

Review

FE space for

0-forms $\hat{=} W^0(M) = \text{span} \{ b_\alpha \}$
 $\alpha \in \mathcal{F}_0(M)$

$b_\alpha|_T = \lambda_i$ if $a_i = \alpha$ (for tetrahedral mesh)
 def. $u \rightarrow u(\alpha)$

1-forms $\hat{=} W^1(M) = \text{span} \{ b_e \}$
 $e \in \mathcal{F}_1(M)$

$b_e|_T = \lambda_i \alpha_j - \lambda_j \alpha_i$ if $e = [a_i, a_j]$ def.
 $u \rightarrow \int_e u ds$

2-forms $\hat{=} W^2(M) = \text{span} \{ b_f \}$
 $f \in \mathcal{F}_2(M)$

$b_f|_T = 2(\lambda_i \alpha_j \times \lambda_k \alpha_l + \lambda_j \alpha_k \times \lambda_l \alpha_i + \lambda_k \alpha_l \times \lambda_i \alpha_j)$

if $f = [a_i, a_j, a_k]$

def.
 $u \rightarrow \int_f u \cdot nds$

3-forms $\hat{=} W^3(M) = \text{span} \{ b_T \}$
 $T \in \mathcal{F}_3(M)$

$b_T|_T = \frac{1}{|T|}$

$u \rightarrow \int_T u dx$

Chap 3. Stationary electromagnetics

3.1 Stationary field eqns

$\begin{cases} \text{curl } \underline{e} = -\partial_t \underline{b} \\ \text{curl } \underline{h} = \partial_t \underline{d} + \underline{j} \\ \text{div } \underline{b} = 0 \\ \text{div } \underline{d} = f \Rightarrow -\partial_t f = \text{div } \underline{j} \end{cases}$	Stationary case $\partial_t \neq 0 \Rightarrow$	$\begin{cases} \text{curl } \underline{e} = 0 \\ \text{curl } \underline{h} = \underline{j} \end{cases}$	(div $\underline{j} = 0$) compatibility cond.
	\Rightarrow	$\begin{cases} \text{div } \underline{b} = 0 \\ \text{div } \underline{d} = f \end{cases}$	\Rightarrow

Observation: decoupling of electric & magnetic fields

— $\hat{=} \text{electric eqns}$

— $\hat{=} \text{magnetic eqns}$

3.2 Electrostatics

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3.2.1. V -based variational formulation

• $\text{curl } \underline{e} = 0$ on $A_3 \Rightarrow \underline{e} = -\text{grad } v$

• material law (energy oriented form)

$$\langle D\mathcal{E}_{el}(\underline{e}), \underline{e}' \rangle = \int_{\Omega} \underline{d} \cdot \underline{e}' \, dx \quad \forall \underline{e}' \in \mathcal{F}(\Omega)$$

\uparrow
not A_3

• $\text{div } \underline{d} = \rho$ weakly

$$\begin{aligned} \int_{\Omega} \text{div } \underline{d} \, v &= - \int_{\Omega} \underline{d} \cdot \text{grad } v' + \int_{\partial\Omega} \underline{d} \cdot \underline{n} \, v' \, dS \\ &= - \langle D\mathcal{E}_{el}(\underline{e}), \text{grad } v' \rangle + \int_{\partial\Omega} \underline{d} \cdot \underline{n} \, v' \, dS \\ &= \int_{\Omega} \rho v' \, dx \quad \forall v' \in \mathcal{F}^0(\Omega) \end{aligned}$$

$$\Delta \langle D\mathcal{E}_{el}(-\text{grad } v), -\text{grad } v' \rangle + \int_{\partial\Omega} \underline{d} \cdot \underline{n} \, v' \, dS = \int_{\Omega} \rho v' \, dx \quad (3.2.a)$$

For ~~local~~ linear material law:

$$\boxed{\int_{\Omega} \underline{\varepsilon} \text{grad } v \cdot \text{grad } v' + \int_{\partial\Omega} \underline{d} \cdot \underline{n} \, v' \, dS = \int_{\Omega} \rho v' \, dx} \quad (3.2.b)$$

B.C. for electrostatics:

PEC $\underline{e} \times \underline{n} = 0$ on $\partial\Omega \Rightarrow v = 0$ on $\partial\Omega$

Strong B.C. imposed on trial and test functions

$$v|_{\partial\Omega} = 0 \quad v'|_{\partial\Omega} = 0$$

surface charge: $\underline{d} \cdot \underline{n} = \rho_{\partial\Omega}$ weakly enforced.

