence of Lagrangian subspaces comprising only co-closed forms.

LEMMA 6.6. *The symplectic orthogonal of the subspace of co-closed forms of $W^{-1/2,1}(d, \partial D)$ is $\star dW^{3/2,0}(\partial D)$.*

Proof. Use the definition of the symplectic orthogonal as

$$\{\omega \in W^{-1/2,1}(d, \partial D) : [\omega, \eta]_{\partial D} = 0 \quad \forall \eta \text{ co-closed}\} . \quad (6.20)$$

Using Theorem 5.2 for $\omega = d\omega_0 + \star d\omega_{\perp} + \omega_H$ and Lemma 6.5 for $\eta = \star d\eta_{\perp} + \eta_H$, (5.13) gives

$$[\omega, \eta]_{\partial D} = [d\omega_0, \star d\eta_{\perp}]_{\partial D} + [\omega_H, \eta_H]_{\partial D} . \quad (6.21)$$

Choosing $\eta = \star\omega_H = \eta_H$ (here we use the stability of $\mathcal{H}^1(\partial D)$ with respect to the Hodge operator) this implies

$$[\omega, \star\omega_H]_{\partial D} = [\omega_H, \star\omega_H]_{\partial D} = \int_{\partial D} \omega_H \wedge \star\omega_H = 0 \quad \implies \quad \omega_H = 0,$$

and, for $\eta = \star d\eta_{\perp}$ with $\eta_{\perp} \in W^{\frac{3}{2},0}(\partial D)$

$$[\omega, \star d\eta_{\perp}]_{\partial D} = [d\omega_0, \star d\eta_{\perp}]_{\partial D} = \int_{\partial D} d\omega_0 \wedge \star d\eta_{\perp} = 0 \quad \implies \quad d\star(d\omega_0) = 0 .$$

Moreover, one has $d(d\omega_0) = 0$ and $(d\omega_0)_H = 0$, which shows that $d\omega_0 = 0$.

Hence, we have $\omega = \star d\omega_{\perp}$ ($d\omega_0 = 0$ and $\omega_H = 0$). The other inclusion holds due to (6.21). \square

Remark 6. Formally, in the proof we have used $\eta = \star d\eta_{\perp}$ with $\eta_{\perp} = \omega_0$ which shows that

$$[\omega, \eta]_{\partial D} = [d\omega_0, \star d\omega_0]_{\partial D} = \int_{\partial D} d\omega_0 \wedge \star d\omega_0 \quad \implies \quad d\omega_0 = 0. \quad (6.22)$$

However, the lack of regularity of ω_0 does not allow this straightforward computation.

When restricted to the space of co-closed forms, the bilinear pairing $[\cdot, \cdot]_{\partial D}$ becomes degenerate. However, due to Lemma 6.6, it is a non-degenerate symplectic product on the co-homology factor space.

$$\left\{ \omega \in W^{-1/2,1}(d, \partial D) : d\star\omega = 0 \right\} / \star dW^{3/2,0}(\partial D), \quad (6.23)$$

which can be identified with $\mathcal{H}^1(\partial D)$. Indeed, also on the subset of co-closed forms, one can evaluate $[\cdot, \cdot]_{\partial D}$ by means of (6.8).

LEMMA 6.7. *The complete Lagrangian subspaces L of $W^{-1/2,1}(d, \partial D)$ containing only co-closed forms are one-to-one related to the complete Lagrangian subspaces $L_{\mathcal{H}}$ of $\mathcal{H}^1(\partial D)$ by*

$$L = \star dW^{3/2,0}(\partial D) \oplus L_{\mathcal{H}} . \quad (6.24)$$

Theorem 4.3 and Lemma 6.7 lead to the characterization of the self-adjoint **curl** operators based on coclosed forms:

THEOREM 6.8. *There is a one to one correspondance between the set of all self-adjoint operators $\star d_S$ satisfying*

$$\mathcal{D}(\star d_S) \subset \left\{ \omega \in W^1(d, \partial D) : d\star(i^*\omega) = 0 \right\} \quad (6.25)$$

and the set of complete Lagrangian subspaces $L_{\mathcal{H}}$ of $\mathcal{H}^1(\partial D)$ equipped with $[\cdot, \cdot]_{\partial D}$. The underlying bijection is

$$\mathcal{D}(\star d_S) = \left\{ \omega \in W^1(d, D) : i^* \omega \in \star dW^{3/2,0}(\partial D) \oplus L_{\mathcal{H}} \right\}. \quad (6.26)$$

Remark 7. Let D be a domain with trivial topology. Then there is only one self-adjoint operator $\star d$ whose domain containing only forms whose traces are coclosed

$$\mathcal{D}(\star d_S) = \left\{ \omega \in W^0(d, \Omega) : d \star (i^* \omega) = 0 \right\}. \quad (6.27)$$

In terms of Euclidean vector proxies, we obtain the self-adjoint **curl** operator with domain

$$\mathcal{D}(\mathbf{curl}_S) = \left\{ \mathbf{u} \in \mathbf{H}(\mathbf{curl}, D) : \operatorname{div}_{\partial}(\gamma_t(\mathbf{u})) = 0 \text{ on } \partial D \right\}. \quad (6.28)$$

On the contrary, if D has non trivial topology, then one has to identify the complete Lagrangian subspaces of $\mathcal{H}^1(\partial D)$. This is the topic of the next section.

6.3. Complete Lagrangian subspaces of $\mathcal{H}^1(\partial D)$. The goal is to give a rather concrete description of the boundary conditions implied by (6.13) and (6.26). Concepts from topology will be pivotal.

To begin with we exploit a consequence of the long Mayer-Vietoris exact sequence in co-homology [4], namely the algebraic isomorphisms [23]

$$\mathcal{H}^1(\partial D) \cong \mathbb{H}^1(\partial D; \mathbb{R}) \cong i_{\text{in}}^* \mathbb{H}^1(D; \mathbb{R}) + i_{\text{out}}^* \mathbb{H}^1(D'; \mathbb{R}). \quad (6.29)$$

Here, $\mathbb{H}^1(D)$ is the co-homology space $Z^1(d, D)/dW^0(d, D)$, and $i_{\text{in}} : \partial D \mapsto D$, $i_{\text{out}} : \partial D \mapsto D'$ stand for the canonical inclusion maps. We also point out that [23]

$$\frac{1}{2} \dim \mathbb{H}^1(\partial D; \mathbb{R}) = \dim \mathbb{H}^1(D; \mathbb{R}) = \dim \mathbb{H}^1(D'; \mathbb{R}) = g, \quad (6.30)$$

where $g \in \mathbb{N}_0$ is the genus of D .

