

Numerical solution of matrix eigenvalue problems

Part 1: Power method and friends

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Outline

- ▶ power method
- ▶ subspace iteration
- ▶ inverse iteration
- ▶ Rayleigh-quotient iteration

The power method

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Input: start vector  $v_0 \in \{\mathbb{R}, \mathbb{C}\}^n$ , matrix  $A \in \{\mathbb{R}, \mathbb{C}\}^{n \times n}$ .  
for  $i = 0, 1, 2, \dots$  do  
     $v_{i+1} = Av_i$   
end for
```

Let $\lambda_1, \dots, \lambda_n$ be eigenvalues of A s.t.

$$|\lambda_1| > |\lambda_2| \geq \dots \geq |\lambda_n|$$

with corresponding eigenvectors x_1, x_2, \dots, x_n .

Power method **converges to**
 x_1 :

$$\theta(x_1, v_i) = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^i\right)$$

Angle between vectors $v, w \in \mathbb{C}^n$:

$$\cos \theta(v, w) = \frac{|w^H v|}{\|v\|_2 \|w\|_2}$$

The power method

Input: **start vector** $v_0 \in \{\mathbb{R}, \mathbb{C}\}^n$, **matrix** $A \in \{\mathbb{R}, \mathbb{C}\}^{n \times n}$.

Output: Approximation v_i to **dominant eigenvector**.

for $i = 0, 1, 2, \dots$ **do**

$$\tilde{v}_{i+1} = Av_i$$

$$v_{i+1} = \tilde{v}_{i+1} / \|\tilde{v}_{i+1}\|_2$$

end for

To get an approximation to λ_1 , choose μ_i s.t.

$$\|Av_i - \mu_i v_i\|_2 \rightarrow \min$$

\rightsquigarrow **Rayleigh quotient** $\mu_i := v_i^H Av_i = v_i^H \tilde{v}_{i+1}$.

$$|\mu_i - \lambda_1| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^i\right).$$

For **symmetric** A :

$$|\mu_i - \lambda_1| \leq |\lambda_n - \lambda_1| \sin^2 \theta(x_1, v_0) \left|\frac{\lambda_2}{\lambda_1}\right|^{2k}.$$

The power method

Termination? Is $|\mu_{i+1} - \mu_i| \approx 0$ a suitable criterion?

- ▶ For symmetric/normal matrices, **yes**:

$$|\mu_{i+1} - \mu_i| \leq \text{tol} \quad \Rightarrow \quad |\mu_k - \lambda| \leq \frac{1}{1 - |\lambda_2/\lambda_1|} \text{tol}.$$

- ▶ For nonnormal matrices, **no**. Transient growth! Show transient.m

Only reasonable choice: $r := Av_i - \mu_i v_i \approx 0$.

Backward error interpretation: (μ_i, v_i) *exact* eigenvalue/eigenvector pair of *perturbed* matrix

$$A + \Delta A, \quad \Delta A := -r v_i^H.$$

With this choice, $\|\Delta A\|_2 = \|r\|_2$.

Snippets of perturbation analysis

First-order influence of ΔA on accuracy of eigenvalues/eigenvectors:

$$Ax = \lambda x, \quad \|x\|_2 = 1.$$

↓

$$(A + \epsilon \Delta A)x(\epsilon) = \lambda(\epsilon)x(\epsilon), \quad \|x(\epsilon)\|_2 = 1.$$

↓

$$\dot{\lambda}(0) = \frac{y^H \Delta A x}{y^H x},$$

where $y^H A = \lambda y^H$.

Accuracy of eigenvalues/eigenvectors

In **general**:

$$|\mu_i - \lambda_1| \leq \frac{1}{|y_1^H x_1|} \|\Delta A\|_2 + O(\|\Delta A\|_2^2)$$

and

$$\theta(v_i, \theta_1) \leq \|[(I - x_1 x_1^H)(A - \lambda_1 I)(I - x_1 x_1^H)]^\dagger\|_2 \|\Delta A\|_2 + O(\|\Delta A\|_2^2).$$

If A is **symmetric**:

$$|\mu_i - \lambda_1| \leq \|\Delta A\|_2.$$

and

$$\sin \theta(x_1, v_i) = \frac{1}{|\mu_i - \lambda_2|} \|\Delta A\|_2.$$

A posteriori estimates