(3.2.b) \Rightarrow linear variational problem

$$u \in V \quad a(u, v) = f(v) \quad \forall v \in V \quad (3.2.c)$$

$a(\cdot, \cdot)$ symmetric, coercive, continuous bilinear form

$f(\cdot)$ continuous linear form

$$a(u, v) = \int_{\Omega} \underline{\varepsilon} \text{grad } u \cdot \text{grad } v$$

Try $V = C^{\infty}(\bar{\Omega})$ or $(C_0^{\infty}(\bar{\Omega}))$ for PEC case

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Lemma 3.2. A. (Poincaré-Friedrichs inequality)

$$\|u\|_{L^2(\Omega)} \leq C(\Omega) \|\text{grad} u\|_{L^2(\Omega)} \quad u \in C_0^{\infty}(\bar{\Omega})$$

$$\|u\|_{L^2(\Omega)} \leq C(\Omega) \|\text{grad} u\|_{L^2(\Omega)} \quad u \in C^{\infty}(\bar{\Omega}) \int_{\Omega} u \, dx = 0$$

Proof (if Ω is convex)

$\|v\|_A = \sqrt{a(v,v)}$ is a norm of

• Construction of solutions to (3.2.6) $C_*^{\infty}(\bar{\Omega}) = \{v \in C^{\infty}(\bar{\Omega}) \mid \int_{\Omega} v = 0\}$

• $f \in L^2(\Omega) \Rightarrow v \mapsto \int_{\Omega} f v \, dx$ is linear conti. on V

• $\text{Kern}(f) = \{v \in V \mid f(v) = 0\} \neq V$ for $f \neq 0 \Rightarrow \text{Kern}(f) \neq \{0\}$

$\rightarrow \exists w \neq 0, w \in \text{Kern}(f)^{\perp}$

does not exist for inner product space

$$f(\underbrace{f(v)w - f(w)v}_{\in \text{Kern}(f)}) = 0 \quad \forall v \in W$$

$$\Delta a(w, f(v)w - f(w)v) = 0$$

$$\Delta \text{By linearity} \quad a\left(\frac{w f(v)}{\|w\|_A^2}, v\right) = f(v) \quad \forall v \in V$$

← Riesz representation theorem

"we find the unique solution"

Example: $u(x,y) = \sin(x) \sin(y)$ solves

$$-\Delta u = u \quad \text{on } \Omega = [0, \pi]^2, \quad u=0 \text{ on } \partial\Omega$$

$$\Rightarrow \int_{\Omega} \text{grad} u \cdot \text{grad} v \, dx = \int_{\Omega} u v \, dx \quad \forall v \in C_0^{\infty}(\bar{\Omega})$$

But $u(x,y) \notin C_0^{\infty}(\bar{\Omega})$

We need $(C_*^{\infty}(\bar{\Omega}), \|\cdot\|_A)$ to be complete by completion.

$$C_*^{\infty}(\bar{\Omega}) \longrightarrow H_*^1(\Omega) \quad C_0^{\infty}(\bar{\Omega}) \longrightarrow H_0^1(\Omega)$$

put the proof in the setting of Sobolev spaces

Thm 3.2.c (3.2.b) has a unique solution $u \in \begin{cases} H^1(\Omega) & \text{for zero charge B.C.} \\ H_0^1(\Omega) & \text{for PEC} \end{cases}$

RK: (1) $C^\infty(\bar{\Omega})$ is dense in $H^1(\Omega)$

Assertion of Sobolev function \Rightarrow reduces to relations of norms

Procedure: \circ prove first for continuous case

\circ Take limit by density

$$(2) H^1(\Omega) = \{ u \in L^2(\Omega) \mid \text{grad } u \in L^2(\Omega) \}$$

• For nonlocal nonlinear material law

(3.2.a) reduces to: Seek $u \in H_0^1(\Omega)$

$$\langle D E_{el}(-\text{grad } v), -\text{grad } v' \rangle = \int_{\Omega} \varphi v' dx \quad \forall v' \in H_0^1(\Omega) \quad (3.2.f)$$

