The Matrix gallery(5) of MATLAB

In MATLAB the matrix

		-9	11	-21	63	-252
		70	-69	141	-421	1684
(1)	A = gallery(5) =	-575	575	-1149	3451	-13801
		3891	-3891	7782	-23345	93365
		1024	-1024	2048	-6144	24572

is provided as an "interesting eigenvalue problem". According to a remark in MATLAB's help file the user is invited to "find its *exact* eigenvalues and eigenvectors".

The naive approach fails, since eig(A) yields

$$\lambda_{1} = -0.03371394752607 + 0.02503344949626i$$

$$\lambda_{2} = -0.03371394752607 - 0.02503344949626i$$

$$\lambda_{3} = 0.01337277132340 + 0.03894049608920i$$

$$\lambda_{4} = 0.01337277132340 - 0.03894049608920i$$

$$\lambda_{5} = 0.04068235241305 ,$$

which contradicts $\lambda_1 \lambda_2 \lambda_3 \lambda_4 \lambda_5 = det(A) = 0$. Somewhat more reliable information is obtained from poly(A), which yields approximate coefficients of the characteristic polynomial $p(\lambda)$:

$$(3) \begin{array}{c} 1.000000000000 \\ -0.0000000000770 \\ 0.00000004765977 \\ -0.00000019062667 \\ 0.00000025761397 \\ -0.00000012160528 \end{array}$$

This may lead to the conjecture that $p(\lambda) = \lambda^5$ is the characteristic polynomial of A, which would imply that $\lambda = 0$ is a 5-fold eigenvalue, i.e. $\lambda = 0$ has the algebraic multiplicity 5.

According to the theorem of Cayley-Hamilton every matrix satisfies its characteristic equation, which would mean $A^5 = 0$ if the above conjecture is true. In fact we obtain

$$(4.1) A^{2} = \begin{bmatrix} 11 & -18 & 39 & -116 & 464 \\ -230 & 301 & -598 & 1799 & -7194 \\ 1717 & -2292 & 4585 & -13750 & 54992 \\ -11674 & 15565 & -31130 & 93391 & -373503 \\ -3072 & 4096 & -8192 & 24576 & -98288 \end{bmatrix},$$

$$(4.2) A^{3} = \begin{bmatrix} -4 & 8 & -20 & 64 & -255 \\ 243 & -402 & 879 & -2628 & 10509 \\ -1710 & 2852 & -6278 & 18840 & -75323 \end{bmatrix},$$

$$(4.3) A^4 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ -84 & 168 & -420 & 1344 & -5355 \\ 568 & -1136 & 2840 & -9088 & 36210 \\ -3892 & 7784 & -19460 & 62272 & -248115 \\ -1024 & 2048 & -5120 & 16384 & -65280 \end{bmatrix}$$

and $A^5 = 0$. Since the characteristic polynomial of A has the exact degree 5 the above computations prove that

(5)
$$p(\lambda) = \lambda^5$$

is indeed the characteristic polynomial of A, and therefore $\lambda = 0$ is a 5-fold eigenvalue. The result (3) obtained by MATLAB is not that bad after all; it is in error only in the 7th decimal place. However, in this case the actual eigenvalues are extremely sensitive to round-off errors in the computation.

Next we consider the problem of finding eigenvectors of A. We notice that every eigenvector x of A satisfies the homogeneous linear system

$$Ax = 0, \ x \in \mathbb{R}^5 .$$

For solving (6) and related systems the LU factorization A = LR will be used. The statement [L, R] = lu(A) yields

	[-0.00231	1303006939	1.00000	0		0	0]
		0.01799	0023387304	0.50000	1.00000		0	0
	L =	-0.14777	7692109997	0	0.40000	1.000000	00000000	0
		1.00000	0000000000	0	0		0	0
		0.26317	7142122848	0	0	-0.078431	37254902	1.00000
(7)								
		3891.00	-3891.00	7782.00	-23345.0	000000000	93365.000	[0000000
		0	2.00	-3.00	9.0	023130301	-36.043	39475713
	R =	0	0	2.50	-5.5	5191467489	22.363	37882292
		0	0	0	3.3	5554356207	-12.753	32767926
		0	0	0		0		0

From R we infer rank(A) = 4; therefore there is only one eigenvector, $x^{(1)}$, satisfying $Ax^{(1)} = 0$. Hence the geometric multiplicity of $\lambda = 0$ is 1, and there is only one Jordan block corresponding to $\lambda = 0$.

Instead of the missing eigenvectors there exist 4 linearly independent principal vectors $x^{(k)}$, (k = 2, 3, 4, 5) satisfying the conditions

(8)
$$Ax^{(k)} = x^{(k-1)}, \ (k = 1, ..., 5) \text{ with } x^{(0)} = 0,$$

which, for k = 1, include condition (6) for the eigenvector $x^{(1)}$. The vectors $x^{(k)}$ may be computed by backward substitution, beginning with an arbitrary 5-th component $x_5^{(k)}$. If we partition the matrix R as

(9)
$$R = \begin{bmatrix} R1 & r \\ 0 & 0 \end{bmatrix}$$

where R1=R(1:4,1:4) is a regular 4×4 matrix and r=R(1:4,5) is a 4-vector, Equ. (8) may be solved by the MATLAB statements

$$\mathsf{c} = \mathtt{L} \backslash \mathtt{x}^{(k-1)}, \; \mathtt{x}^{(k)} = [\mathtt{R1} \backslash (\mathtt{c}(\mathtt{1}:\mathtt{4}) - \mathtt{r} \ast \mathtt{x}_5^{(k)}); \; \mathtt{x}_5^{(k)}] \; ,$$

to be executed for k = 1, ..., 5. Here $x_5^{(1)} \neq 0$, and, as a check, c_5 vanishes in every step.