- ▶ If A is **nonsymmetric**, apply power method to A and A^H . Obtain approximations v_i and w_i to right/left eigenvectors x_1, y_1 . Then

$$|\mu_i - \lambda_1| \approx \frac{1}{|w_i^H v_i|} \max\{\|Av_i - \mu_i v_i\|_2, \|w_i^H A - \mu_i w_i^H\|_2\}.$$

- ▶ If A is **symmetric**,

$$|\mu_i - \lambda_i| \leq \|r\|_2, \quad \sin \theta(x_1, v_i) = \frac{1}{|\mu_i - \lambda_2|} \|r\|_2.$$

- ▶ Alternative for symmetric A : **Kato-Temple inequality**. Assume \exists interval (a, b) containing μ_i, λ_1 and **no other eigenvalue** of A . Then

$$-\frac{\|r\|_2^2}{\mu_i - a} \leq \mu_i - \lambda_i \leq \frac{\|r\|_2^2}{b - \mu_i}.$$

Subspace iteration

Natural generalization of power method from vectors to subspaces:

Input: **Start matrix** $V_0 \in \{\mathbb{R}, \mathbb{C}\}^{n \times k}$, **matrix** $A \in \{\mathbb{R}, \mathbb{C}\}^{n \times n}$.

for $i = 0, 1, 2, \dots$ **do**

$$\tilde{V}_{i+1} = AV_i$$

Compute QR decomposition $\tilde{V}_{i+1} = V_{i+1}R_{i+1}$.

end for

Convergence: Consider two groups of eigenvalues

$$|\lambda_1| \geq \dots \geq |\lambda_k| > |\lambda_{k+1}| \geq \dots \geq |\lambda_n|$$

with corresponding invariant subspaces $\mathcal{X}_1, \mathcal{X}_2$.

If $\theta(\mathcal{X}_1, \mathcal{V}_0) < \pi/2$, then

$$\theta(\mathcal{X}_1, \mathcal{V}_i) = O\left(\left|\frac{\lambda_{k+1}}{\lambda_k}\right|^i\right)$$

Angles between subspaces:

$$\sin \theta(\mathcal{V}, \mathcal{W}) := \min_{\substack{v \in \mathcal{V} \\ \|v\|_2=1}} \min_{w \in \mathcal{W}} \|v - w\|_2.$$

Given ONBs V, W of \mathcal{V}, \mathcal{W} :

$$\cos \theta(\mathcal{V}, \mathcal{W}) = \|W^H V\|_2.$$

Subspace iteration

Eigenvalue/eigenvector extraction from **Galerkin condition**

$$Av - \mu v \perp \mathcal{V}_i, \quad v \in \mathcal{V}_i.$$

This implies

- ▶ μ is an eigenvalue of the $k \times k$ matrix $V_i^H A V_i$ (**compression** of A);
 - ▶ $v = V_i w$ with $w, \|w\|_2 = 1$, eigenvector of $V_i^H A V_i$ belonging to μ .
- μ, v are called **Ritz value/Ritz vector**.

In the i th iteration, there are k such Ritz pairs

$$(\mu_i^{(1)}, v_i^{(1)}), (\mu_i^{(2)}, v_i^{(2)}), \dots, (\mu_i^{(k)}, v_i^{(k)}).$$

The space $\mathcal{V}_i = \text{span}\{v_i^{(1)}, \dots, v_i^{(k)}\}$ converges **as a whole** with rate $|\lambda_{k+1}/\lambda_k|$. However, some $v_i^{(j)}$ may converge significantly faster than others. Show ssiter.m.

Let A be **symmetric** and order eigenvalues

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n.$$

Minimax theorems:

$$\begin{aligned}\lambda_j &= \max_{\dim(\mathcal{V})=j} \min_{\substack{v \in \mathcal{V} \\ \|v\|_2=1}} v^T A v, \\ \lambda_{n-j+1} &= \min_{\dim(\mathcal{V})=j} \max_{\substack{v \in \mathcal{V} \\ \|v\|_2=1}} v^T A v.\end{aligned}$$

As a consequence, Ritz values **interlace** eigenvalues of A :

$$\lambda_j \geq \mu^{(j)} \geq \lambda_{n-j+1},$$

\rightsquigarrow Ritz values approach eigenvalues from below.

Inverse iteration

Eigenvalue closest to $\tau \in \mathbb{C}$ is dominant eigenvalue of

$$(A - \tau I)^{-1}.$$