L Recall: $E_{el}: L^2(\Omega) \rightarrow \mathbb{R}$

$D E_{el}: L^2(\Omega) \rightarrow (L^2(\Omega))'$ space of linear functionals on $(L^2(\Omega))$
continuous

Define $\hat{E}_{el}(v) = E_{el}(-\text{grad } v)$

$$D \hat{E}_{el}(v) = D E_{el}(-\text{grad } v)$$

$$\langle D \hat{E}_{el}(v), v' \rangle = \langle D E_{el}(-\text{grad } v), -\text{grad } v' \rangle$$

$$\in (H_0^1(\Omega))' = H^1(\Omega)$$

Abstract chain rule:

$$f: X \rightarrow Y \quad g: Z \rightarrow X$$

$$h = f \circ g \quad \text{chain rule}$$

$$\langle D h(z), y \rangle = \langle D(f \circ g)(z), D g(z) y \rangle$$

Assume E_{el} smooth finite

- bounded $D^2 E_{el}(\underline{e})(\underline{e}', \underline{e}'') \leq T \|\underline{e}'\| \cdot \|\underline{e}''\|$ (3.2.d)
 $\forall \underline{e}', \underline{e}'', \underline{e}^*$ with const $T > 0$
 $= \alpha(\cdot, \cdot)$ for linear material law

- coercive $D^2 E_{el}(\underline{e})(\underline{e}', \underline{e}') \geq \gamma \|\underline{e}'\|^2$ (3.2.e)
 $\forall \underline{e}, \underline{e}'$ with $\gamma > 0$

\triangleright well-posed of nonlinear problem:

1. Let $T: H^1(\Omega) \rightarrow H^1(\Omega)$ be defined by

$$a(Tf, v) = f(v) \quad \forall v \in H^1(\Omega)$$

for $a(u, v) = \int_{\Omega} \gamma \operatorname{grad} u \cdot \operatorname{grad} v \, dx$ $\|\cdot\|_A = \sqrt{a(\cdot, \cdot)}$

T is a solution operator (bijective)

$$\|Tf\|_A^2 = f(Tf) \leq \|f\|_{H^1(\Omega)} \|Tf\|_A \Rightarrow \|T\| = 1$$

$\left(\frac{1}{A} \sup_{w \in H^1(\Omega)} \frac{|f(w)|}{\|w\|_A} \right)$

Steepest Descent Iteration:
Newton Method
Fixed Point Iteration
Newton

$$v^{(k+1)} = v^{(k)} - \alpha T(g - \underbrace{D\hat{E}_{el}(v^{(k)})}_{H^{-1}})$$

(3.2.g) $\alpha > 0$

$$g(v) = \int_{\Omega} f v \, dx$$

• Suppose $v^{(k)} \rightarrow v^*$ then $v^* = v^* - \alpha T(g - D\hat{E}_{el}(v^*))$

$$\Leftrightarrow D\hat{E}(v^*) = g \quad \text{in } H^1(\Omega)$$

$$\Leftrightarrow \langle D\hat{E}(v^*), v^i \rangle = \langle g, v^i \rangle \quad \text{for } v^i \in H^1(\Omega)$$

To show existence & uniqueness of limits of (3.2.g)

$$v^{(k+1)} = \phi(v^{(k)}) \quad \phi(v) = v - \alpha T(g -$$

$$\|\phi(u) - \phi(v)\|_A^2 = \|u - v + \alpha T(\widehat{D\tilde{E}_{el}}(u) - \widehat{D\tilde{E}_{el}}(v))\|_A^2 \quad (55)$$

$$= \|u - v\|_A^2 + 2\alpha \underbrace{\langle \widehat{D\tilde{E}_{el}}(u) - \widehat{D\tilde{E}_{el}}(v), u - v \rangle}_{II} + \alpha^2 \underbrace{\|\widehat{D\tilde{E}_{el}}(u) - \widehat{D\tilde{E}_{el}}(v)\|_A^2}_{III}$$

$$\leftarrow \begin{array}{l} \text{mean value theorem} \\ \langle \widehat{D\tilde{E}_{el}}(u) - \widehat{D\tilde{E}_{el}}(v), u - v \rangle = \int_0^1 \widehat{D\tilde{E}_{el}}(v + t(u-v))(u-v, u-v) dt \end{array}$$

$$II \geq \gamma \|\text{grad}(u-v)\|_{L^2}^2 = \|u-v\|_A^2 \quad \text{by (3.2.e)}$$