Next, we find bases of $\mathbb{H}^1(D; \mathbb{R})$ and $\mathbb{H}^1(D'; \mathbb{R})$ using the Poincaré duality between co-homology spaces and relative homology spaces¹

$$\mathbb{H}^1(D; \mathbb{R}) \cong \mathbb{H}_2(D, \partial D; \mathbb{R}). \quad (6.31)$$

Consider the relative homology groups (with coefficients in \mathbb{Z})

$$\mathbb{H}_2(D, \partial D; \mathbb{Z}) \quad \text{and} \quad \mathbb{H}_2(D', \partial D; \mathbb{Z}) \quad (6.32)$$

as integer lattices in the vector spaces

$$\mathbb{H}_2(D, \partial D; \mathbb{R}) \quad \text{and} \quad \mathbb{H}_2(D', \partial D; \mathbb{R}). \quad (6.33)$$

¹In this article, we denote by

- $\mathbb{H}_i(A; R)$ the i^{th} homology group of A with coefficients in R ;
- $\mathbb{H}^i(A; R)$ the i^{th} co-homology space of A with coefficients in R ;
- $\mathbb{H}_i(A, B; R)$ the i^{th} relative homology group of A relative to B with coefficients in R ;
- $\mathbb{H}^i(A, B; R)$ the i^{th} relative co-homology space of A relative to B with coefficients in R .

In [21], it is shown that these lattices as Abelian groups are torsion free, and that representatives of homology classes can be realized as orientable embedded surfaces. More precisely, we can find $2g$ compact orientable embedded Seifert surfaces, or "cuts"

$$S_i, S'_i, \quad 1 \leq i \leq g, \quad (6.34)$$

such that their equivalence classes under appropriate homology relations form bases for the following associated lattices²

$$\{\langle S_i \rangle\}_{i=1}^g \quad \text{for } \mathbb{H}_2(D, \partial D; \mathbb{Z}), \quad \{\langle S'_i \rangle\}_{i=1}^g \quad \text{for } \mathbb{H}_2(D', \partial D; \mathbb{Z}) \quad (6.35)$$

and

$$\{\langle \partial S'_i \rangle, \langle \partial S_i \rangle\}_{i=1}^g \quad \text{for } \mathbb{H}_1(\partial D; \mathbb{Z}). \quad (6.36)$$

In other words, the boundaries $\partial S_i, \partial S'_i$ provide fundamental non-bounding cycles on ∂D .

In [23], it was established that the set of surfaces $\{\langle S_i \rangle\}_{i=1}^g \cup \{\langle S'_i \rangle\}_{i=1}^g$ can be chosen so that they are "dual to each other". Here, this duality is expressed through the intersection numbers of their boundaries, see Chapter 5 of [18].

LEMMA 6.9. *The set of surfaces $\{\langle S_i \rangle\}_{i=1}^g \cup \{\langle S'_i \rangle\}_{i=1}^g$ can be chosen such that the intersection pairing on $\mathbb{H}_1(\partial D; \mathbb{Z})$ can be reduced to $(1 \leq i, j \leq g)$*

$$\begin{cases} \text{Int}(\langle \partial S_i \rangle, \langle \partial S'_j \rangle) = \delta_{i,j}, \\ \text{Int}(\langle \partial S'_i \rangle, \langle \partial S_j \rangle) = -\delta_{i,j}. \end{cases} \quad (6.37)$$

Furthermore, when the boundaries of these surfaces are "pushed out" of their respective regions of definition, we get curves in the complementary region

$$\partial S'_i \longrightarrow C_i, \quad \partial S_i \longrightarrow C'_i. \quad (6.38)$$

The homology classes of these curves form bases for homology lattices as follows

$$\{\langle C_i \rangle\}_{i=1}^g \quad \text{for } \mathbb{H}_1(D; \mathbb{Z}), \quad \text{and} \quad \{\langle C'_i \rangle\}_{i=1}^g \quad \text{for } \mathbb{H}_1(D'; \mathbb{Z}). \quad (6.39)$$

This paves the way for a construction of bases of the co-homology spaces on D and D' [23]:

LEMMA 6.10. *The co-homology classes generated by the closed 1-form in the sets defined for $1 \leq i \leq g$*

$$\begin{aligned} & \left\{ \kappa_i \in L^2(\Lambda^1(D)) : d\kappa_i = 0 \text{ and } \int_{C_j} \kappa_i = \delta_{ij} \text{ for } 1 \leq j \leq g \right\} \\ & \left\{ \kappa'_i \in L^2(\Lambda^1(D')) : d\kappa'_i = 0 \text{ and } \int_{C'_j} \kappa'_i = \delta_{ij} \text{ for } 1 \leq j \leq g \right\} \end{aligned}$$

form bases of $\mathbb{H}^1(D; \mathbb{R})$ and $\mathbb{H}^1(D'; \mathbb{R})$, respectively.

For instance, κ_i can be obtained as the piecewise exterior derivative of a 0-form on $D \setminus S_i$ that has a jump of height 1 across S_i . An analogous statement holds for κ'_i with S_i replaced with S'_i . More precisely, one has for $1 \leq i \leq g$

$$\exists \psi_i \in W^0(\mathfrak{d}, D) : \kappa_i = d\psi_i \quad \text{on } D \setminus S \quad \text{and} \quad [\psi_i]_{S_j} = \delta_{i,j} \quad (6.40)$$

²Throughout the paper $\langle \cdot \rangle$ denotes the operation of taking the (relative) homology class of a cycle

$$\exists \psi'_i \in W^0(\mathbf{d}, D) : \kappa'_i = \mathbf{d} \psi'_i \quad \text{on } D' \setminus S' \quad \text{and} \quad [\psi'_i]_{S'_j} = \delta_{i,j} \quad (6.41)$$

with $[\cdot]_\Gamma$ denoting the jump across Γ .

LEMMA 6.11. *For $1 \leq m, n \leq g$, we have*

$$\begin{aligned} a) \quad & \int_{\partial D} i_{in}^*(\kappa_m) \wedge i_{in}^*(\kappa_n) = 0, \\ b) \quad & \int_{\partial D} i_{out}^*(\kappa'_m) \wedge i_{out}^*(\kappa'_n) = 0. \end{aligned} \quad (6.42)$$

Proof. To establish a) we rewrite the integral as one over D , as the following calculation shows

$$\begin{cases} \int_{\partial D} i_{in}^*(\kappa_m) \wedge i_{in}^*(\kappa_n) &= \int_{\partial D} i_{in}^*(\kappa_m \wedge \kappa_n) = \int_D \mathbf{d}(\kappa_m \wedge \kappa_n) \\ &= \int_D (\mathbf{d} \kappa_m) \wedge \kappa_n - \kappa_m \wedge (\mathbf{d} \kappa_n) = 0. \end{cases}$$

Similarly, b) follows from an analogous calculation where $\partial D = -\partial D'$ with forms defined on D' . \square