Input: **start vector** v_0 , **matrix** A , **target** $\tau \in \mathbb{C}$.

Output: Approximation (μ_i, v_i) to eigenpair closest to τ .

for $i = 0, 1, 2, \dots$ **do**

 Solve $(A - \tau I)\tilde{v}_{i+1} = v_i$

$v_{i+1} = \tilde{v}_{i+1} / \|\tilde{v}_{i+1}\|_2$

$\mu_{i+1} = (\tilde{v}_{i+1}^H v_{i+1})^{-1} + \tau$

end for

Not suited for inexact application of $(A - \tau I)^{-1}$!

Inverse iteration

Order eigenvalues

$$|\lambda_1 - \tau| \geq \dots \geq |\lambda_{n-1} - \tau| > |\lambda_n - \tau|.$$

Convergence to $(\lambda_n, \mathbf{x}_n)$:

$$|\mu_i - \lambda_n| = \mathcal{O}\left(\left|\frac{\lambda_n - \tau}{\lambda_{n-1} - \tau}\right|^i\right)$$

$$\theta(\mathbf{x}_n, \mathbf{v}_i) = \mathcal{O}\left(\left|\frac{\lambda_n - \tau}{\lambda_{n-1} - \tau}\right|^i\right)$$

Rayleigh-quotient iteration

Tempting idea: Improve convergence by adjusting τ .

Input: **start vector** v_0 with $\|v_0\|_2 = 1$, **matrix** A .

Output: Approximation (μ_i, v_i) to **some** eigenpair.

for $i = 0, 1, 2, \dots$ **do**

 Set $\tau = v_i^H A v_i$.

 Solve $(A - \tau I) \tilde{v}_{i+1} = v_i$

$v_{i+1} = \tilde{v}_{i+1} / \|\tilde{v}_{i+1}\|_2$

$\mu_{i+1} = v_{i+1}^H A v_{i+1}$

end for

Local convergence quadratic or even cubic (when A normal).

Global convergence critical!

Start rqiglobal.m

Grassmann Rayleigh-quotient iteration

Natural generalization to subspaces.

Input: start ONB V_0 , symmetric matrix A .

Output: Approximate ONB V_i to some invariant subspace.

for $i = 0, 1, 2, \dots$ **do**

Set $T = V_i^H A V_i$.

Solve Sylvester equation $A \tilde{V}_{i+1} - \tilde{V}_{i+1} T = V_i$.

Compute ONB V_{i+1} of \tilde{V}_{i+1} .

end for

Local convergence cubic. Advantageous over RQI, when several eigenvalues are needed:

- ▶ Avoid repeated convergence to same eigenvalues.
- ▶ In the limit, effective conditioning of $X \mapsto AX - XT$ only depends on external gap.
- ▶ Domain of attraction primarily depends on external gap.

Literature

- ▶ Virtually every book on numerical linear algebra covers the power method. The subspace iteration is covered, e.g., in [G. H. Golub and C. F. Van Loan. *Matrix Computations*. 1996], [G. W. Stewart. *Matrix Algorithms*. Vol. II. 2001].
- ▶ An implementation of the subspace iteration can be found in [Z. Bai and G. W. Stewart. Algorithm 776. SRRIT – A FORTRAN subroutine to calculate the dominant invariant subspaces of a nonsymmetric matrix. *ACM TOMS*, 23:494–513, 1998].
- ▶ The standard reference on the perturbation of *nonsymmetric* eigenvalue problems is [G. W. Stewart and J.-G. Sun. *Matrix Perturbation Theory*. Academic Press, New York, 1990].
- ▶ An overview of available relative perturbation bounds for *symmetric* eigenvalue problems is given in [I. C. F. Ipsen. Relative Perturbation Bounds for Matrix Eigenvalues and Singular Values. *Acta Numerica*, pp 151–201, (1998)].
- ▶ The Grassmann RQI and related methods are described in the recent monograph [P.-A. Absil, R. Mahony, R. Sepulchre. *Optimization Algorithms on Matrix Manifolds*. Princeton University Press, 2008].