$$III \leq \frac{\Gamma}{\gamma} \|u-v\|_A^2 \quad \text{by (3.2.d)}$$

$$\|\phi(u) - \phi(v)\|_A^2 \leq \|u-v\|_A^2 + 2\alpha \|u-v\|_A^2 + \alpha^2 \frac{\Gamma}{\gamma} \|u-v\|_A^2 \quad (\alpha < 0)$$

$$= \underbrace{(1 + 2\alpha + \alpha^2 \frac{\Gamma}{\gamma})}_{\varphi} \|u-v\|_A^2$$

choose $\alpha \rightarrow 0$ s.t. $\varphi < 1$

By contraction mapping principle $\Rightarrow \exists! u^*$
 "Banach fixed point theorem"

3.2.2 d-based variational formulation

- $\text{div } \underline{d} = f$ strongly
- $\underline{e} = -\text{grad } v$ weakly

$$\int_{\Omega} v \text{div } \underline{d}' - \int_{\partial\Omega} v \underline{d}' \cdot \underline{n} \, dS = \int_{\Omega} \underline{e} \cdot \underline{d}' \, dx$$

material law $\langle D\epsilon_{el}(\underline{d}), \underline{d}' \rangle = \int_{\Omega} \underline{e} \cdot \underline{d}' \, dx$

$$\triangleright \begin{cases} \langle D\epsilon_{el}(\underline{d}), \underline{d}' \rangle - \int_{\Omega} v \text{div } \underline{d}' \, dx = - \int_{\partial\Omega} v \underline{d}' \cdot \underline{n} \, dS & (3.2.6) \\ - \int_{\Omega} \text{div } \underline{d} \, v' \, dx = - \int_{\Omega} f v' \, dx & \forall v' \in H^1_0(\Omega) \end{cases}$$

for local linear

$$\begin{cases} \int_{\Omega} \underline{\epsilon}^{-1} \underline{d} \cdot \underline{d}' - \int_{\Omega} \text{div } \underline{d}' \, v \, dx = - \int_{\partial\Omega} v \underline{d}' \cdot \underline{n} \, dS & \forall \underline{d}' \in H^1(\Omega) & (3.2.7) \\ - \int_{\Omega} \text{div } \underline{d} \, v' \, dx = - \int_{\Omega} f v' \, dx & \forall v' \in H^1_0(\Omega) \end{cases}$$

$\hat{=}$ linear variational problem in saddle point form.

Abstract setting

$$\begin{cases} a(\underline{d}, \underline{d}') + b(\underline{d}', v) = f(\underline{d}') & \forall \underline{d}' \in V \\ b(\underline{d}, v') = f(v') & \forall v' \in Q \end{cases} \quad (3.2.7')$$

• Hilbert space framework for (3.2.7)

- find norms s.t. $a(\cdot, \cdot)$, $b(\cdot, \cdot)$ are continuous
- find weak norms to guarantee ellipticity.

$$V = H(\text{div}, \Omega), \quad Q = L^2(\Omega)$$

By PEC B.C. require $\oint_{\partial\Omega} v \underline{d} \cdot \underline{n} \, dS = 0$

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zero surface charge condition $\underline{d} \cdot \underline{n} = 0$ (strongly enforced.)

$V = H_0(\text{div}, \Omega)$ to treat B.C.

• Well-posedness of abstract saddle point problem.

Heuristic (3.2.i) \sim block matrix $\begin{pmatrix} A & B^T \\ B & \end{pmatrix} \begin{pmatrix} \underline{d}' \\ \underline{v}' \end{pmatrix} = \begin{pmatrix} \underline{f} \\ \underline{F} \end{pmatrix}$

$\text{Kern}(B) = \{ \underline{d} \in V : b(\underline{d}, \underline{v}') = 0 \ \forall \underline{v}' \in Q \} \subset \text{closed subspace of } Q$

Orthogonal decomposition: $V = \text{Kern}(B) \oplus_V (\text{Kern}(B))^\perp$

Then (3.2.i) \Rightarrow : Seek $\underline{d}'_0 \in \text{Kern}(B)$, $\underline{d}'_1 \in (\text{Kern}(B))^\perp$, $\underline{v}' \in Q$