LEMMA 6.12. *For $1 \leq i, j \leq g$, we have*

$$\int_{\partial D} i_{in}^*(\kappa_i) \wedge i_{out}^*(\kappa'_j) = \delta_{i,j}. \quad (6.43)$$

Proof. Let us represent the 1-form κ_i by means the 0-form ψ_i , which jumps across S_i , see (6.40). Taking into account that $\mathbf{d} i_{out}^* \kappa'_j = 0$, we get

$$i_{in}^* \kappa_i \wedge i_{out}^* \kappa'_j = \mathbf{d} i_{in}^* \psi_i \wedge i_{out}^* \kappa'_j = \mathbf{d} (i_{in}^* \psi_i \wedge i_{out}^* \kappa'_j). \quad (6.44)$$

Applying Stokes Theorem leads to (one has to take care of the orientation)

$$\int_{\partial D} i_{in}^* \kappa_i \wedge i_{out}^* \kappa'_j = \int_{\partial S_i} [i_{in}^* \psi_i \wedge i_{out}^* \kappa'_j]_{\partial S_i} + \int_{\partial S'_j} [i_{in}^* \psi_i \wedge i_{out}^* \kappa'_j]_{\partial S_i}. \quad (6.45)$$

By (6.40), we get

$$\int_{\partial D} i_{in}^* \kappa_i \wedge i_{out}^* \kappa'_j = \int_{\partial S_i} \kappa'_j + 0. \quad (6.46)$$

Since $\partial S_i \in \langle C'_i \rangle$, the result follows from (6.38) and Lemma 6.10. \square

Remark 8. When the cuts do not satisfy (6.37), a generalization of Lemma 6.12 takes the form

$$\int_{\partial D} i_{in}^*(\kappa_i) \wedge i_{out}^*(\kappa'_j) = \text{Int}(\langle \partial S_i \rangle, \langle \partial S'_j \rangle). \quad (6.47)$$

with $\text{Int}(\langle \partial S_i \rangle, \langle \partial S'_j \rangle)$ the intersection number of $\langle \partial S_i \rangle$ and $\langle \partial S'_j \rangle$, see [18].

Now, take (6.37) for granted. Write $\kappa_{H,i}, \kappa'_{H,i}, 1 \leq i \leq g$, for the unique harmonic 1-forms, i.e., $\kappa_{H,i}, \kappa'_{H,i} \in \mathcal{H}^1(\partial D)$, such that

$$i_{in}^* \kappa_i = \kappa_{H,i} + \mathbf{d} \alpha \quad , \quad i_{out}^* \kappa'_i = \kappa'_{H,i} + \mathbf{d} \beta, \quad (6.48)$$

for some $\alpha, \beta \in L^2(\Lambda^0(\partial D))$. Combining Lemmas 6.11 and 6.12 gives the desired symplectic basis of the space of harmonic 1-forms on ∂D :

LEMMA 6.13. *The set $\{\kappa_{H,i}, \kappa'_{H,i}\}_{i=1}^g$ is a symplectic basis of $\mathcal{H}^1(\partial D)$.*

Obviously, since the trace preserves integrals and integrating a closed form over a cycle evaluates to zero, the 1-forms $\kappa_{H,i}$ and $\kappa'_{H,i}$ inherit the integral values over fundamental cycles from κ_i and κ'_i , cf. Lemma 6.10:

$$\int_{\partial S_j} \kappa_{H,i} = \delta_{ij}, \quad \int_{\partial S'_j} \kappa_{H,i} = 0, \quad \int_{\partial S'_j} \kappa'_{H,i} = \delta_{ij}, \quad \int_{\partial S_j} \kappa'_{H,i} = 0. \quad (6.49)$$

LEMMA 6.14. *Given interior and exterior Seifert surfaces S_i, S'_i , the conditions (6.49) uniquely determine a symplectic basis $\{\kappa_{H,1}, \dots, \kappa_{H,g}, \kappa'_{H,1}, \dots, \kappa'_{H,g}\}$ of $\mathcal{H}^1(\partial D)$.*

Proof. If there was another basis complying with (6.49), the differences of the basis forms would be harmonic 1-forms with vanishing integral over *any* cycle. They must vanish identically. \square

Given a symplectic basis, we can embark on the canonical construction of complete Lagrangian subspaces of $\mathcal{H}^1(\partial D)$ presented in Remark 3. We start from a partition

$$I \cup I' = \{1, \dots, g\}, \quad I \cap I' = \emptyset. \quad (6.50)$$

Owing to Lemma 6.12 and (6.37) the symplectic pairing $[\cdot, \cdot]_{\partial D}$ has the matrix representation

$$\begin{bmatrix} \mathbf{0}_{g \times g} & \mathbf{I}_{g \times g} \\ -\mathbf{I}_{g \times g} & \mathbf{0}_{g \times g} \end{bmatrix} \in \mathbb{R}^{2g, 2g}, \quad (6.51)$$

with respect to the basis

$$\left(\{\kappa_{H,i}\}_{i \in I} \cup \{-\kappa'_{H,i}\}_{i \in I'} \right) \cup \left(\{-\kappa'_{H,i}\}_{i \in I} \cup \{\kappa_{H,i}\}_{i \in I'} \right) \quad (6.52)$$

of $\mathcal{H}^1(\partial D)$. Thus,

$$L_{\mathcal{H}} := \text{span}\{\kappa_{H,i}\}_{i \in I} \cup \{-\kappa'_{H,i}\}_{i \in I'} \quad (6.53)$$

will yield a complete Lagrangian subspace of $\mathcal{H}^1(\partial D)$. By theorems 6.4 and 6.8, $L_{\mathcal{H}}$ induces self-adjoint $\mathbf{curl} = \star \mathbf{d}$ operators. From Lemma 6.1, Lemma 6.5 and (6.49) we learn that their domains allow the characterization

$$\mathcal{D}(\mathbf{curl}_s) := \left\{ \omega \in W^1(\mathbf{d}, D) : \mathbf{d}(i^* \omega) = 0, \int_{\partial S_j} \omega = 0, j \in I, \int_{\partial S'_j} \omega = 0, j \in I' \right\} \quad (6.54)$$

in the case of closed traces, and

$$\mathcal{D}(\mathbf{curl}_s) := \left\{ \omega \in W^1(\mathbf{d}, D) : \mathbf{d} \star (i^* \omega) = 0, \int_{\partial S_j} \omega = 0, j \in I, \int_{\partial S'_j} \omega = 0, j \in I' \right\}, \quad (6.55)$$

in the case of co-closed traces, respectively. In fact, the choice $I' = \emptyset$ together with closed trace is the one proposed in [39] to obtain a self-adjoint \mathbf{curl} .