It would be desirable to choose the free parameters $x_5^{(k)}$, (k = 1, ..., 5) such that $x^{(k)}$ are vectors with integer elements, if possible. A brute-force approach is to search through the values $x_5^{(k)} = \pm 1, \pm 2, ...,$ until an integer vector $x^{(k)}$ is found. It turns out that with

(10)
$$x_5^{(1)} = 256, \ x_5^{(2)} = -64, \ x_5^{(3)} = 16, \ x_5^{(4)} = -4, \ x_5^{(5)} = 1$$

integer vectors $x^{(k)}$ are indeed produced, and that the values of $x_5^{(k)}$ that result in integer vectors $x^{(k)}$ are determined only modulo 256. A more subtle approach would involve the theory of linear diophantine equations.

By using the values (10) the sequence of integer vectors $x^{(k)}$ may be generated by the short MATLAB program (12) given below. Due to round-off errors the elements of these vectors will not be exact integers, but have to be rounded to the nearest integer vectors. The integer eigenvector and principal vectors are collected as columns of the transformation matrix T. Since det(T) = 1, the inverse T1 of T is an integer matrix as well which is recovered by T1=round(inv(T)). Since A relates to its Jordan normal form J by

(11)
$$A = T J T^{-1}$$
,

J will finally be explicitly computed as J = T1 * A * T.

$$\begin{array}{l} {\tt A} = \texttt{gallery}(5) \\ [L,R] = \texttt{lu}(A); \ \texttt{R1} = \texttt{R}(1:4,1:4); \ \texttt{r} = \texttt{R}(1:4,5); \ \texttt{x} = \texttt{zeros}(5,1); \ \texttt{T} = [\]; \\ \texttt{for } \texttt{k} = 4:-1:0, \\ (12) \qquad \qquad \texttt{c} = \texttt{L} \backslash \texttt{x}, \ \texttt{x5} = (-4)^\texttt{k}; \ \texttt{x1} = \texttt{R1} \backslash (\texttt{c}(1:4) - \texttt{x5} * \texttt{r}); \\ \texttt{x} = [\texttt{round}(\texttt{x1}); \texttt{x5}]; \ \texttt{T} = [\texttt{T},\texttt{x}]; \\ \texttt{end}; \\ \texttt{T}, \ \texttt{T1} = \texttt{round}(\texttt{inv}(\texttt{T})), \ \texttt{J} = \texttt{T1} * \texttt{A} * \texttt{T} \end{array}$$

The results computed in the last line of the program (12) are

(13.1)
$$T = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 21 & -3 & 2 & 0 & 0 \\ -142 & 37 & -8 & 3 & 0 \\ 973 & -243 & 61 & -15 & 4 \\ 256 & -64 & 16 & -4 & 1 \end{bmatrix},$$

(13.2)
$$T1 = \begin{bmatrix} 1 & -1 & 2 & -6 & 24 \\ 1 & 0 & 0 & 0 & 0 \\ -9 & 11 & -21 & 63 & -252 \\ 11 & -18 & 39 & -116 & 464 \\ -4 & 8 & -20 & 64 & -255 \end{bmatrix}.$$

(13.3)
$$J = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

To find more, possibly all, integer transformation matrices S with the property

(14)
$$A = S J S^{-1}$$

assume

$$(15) S = T Q$$

where Q and Q^{-1} are 5 × 5 matrices with integer elements. Equs. (14), (15) together with (11) yield the condition

(16)
$$J = Q J Q^{-1} \quad \text{or} \quad J Q = Q J ,$$

i.e. Q must commute with J. This is achieved by writing Q as a power series in J which, due to $J^5 = 0$, truncates after 5 terms:

(17)
$$Q = q_0 I + q_1 J + q_2 J^2 + q_3 J^3 + q_4 J^4.$$

If $q_0 = \pm 1$ and q_1, q_2, q_3, q_4 are integers, the reciprocal series has integer coefficients as well, and both matrices Q and Q^{-1} have integer elements.

The symbolic-algebra package MAPLE contains a procedure jordan which is able to directly generate the Jordan normal form of A. The statement J:= jordan(A, S1') yields J of Equ. (13.3) and

(18)
$$\mathbf{S1} = S^{-1} = \begin{bmatrix} 0 & -1 & 7 & -36 & 144171/1024 \\ 0 & -1 & 6 & -28 & 28117/256 \\ 0 & -1 & 5 & -21 & 5291/64 \\ 0 & -1 & 4 & -15 & 949/16 \\ 1 & -2 & 5 & -16 & 255/4 \end{bmatrix},$$

a rational inverse transformation matrix corresponding to

(19)
$$Q = \begin{bmatrix} -4 & 11 & -9 & 1 & 1 \\ 0 & -4 & 11 & -9 & 1 \\ 0 & 0 & -4 & 11 & -9 \\ 0 & 0 & 0 & -4 & 11 \\ 0 & 0 & 0 & 0 & -4 \end{bmatrix},$$

i.e. $q_0 = -4$, $q_1 = 11$, $q_2 = -9$, $q_3 = 1$, $q_4 = 1$.

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