Test $\underline{d}'_0 \in \text{Kern}(B)$

$$\begin{cases} a(\underline{d}'_0, \underline{d}'_0) + a(\underline{d}'_0, \underline{d}'_1) = g(\underline{d}'_0) & \underline{d}'_0 \in \text{Kern}(B) \\ a(\underline{d}'_0, \underline{d}'_1) + a(\underline{d}'_1, \underline{d}'_1) + b(\underline{d}'_1, \underline{v}') = g(\underline{d}'_1) & \underline{d}'_1 \in (\text{Kern}(B))^\perp \\ b(\underline{d}'_1, \underline{v}') = f(\underline{v}') & \forall \underline{v}' \in Q \end{cases}$$

Solve $\underline{d}'_1 \rightarrow \underline{d}'_0 \rightarrow \underline{v}$

For (3.2.i) & PEC

① find $\underline{d}'_1 \in H(\text{div}, \Omega)$ $\text{div} \underline{d}'_1 = \underline{f}$ (this \underline{d}'_1 has \underline{d}'_1 and \underline{v}' part from $\text{Kern}(B)$ but it does not blow up.)
 Let $\underline{d}'_1 = \text{grad} \phi \Rightarrow \begin{cases} \Delta \phi = \underline{f} & \text{in } \Omega \\ \phi = 0 & \text{on } \partial\Omega \end{cases}$

$\Rightarrow \|\underline{d}'_1\|_{L^2} \leq \|\underline{f}\|_{L^2(\Omega)} \hookrightarrow \text{convex } \Omega$

② Seek $\underline{d}'_0 \in \text{Kern}(B) = H(\text{div} 0, \Omega) = \{ \underline{v} \in H(\text{div}, \Omega) : \text{div} \underline{v} = 0 \}$

$$\int_{\Omega} \underline{\underline{\varepsilon}}^{-1} \underline{d}_0 \cdot \underline{d}'_0 dx = - \int_{\Omega} \underline{\underline{\varepsilon}}^{-1} \underline{d}'_1 \cdot \underline{d}'_0 dx \quad \forall \underline{d}'_0 \in H(\text{div}, \Omega) \quad (5.8)$$

$$\textcircled{2} \triangleright \|\underline{d}_0\|_{L^2} \lesssim C(\underline{\underline{\varepsilon}}) \|\underline{d}_1\|_{L^2(\Omega)}$$

$$\textcircled{3} \text{ Find } v \in L^2(\Omega) \text{ s.t.}$$

$$\int_{\Omega} \underline{\underline{\varepsilon}}^{-1} (\underline{d}_0 + \underline{d}_1) \cdot \underline{d}'_1 dx + \int_{\Omega} \text{div} \underline{d}'_1 v dx = 0 \quad \forall \underline{d}'_1 \in \ker(B)^{\perp}$$

from ② we get a map $L: L^2(\Omega) \rightarrow H(\text{div}, \Omega)$ and $\text{div} \circ L = \text{id}$ $\begin{matrix} \ker(\text{div})^{\perp} \\ \text{and } (4.4.1) \end{matrix}$

$$\text{Set } \underline{d}'_1 = Lv$$

$$\triangleright \int_{\Omega} \underline{\underline{\varepsilon}}^{-1} (\underline{d}_0 + \underline{d}_1) \cdot Lv dx + \int_{\Omega} v \text{div} v dx = 0$$

$$\Rightarrow \underline{d} = \underline{d}_0 + \underline{d}_1 \text{ and } v \text{ solve (3.2.i)}$$

$$H(\text{div}, \Omega) = H(\text{div}, \Omega) + L(L^2(\Omega))$$

properties: $\|\underline{d}_0\|_{L^2(\Omega)} \leq C \|\phi\|_{L^2}$

$$\|\underline{d}_0\|_{L^2(\Omega)} \leq \|\underline{d}_1\|_{L^2}$$

$$\|v\|_{L^2(\Omega)}^2 \leq \|\underline{d}_0 + \underline{d}_1\|_{L^2} \cdot \underbrace{\|Lv\|_{L^2}}_{\leq C \|v\|_{L^2}}$$

$$\Rightarrow \|\underline{d}\|_{L^2} + \|v\|_{L^2} \lesssim \|\phi\|_{L^2}$$

$$\|\text{div} \underline{d}\|_{L^2}$$

$$\lesssim \|\phi\|_{H^1} \leq \|\phi\|_{L^2} \text{ (in step ①)}$$