7. Spectral properties. Having constructed self-adjoint versions of the **curl** operator, we go on to verify whether their essential spectrum is confined to 0 and their eigenfunctions can form a complete orthonormal system in $\mathbf{L}^2(D)$. These are common important features of self-adjoint partial differential operators.

The following compact embedding result is instrumental in investigating the spectrum of \mathbf{curl}_s . Related results can be found in [37] and [32].

THEOREM 7.1 (Compact embedding). *The spaces, endowed with the $W^1(d, D)$ -norm,*

$$X_0 := \{\omega \in W^1(d, D) : d^* \omega = 0, i^*(\star \omega) = 0\}$$

$$\text{and } X^\perp := \{\omega \in W^1(d, D) : d^* \omega = 0, d\star(i^* \omega) = 0\}$$

are compactly embedded into $L^2(\Lambda^1(D))$.

Remark 9. In terms of Euclidean vector proxies these spaces read

$$X_0 = \{\mathbf{v} \in \mathbf{H}(\mathbf{curl}, D) : \operatorname{div} \mathbf{v} = 0, \gamma_n \mathbf{u} = 0\},$$

$$X^\perp = \{\mathbf{v} \in \mathbf{H}(\mathbf{curl}, D) : \operatorname{div} \mathbf{v} = 0, \operatorname{div}_\partial(\gamma_t \mathbf{u}) = 0\}$$

where the constraint $\operatorname{div}_\partial(\gamma_t \mathbf{u}) = 0$ should be read as “orthogonality” to $\mathbf{grad}_\partial H^{\frac{1}{2}}(\partial D)$ in the sense of the Hodge decomposition.

Proof. [of Thm. 7.1] The proof will be given for X^\perp only. The simpler case of X_0 draws on the same ideas. We are using vector proxy notation, because the proof takes us beyond the calculus of differential forms. Note that the inner product chosen for the vector proxies does not affect the statement of the theorem.

A key tool is the so-called regular decomposition theorem that was discovered in [3], consult [19, Sect. 2.4] for a comprehensive presentation including proofs. It asserts that there is $C > 0$ depending only on D such that for all $\mathbf{u} \in \mathbf{H}(\mathbf{curl}, D)$ there are functions $\Phi \in (H^1(D))^3$, $\varphi \in H^1(D)$, with

$$\mathbf{u} = \Phi + \mathbf{grad} \varphi \quad , \quad \|\Phi\|_{H^1(D)} + |\varphi|_{H^1(D)} \leq C \|\mathbf{u}\|_{\mathbf{H}(\mathbf{curl}, D)} . \quad (7.1)$$

Let $(\mathbf{u}_n)_{n \in \mathbb{N}}$ be a bounded sequence in X^\perp that is

$$\operatorname{div} \mathbf{u}_n = 0 \quad \text{in } D \quad \text{and} \quad \operatorname{div}_\partial(\gamma_t \mathbf{u}_n) = 0 \quad \text{on } \partial D , \quad (7.2)$$

$$\exists C > 0 : \quad \|\mathbf{u}_n\|_{L^2(D)} + \|\mathbf{curl} \mathbf{u}_n\|_{L^2(D)} \leq C . \quad (7.3)$$

Write $\mathbf{u}_n = \Phi_n + \mathbf{grad} \varphi_n$ for the regular decomposition according to (7.1). Thus, $(\Phi_n)_{n \in \mathbb{N}}$ is bounded in $(H^1(D))^3$ and, by Rellich’s theorem, will possess a sub-sequence that converges in $\mathbf{L}^2(D)$. We pick the corresponding sub-sequence of $(\mathbf{u}_n)_{n \in \mathbb{N}}$ without changing the notation.

Further,

$$\operatorname{div} \mathbf{u}_n = 0 \quad \Rightarrow \quad -\Delta \varphi_n = \operatorname{div} \Phi_n \quad (\text{bounded in } L^2(D)) , \quad (7.4)$$

$$\operatorname{div}_\partial(\gamma_t \mathbf{u}) = 0 \quad \Rightarrow \quad -\Delta_{\partial D}(\gamma \varphi_n) = \operatorname{div}_\partial(\gamma_t \Phi_n) \quad (\text{bounded in } H^{-\frac{1}{2}}(\partial D)) . \quad (7.5)$$

We conclude that $(\gamma \varphi_n)_{n \in \mathbb{N}}$ is bounded in $H^1(\partial D)$ and, hence, has a convergent sub-sequence in $H^{\frac{1}{2}}(\partial D)$ (for which we still use the same notation). The harmonic extensions $\tilde{\varphi}_n$ of $\gamma \varphi_n$ will converge in $H^1(D)$.

Finally, the solutions $\hat{\varphi}_n \in H^1(D)$ of the boundary value problems

$$-\Delta \hat{\varphi}_n = \operatorname{div} \Phi_n \quad \text{in } D \quad , \quad \hat{\varphi}_n = 0 \quad \text{on } \partial D , \quad (7.6)$$

will possess a sub-sequence that converges in $H^1(D)$, as $(-\Delta_{\text{Dir}})^{-1}L^2(D)$ is compactly embedded in $H^1(D)$. Since $\varphi_n = \tilde{\varphi}_n + \hat{\varphi}_n$, this provides convergence of a subsequence of $(\Phi_n + \mathbf{grad} \varphi_n)_{n \in \mathbb{N}}$ in $L^2(D)$. \square

Let $\mathbf{curl}_s : \mathcal{D}_s \subset L^2(\Lambda^1(D)) \mapsto L^2(\Lambda^1(D))$ be one of the self-adjoint realizations of \mathbf{curl} discussed in the previous section. Recall that we pursued two constructions based on closed and co-closed traces, respectively.

Remark 10. Even if the domain \mathcal{D}_s of the self-adjoint \mathbf{curl}_s is known only up to the contribution of a Lagrangian subspace of $L_{\mathcal{H}}$, we can already single out special subspaces of \mathcal{D}_s :

- (i) For the \mathbf{curl} operators based on closed traces, see Sect. 6.1, in particular Thm. 6.4, we find

$$\mathbf{d}W^0(\mathbf{d}, D) \subset \mathcal{D}_s . \quad (7.7)$$

Indeed, for $\omega \in \mathbf{d}W^0(\mathbf{d}, D)$ there exists $\eta \in W^0(\mathbf{d}, D)$ with $\omega = \mathbf{d}\eta$. Due to the trace theorem, $i^*\eta$ belongs to $W^{-\frac{1}{2}}(\mathbf{d}, \partial D)$. Consequently, it follows from the commutative relation (2.6) that $i^*\omega = \mathbf{d}i^*\eta$ belongs to $\mathbf{d}W^{-\frac{1}{2}}(\mathbf{d}, \partial D)$. We conclude using (6.13).

- (ii) For the \mathbf{curl} operators based on co-closed traces introduced in Sect. 6.2, it follows that

$$\mathbf{d}W_0^0(\mathbf{d}, D) \subset \mathcal{D}_s . \quad (7.8)$$

This is immediate from the fact that

$$\eta \in W_0^0(\mathbf{d}, D) \text{ and } \omega = \mathbf{d}\eta \text{ implies } i^*\omega = \mathbf{d}i^*\eta = 0 , \quad (7.9)$$

which means that ω belongs to \mathcal{D}_s , see (6.26).

In the sequel, the kernel of \mathbf{curl}_s will be required. We recall that

$$\mathcal{N}(\mathbf{curl}_s) = \mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_{\max})$$

is a closed subspace of $L^2(\Lambda^1(D))$. Moreover, since $\mathbf{d}^2 = 0$ and due to (7.7) and (7.8), one has

$$\mathbf{d}W^0(\mathbf{d}, D) \subset \mathcal{N}(\mathbf{curl}_s) \quad \text{in the closed case,} \quad (7.10)$$

$$\mathbf{d}W_0^0(\mathbf{d}, D) \subset \mathcal{N}(\mathbf{curl}_s) \quad \text{in the co-closed case.} \quad (7.11)$$

LEMMA 7.2. *The operator \mathbf{curl}_s is bounded from below on $\mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp$:*

$$\exists C = C(D) : \quad \|\omega\| \leq C \|\mathbf{curl}_s \omega\| \quad \forall \omega \in \mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp .$$

Proof. The indirect proof will be elaborated for the case of co-closed traces only. The same approach will work for closed traces.

We assume that there is a sequence $(\omega_n)_{n \in \mathbb{N}} \subset \mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp$ such that

$$\|\omega_n\| = 1 \quad , \quad \|\mathbf{curl}_s \omega_n\| \leq n^{-1} \quad \forall n \in \mathbb{N} . \quad (7.12)$$

Since $\omega_n \in \mathcal{N}(\mathbf{curl}_s)^\perp$, the inclusion (7.11) implies that $\mathbf{d}^*\omega_n = 0$. As a consequence of (7.12), $(\omega_n)_{n \in \mathbb{N}}$ is a bounded sequence in X^\perp . Theorem 7.1 tells us that it will possess a subsequence that converges in $L^2(\Lambda^1(D))$, again we call it $(\omega_n)_{n \in \mathbb{N}}$. Thanks

to (7.12) it will converge in the graph norm on \mathcal{D}_s and the non-zero limit will belong to $\mathcal{N}(\mathbf{curl}_s) \cap \mathcal{N}(\mathbf{curl}_s)^\perp = \{0\}$. This contradicts $\|\omega_n\| = 1$. \square

From Lemma 7.2 we conclude that the range space $\mathcal{R}(\mathbf{curl}_s)$ is a closed subspace of $L^2(\Lambda^1(D))$, which means,

$$\mathcal{R}(\mathbf{curl}_s) = \mathcal{N}(\mathbf{curl}_s)^\perp . \quad (7.13)$$

Thus, we are lead to consider the symmetric, bijective operator

$$\mathbf{C} := \mathbf{curl}_s : \mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp \subset \mathcal{N}(\mathbf{curl}_s)^\perp \mapsto \mathcal{N}(\mathbf{curl}_s)^\perp . \quad (7.14)$$

It is an isomorphism, when $\mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp$ is equipped with the graph norm, and $\mathcal{N}(\mathbf{curl}_s)^\perp$ with the $L^2(\Lambda^1(D))$ -norm. Its inverse \mathbf{C}^{-1} is a bounded, self-adjoint operator.

THEOREM 7.3. *The operator \mathbf{curl}_s has a pure point spectrum with ∞ as sole accumulation point. It possesses a complete L^2 -orthonormal system of eigenfunctions.*

Proof. The inverse operator

$$\mathbf{C}^{-1} : \mathcal{N}(\mathbf{curl}_s)^\perp \mapsto \mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp \quad (7.15)$$

is even *compact* as a mapping $L^2(\Lambda^1(D)) \mapsto L^2(\Lambda^1(D))$. Indeed, due to (7.10) and (7.11) the range of \mathbf{C}^{-1} satisfies

$$\mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp \subset X_0 \text{ in the closed case,} \quad (7.16)$$

$$\mathcal{D}_s \cap \mathcal{N}(\mathbf{curl}_s)^\perp \subset X^\perp \text{ in the co-closed case.} \quad (7.17)$$

By Theorem 7.1, the compactness follows. Riesz-Schauder theory [40, Sect. X.5] tells us that, except for 0 its spectrum will be a pure (discrete) point spectrum with zero as accumulation point and it will possess a complete orthonormal system of eigenfunctions.

The formula, see [38, Thm. 5.10],

$$\lambda^{-1} - \mathbf{C}^{-1} = \lambda^{-1}(\mathbf{C} - \lambda)\mathbf{C}^{-1} \quad (7.18)$$

shows that for $\lambda \neq 0$,

- $\lambda^{-1} - \mathbf{C}^{-1}$ bijective $\Rightarrow \mathbf{C} - \lambda$ bijective ,
- $\mathcal{N}(\lambda^{-1} - \mathbf{C}^{-1}) = \mathcal{N}(\mathbf{C} - \lambda)$.

Thus, $\sigma(\mathbf{C}) = (\sigma(\mathbf{C}^{-1}) \setminus \{0\})^{-1}$ and the eigenfunctions are the same. \square

8. **curl** and **curl curl**.

8.1. Self-adjoint **curl curl operators.** In the context of electromagnetism we mainly encounter the self-adjoint operator **curl curl**. Now we explore its relationship with the **curl** operators discussed before. A metric on D and an associated Hodge operator \star will be taken for granted.

DEFINITION 8.1. *A linear operator $\mathbf{S} : \mathcal{D}(\mathbf{S}) \subset L^2(\Lambda^1(D)) \mapsto L^2(\Lambda^1(D))$ is a **curl curl** operator, if and only if \mathbf{S} is a closed extension of the operator $\star d \star d$ defined for smooth compactly supported 1-forms.*

Two important extensions of the **curl curl** operator are the maximal and the minimal extensions:

LEMMA 8.2. *The domain of the minimal closed extension $(\mathbf{curl\ curl})_{\min}$ of the **curl curl** operator is*

$$\mathcal{D}_{\min} = \left\{ \omega \in W_0^1(d, D) : \star d\omega \in W_0^1(d, D) \right\} \quad (8.1)$$

or, equivalently, in terms of Euclidean vector proxies

$$\mathcal{D}_{\min} = \left\{ \mathbf{u} \in \mathbf{L}^2(D) : \mathbf{curl\ curl\ u} \in \mathbf{L}^2(D), \mathbf{curl\ curl\ u} \in \mathbf{L}^2(D), \right. \\ \left. \gamma_t(\mathbf{u}) = 0, \text{ and } \gamma_t(\mathbf{curl\ u}) = 0 \text{ on } \partial D \right\}.$$

The adjoint of $(\mathbf{curl\ curl})_{\min}$ is the maximal closed extension $(\mathbf{curl\ curl})_{\max}$. It is an extension of the **curl curl** operator with domain

$$\mathcal{D}_{\max} = \mathcal{D}_1 \oplus \mathcal{D}_2, \quad (8.2)$$

with

$$\mathcal{D}_1 = \left\{ \omega \in W_0^1(d, D) : \star d\omega \in W^1(d, D) \right\}, \quad (8.3)$$

$$\mathcal{D}_2 = \left\{ \omega \in L^2(\Lambda^1(D)) : d\star d\omega = 0 \right\}. \quad (8.4)$$

Proof. The domain \mathcal{D}_{\min} of the minimal closure is straightforward. We recall the definition of the domain of the adjoint \mathbb{T}^* of an operator $\mathbb{T} : \mathcal{D}(\mathbb{T}) \subset H \mapsto H$

$$\mathcal{D}(\mathbb{T}^*) = \left\{ u \in H : \exists C_u > 0 : (u, \mathbb{T}v)_H \leq C_u \|v\|_H \quad \forall v \in \mathcal{D}(\mathbb{T}) \right\}. \quad (8.5)$$

Let \mathcal{D}_{\max} stand for the domain of the adjoint of the minimal **curl curl** operator. First we show that

$$\mathcal{D}_1 \oplus \mathcal{D}_2 \subset \mathcal{D}_{\max}. \quad (8.6)$$

Let us consider $\omega \in \mathcal{D}_1$ and $\eta \in \mathcal{D}_{\min}$. By integration by parts and the isometry properties of \star we get

$$\int_D \omega \wedge d\star d\eta = \int_D d\star d\omega \wedge \eta \leq \|d\star d\omega\| \|\eta\|. \quad (8.7)$$

This involves $\mathcal{D}_1 \subset \mathcal{D}_{\max}$.

Now we consider $\omega \in \mathcal{D}_2$. The relation $d\star d\omega = 0$ has to be understood as

$$\int_D d\star d\omega \wedge \eta = 0 \quad \forall \eta \in \Lambda^1(D) \text{ smooth, compactly supported}. \quad (8.8)$$

As the smooth compactly supported 1-forms are dense in \mathcal{D}_{\min} with respect to the topology induced by the norm

$$\|\omega\| + \|\mathbf{curl}(\omega)\| + \|\mathbf{curl}(\mathbf{curl}(\omega))\|, \quad (8.9)$$

it follows that

$$\int_D \omega \wedge \mathbf{d} \star \mathbf{d} \eta = 0 \quad \forall \eta \in \mathcal{D}_{\min}, \quad (8.10)$$

and, finally, $\mathcal{D}_2 \subset \mathcal{D}_{\max}$. This confirms (8.6).

Next, we prove

$$\mathcal{D}_{\max} \subset \mathcal{D}_1 \oplus \mathcal{D}_2. \quad (8.11)$$

Pick, $\omega \in \mathcal{D}_{\max}$. There exists $\varphi \in L^2(\Lambda^1(D))$ such that

$$\int_D \omega \wedge \mathbf{d} \star \mathbf{d} \eta = \int_D \varphi \wedge \star \eta \quad \forall \eta \in \mathcal{D}_{\min}. \quad (8.12)$$

Since $\mathbf{d}^* \varphi = 0$ (pick $\eta = \mathbf{d} \nu$ in (8.12)), and $\int_D \varphi \wedge \star \eta_{\mathcal{H}} = 0$ for $\eta_{\mathcal{H}} \in \mathcal{H}^1(D)$, there exists $\omega_1 \in W^1(\mathbf{d}, D)$ satisfying

$$\begin{cases} \star \mathbf{d} \star \mathbf{d} \omega_1 = \varphi & \text{in } D, \\ i^* \omega_1 = 0 & \text{on } \partial D. \end{cases} \quad (8.13)$$

Note that this ω_1 belongs to \mathcal{D}_1 . Then $\omega_2 = \omega - \omega_1$ satisfies

$$\int_D (\omega - \omega_1) \wedge \mathbf{d} \star \mathbf{d} \eta = 0 \quad \forall \eta \in \mathcal{D}_{\min} \implies \mathbf{d} \star \mathbf{d} \omega_2 = 0. \quad (8.14)$$

It follows that $\omega_2 \in \mathcal{D}_2$. Since $\omega = \omega_1 + \omega_2$, we have proven (8.11). \square

Remark 11. The last lemma gives a nice example for

$$(\mathbb{T}^2)^* \neq (\mathbb{T}^2)^*.$$

Indeed, the minimal extension of the formal **curl curl** boils down to the squared minimal **curl** operator \mathbf{curl}_{\min} with domain $W_0^1(\mathbf{d}, D)$

$$(\mathbf{curl} \mathbf{curl})_{\min} = \mathbf{curl}_{\min} \mathbf{curl}_{\min}$$

The adjoint of \mathbf{curl}_{\min} is the \mathbf{curl}_{\max} operator with domain $W^1(\mathbf{d}, D)$, but

$$(\mathbf{curl} \mathbf{curl})_{\max} \neq \mathbf{curl}_{\max} \mathbf{curl}_{\max}.$$

To identify self-adjoint **curl curl** operators we could also rely on the toolkit of symplectic algebra, using the metric-dependent symplectic pairing

$$[\omega, \eta] = \int_D \mathbf{d} \star \mathbf{d} \omega \wedge \eta - \int_D \omega \wedge \mathbf{d} \star \mathbf{d} \eta. \quad (8.15)$$

As before, complete Lagrangian subspaces will give us self-adjoint extensions of $(\mathbf{curl} \mathbf{curl})_{\min}$ that are restrictions of $(\mathbf{curl} \mathbf{curl})_{\max}$. However, we will not pursue this further.

There are two classical self-adjoint **curl curl** operators that play a central role in electromagnetic boundary value problems. Their domains are

$$\mathcal{D}((\mathbf{curl} \mathbf{curl})_{\text{Dir}}) = \left\{ \omega \in W_0^1(\mathbf{d}, D) : \star \mathbf{d} \omega \in W^1(\mathbf{d}, D) \right\}, \quad (8.16)$$

$$\mathcal{D}((\mathbf{curl} \mathbf{curl})_{\text{Neu}}) = \left\{ \omega \in W^1(\mathbf{d}, D) : \star \mathbf{d} \omega \in W_0^1(\mathbf{d}, D) \right\}. \quad (8.17)$$

Both can be written as the product of a **curl** operator and its adjoint:

$$(\mathbf{curl} \mathbf{curl})_{\text{Dir}} = \mathbf{curl}_{\max} \mathbf{curl}_{\min} \quad , \quad (\mathbf{curl} \mathbf{curl})_{\text{Neu}} = \mathbf{curl}_{\min} \mathbf{curl}_{\max} . \quad (8.18)$$

Less familiar self-adjoint **curl curl** operators will emerge from taking the square of a self-adjoint **curl** operator as introduced in Section 6.

8.2. Square roots of curl curl operators. It is natural to ask whether any self-adjoint **curl curl** operator can be obtained as the square of a self-adjoint **curl**. We start with reviewing the abstract theory of square roots of operators, see [38, Sect. 7.3].

Let S be a positive (unbounded) self-adjoint operator on the Hilbert space H . We recall from [38, Thm. 7.20] that there exists a unique self-adjoint positive (unbounded) operator R satisfying

$$S = R^2, \text{ i.e. } \mathcal{D}(S) = \mathcal{D}(R^2) := \{u \in \mathcal{D}(R) / Ru \in \mathcal{D}(R)\} \text{ and } Su = R^2u \text{ if } u \in \mathcal{D}(S). \quad (8.19)$$

LEMMA 8.3 (domain of square roots). *Let R_1 and R_2 be two closed densely defined unbounded operators on H with domains $\mathcal{D}(R_1), \mathcal{D}(R_2) \subset H$.*

If $R_1^ R_1 = R_2^* R_2$, that is,*

$$\mathcal{D}(R_1^* R_1) = \mathcal{D}(R_2^* R_2) \quad \text{and} \quad \forall u \in \mathcal{D}(R_1^* R_1), \quad R_1^* R_1 u = R_2^* R_2 u ,$$

then $\mathcal{D}(R_1) = \mathcal{D}(R_2)$.

Proof. For $i = 1, 2$, $\mathcal{D}(R_i)$ equipped with the scalar product $(u, v)_i = (u, v)_H + (R_i u, R_i v)_H$ is a Hilbert space.

Let us first prove that $\mathcal{D}(R_i^* R_i)$ is dense in $\mathcal{D}(R_i)$ with respect to $(\cdot, \cdot)_i$. We consider $u \in \mathcal{D}(R_i^* R_i)^\perp$

$$\forall v \in \mathcal{D}(R_i^* R_i), \quad 0 = (u, v)_i = (u, v)_H + (R_i u, R_i v)_H = (u, v + R_i^* R_i v)_H \quad (8.20)$$

As $\text{Id} + R_i^* R_i$ is surjective from $\mathcal{D}(R_i^* R_i)$ to H , see [36, Theorem 13.31], u is equal to zero.

Hence, the spaces $\mathcal{D}(R_1)$ and $\mathcal{D}(R_2)$ share the dense subspace $\mathcal{D}(R_1^* R_1) = \mathcal{D}(R_2^* R_2)$. Moreover, their scalar products coincide on this subset:

$$(u, v)_H + (R_1 u, R_1 v)_H = (u, v + R_1^* R_1 v)_H = (u, v + R_2^* R_2 v)_H = (u, v)_H + (R_2 u, R_2 v)_H.$$

We conclude using Cauchy sequences. \square

Surprisingly, the simple self-adjoint operator $(\mathbf{curl} \mathbf{curl})_{\text{Dir}}$ does not have a square root that is a self-adjoint **curl**:

LEMMA 8.4. *The **curl curl** operator $\mathbf{curl}_{\max} \mathbf{curl}_{\min}$ does not have a square root that is a self-adjoint **curl**.*

Proof. Let us suppose that $T = \mathbf{curl}_{\max} \mathbf{curl}_{\min}$ admits a **curl** self-adjoint square root S which implies that

$$\mathbf{curl}_{\max} \mathbf{curl}_{\max}^* = \mathbf{curl}_{\max} \mathbf{curl}_{\min} = T = S^2 = S S^* . \quad (8.21)$$

since \mathbf{curl}_{\max} and \mathbf{curl}_{\min} are adjoint and \mathbf{S} is self-adjoint. Due to lemma 8.3, we have $\mathcal{D}(\mathbf{curl}_{\max}) = \mathcal{D}(\mathbf{S})$ and therefore

$$\mathbf{S} = \mathbf{curl}_{\max} \quad (8.22)$$

since \mathbf{S} and \mathbf{curl}_{\max} are both \mathbf{curl} operators. Clearly, this is not possible since \mathbf{curl}_{\max} is not self-adjoint. \square

Remark 12. We remark that the same arguments apply to the operator $(\mathbf{curl} \mathbf{curl})_{\text{Neu}}$.

8.3. $\mathbf{curl} \mathbf{curl} \neq \mathbf{curl} \mathbf{curl}^*$ is possible. Finally, we would like to show that not all the self-adjoint $\mathbf{curl} \mathbf{curl}$ operators are of the form $\mathbf{R} \mathbf{R}^*$ with \mathbf{R} a \mathbf{curl} operator.

Following an idea of Everitt and Markus—a similar construction or the Laplacian is introduced in [16]—we consider the self-adjoint $\mathbf{curl} \mathbf{curl}$ operator

$$\mathbb{T}^0 : \mathcal{D}(\mathbb{T}^0) \subset \mathbf{L}^2(D) \mapsto \mathbf{L}^2(D), \quad \mathbf{u} \mapsto \mathbf{curl} \mathbf{curl} \mathbf{u} \quad (8.23)$$

with domain

$$\mathcal{D}(\mathbb{T}^0) = \mathcal{D}_{\min} \oplus \mathcal{D}_2, \quad (8.24)$$

where \mathcal{D}_{\min} and \mathcal{D}_2 are defined in (8.1) and (8.4).

PROPOSITION 8.5. *There exists no \mathbf{curl} operator \mathbf{R} such that*

$$\mathbb{T}^0 = \mathbf{R} \mathbf{R}^*. \quad (8.25)$$

Proof. Suppose that there exists a \mathbf{curl} operator \mathbf{R} satisfying (8.25). By definition of the composition of operators one has

$$\mathcal{D}(\mathbb{T}^0) = \left\{ u \in \mathcal{D}(\mathbf{R}^*) : \mathbf{R}u \in \mathcal{D}(\mathbf{R}) \right\}.$$

Hence, this implies

$$\mathcal{D}_2 \subset \mathcal{D}(\mathbb{T}^0) \subset \mathcal{D}(\mathbf{R}^*) \subset W^1(\mathbf{d}, D).$$

This is not possible since \mathcal{D}_2 is not a subspace $W^1(\mathbf{d}, D)$.

This can be illustrated by means of vector proxies and in the case of the unit sphere D . Consider the function

$$\mathbf{u}(r, \theta, z) = \left(\sum_{n=1}^{+\infty} r^n \sin n\theta \right) \mathbf{e}_z,$$

given the cylindrical coordinates. The \mathbf{curl} and $\mathbf{curl} \mathbf{curl}$ of \mathbf{u} are

$$\begin{aligned} \mathbf{curl} \mathbf{u} &= \left(\sum_{n=1}^{+\infty} n r^{n-1} \cos n\theta \right) \mathbf{e}_r - \left(\sum_{n=1}^{+\infty} n r^{n-1} \sin n\theta \right) \mathbf{e}_\theta, \\ \mathbf{curl} \mathbf{curl} \mathbf{u} &= \mathbf{0}. \end{aligned}$$

Direct computation leads to

$$\|\mathbf{u}\|^2 < +\infty \quad \text{and} \quad \|\mathbf{curl} \mathbf{u}\| = +\infty.$$

Hence, this \mathbf{u} satisfies $\mathbf{u} \in \mathcal{D}_2$ but $\mathbf{u} \notin \mathbf{H}(\mathbf{curl}, D)$. \square

Remark 13. In the same way, we show that there exists no \mathbf{curl} operators \mathbf{R}_1 and \mathbf{R}_2 satisfying

$$\mathbf{T}^0 = \mathbf{R}_1 \mathbf{R}_2 . \quad (8.26)$$

Appendix. Frequently used notations:

D	bounded (open) Lipschitz domain in affine space \mathbb{R}^3
D'	(compactified) complement $D' := \mathbb{R}^3 \setminus \bar{D}$
∂D	boundary of D
\mathbf{n}	exterior unit normal vector field on ∂D
$\mathbf{u}, \mathbf{v}, \dots$	vector fields on a three-dimensional domain
ω, η, \dots	differential forms
\mathbf{v}, \mathbf{u}	elements of a factor space/trace space of vector proxies
\cdot	Euclidean inner product in \mathbb{R}^3
\times	cross product of vectors $\in \mathbb{R}^3$
$\mathbf{T}, \mathbf{S}, \dots$	(unbounded) linear operators on a Hilbert space
\mathbf{T}^*	adjoint operator
\mathbf{T}_{min}	The minimal closure of \mathbf{T}
\mathbf{T}_{max}	The maximal closure of \mathbf{T}
$\mathcal{D}(\mathbf{T})$	domain of definition of the linear operator \mathbf{T}
$\mathcal{N}(\mathbf{T})$	kernel (null space) of linear operator \mathbf{T}
$\mathcal{R}(\mathbf{T})$	range space of an operator \mathbf{T}
$C^\infty(D)$	space of infinite differentiable functions on D
$\mathbf{C}^\infty(D)$	space of smooth vector fields $(C^\infty(D))^3$
$C_0^\infty(D)$	functions in $C^\infty(D)$ with compact support in D
$\mathbf{C}_0^\infty(D)$	vector fields in $(C_0^\infty(D))^3$
$L^2(D)$	real Hilbert space of square integrable functions on D
$\mathbf{L}^2(D)$	square integrable vector fields in $(L^2(D))^3$
$\mathbf{H}(\mathbf{curl}, D)$	real Hilbert space $\{\mathbf{v} \in \mathbf{L}^2(D) : \mathbf{curl} \mathbf{v} \in \mathbf{L}^2(D)\}$ with graph norm
$\mathbf{H}_0(\mathbf{curl}, D)$	closure of $\mathbf{C}_0^\infty(D)$ in $\mathbf{H}(\mathbf{curl}, D)$
γ_t	tangential boundary trace of a vector field
γ_n	normal component trace of a vector field
\mathbf{grad}_∂	surface gradient
\mathbf{curl}_∂	scalar valued surface rotation
\mathbf{div}_∂	surface divergence
\mathbf{d}	exterior derivative of differential forms
$\Lambda^k(M)$	differential k -forms on manifold M
\wedge	exterior product of differential forms
\star_g	Hodge operator induced by metric g
$(\cdot, \cdot)_{k,M}$	inner product on $\Lambda^k(M)$ induced by a Hodge operator \star
$L^2(\Lambda^k(M))$	Hilbert space of square integrable k -forms on M
$\ \cdot\ $	norm of $L^2(\Lambda^k(M))$ (" L^2 -norm"): $\ \omega\ ^2 := (\omega, \omega)_{k,M}$
$W^k(\mathbf{d}, D)$	Sobolev space of square integrable k -forms with square integrable exterior derivative
$W_0^k(\mathbf{d}, D)$	completion of compactly supported k -forms in $W^k(\mathbf{d}, D)$
i^*	natural trace operator for differential forms
$[\cdot, \cdot]$	generic symplectic pairing

$[\cdot, \cdot]_M$	symplectic pairing of 1-forms on 2-manifold M
$[\cdot]_\Gamma$	jump of trace of a function across 2-manifold Γ
L^\sharp	symplectic orthogonal of subspace L of a symplectic space
$\langle \cdot \rangle$	(relative) homology class of a cycle
$\mathbb{H}_i(A; R)$	i^{th} homology group of A with coefficients in R
$\mathbb{H}^i(A; R)$	i^{th} co-homology space of A with coefficients in R
$\mathbb{H}_i(A, B; R)$	i^{th} relative homology group of A relative to B with coefficients in R
$\mathbb{H}^i(A, B; R)$	relative co-homology space of A relative to B with coefficients in R
$\mathcal{H}^1(\partial D)$	co-homology space of harmonic 1-forms on ∂D
$\mathbb{H}^1(\partial D)$	first co-homology factor space of non-exact closed 1-forms on ∂D
$\mathbb{H}_1(\partial D)$	first homology factor space of non-bounding cycles on ∂D
$\langle \cdot \rangle$	selects (relative) homology class of a cycle
$W^{-\frac{1}{2}, 1}(\mathbf{d}, \partial D)$	trace space of $W^1(\mathbf{d}, D)$
$\mathbf{H}_t^{-\frac{1}{2}}(\text{curl}_\partial, \partial D)$	tangential traces of vector fields in $\mathbf{H}(\text{curl}, D)$
$Z^{-\frac{1}{2}}(\partial D)$	closed 1-forms in $W^{-\frac{1}{2}, 1}(\mathbf{d}, \partial D)$
ω^0, ω^\perp	components of the Hodge decomposition of $\omega \in W^{-\frac{1}{2}, 1}(\mathbf{d}, \partial D)$

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08-14	M. Torrilhon and H. Struchtrup	Boundary conditions for regularized 13-Moment-Equations for Micro-Channel-Flows
08-13	H. Struchtrup and M. Torrilhon	Modelling micro mass and heat transfer for gases using extended continuum equations