

## 2.5 Whitney forms and Galerkin approach

Lecture II 17-10-2023

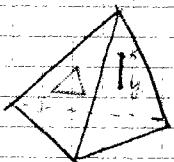
- Review of Whitney maps.

### 2.5.1 Simplicial Whitney forms (cont'd)

$$l=0. \quad x = \sum_i \lambda_i(x) a_i$$

$$W^0 w_l(x) = \sum_i \lambda_i(x) w_l(a_i)$$

$$l=1. \quad [x, y] = \sum_{i,j} (\lambda_i(x)\lambda_j(y) - \lambda_j(x)\lambda_i(y)) [a_i, a_j] = \sum_{i,j} \lambda_i(x)\lambda_j(y) [a_i, a_j]$$



$$\int_{[x,y]} W^1 w_l(x) = \sum_{i,j} \lambda_i(x)\lambda_j(y) w_l([a_i, a_j])$$

$$l=2. \quad \int_{[x, y, z]} W^2 w_l(x) = \sum_i \sum_j \sum_k \lambda_i(x)\lambda_j(y)\lambda_k(z) w_l([a_i, a_j, a_k])$$

With  $W^l w_l$  well defined for all  $l$ -facet-triangles  $T$ , we can define

### Local Reconstruction of differential forms

Recall by recovery formula:

$$w \in \Omega^k. \quad w(x)(x_1, \dots, x_k) = \int_{\mathbb{R}^k} \frac{t^k}{k!} \int_{\Sigma_t} w$$

$\Sigma_t = \text{convex hull } (x, x+tv_1, \dots, x+tv_k)$

$$l=1. \quad (W^1 w_l)(x)(v) = \int_{\mathbb{R}^2} \frac{1}{t} \int_{[x, x+tv]} W^1 w_l = \int_{\partial[x, x+tv]} \lambda_j = \int_{[x, x+tv]} d\lambda_j$$

$$\stackrel{\text{def. of } W}{=} \int_{t>0} \sum_{i,j} \left[ \lambda_i(x) \lambda_j(x+tv) - \lambda_j(x) \right] - \lambda_j(x) \frac{\lambda_i(x+tv) - \lambda_i(x)}{t}$$

(Note: always add/subtract  $\frac{1}{2} \sum_{i,j} \lambda_i(x) \lambda_j(x)$ )

$$\stackrel{*}{=} \sum_{i,j} (\lambda_i(x) d\lambda_j(x)(v) - \lambda_j(x) d\lambda_i(x)(v)) w_l(a_i, a_j)$$

$$\triangleright (W^1 w_l)(x) = \sum_{i,j} (\lambda_i(x) d\lambda_j(x) - \lambda_j(x) d\lambda_i(x)) w_l([a_i, a_j])$$

bases 1-form

$$(W^1 w_l)(x) = \sum_i \underbrace{\lambda_i(x)}_{\text{basis 0-form}} w_l(a_i)$$

bases 0-form

$$(W^2 w_l)(x) = \sum_{i_0 < i_1 < i_2} \sum_{j=0}^2 (-1)^j \lambda_{i_0} \lambda_{i_1} \lambda_{i_2} \overline{\lambda} \left( \lambda_j d\lambda_{i_0}(x) \right) w_l([a_{i_0}, a_{i_1}, a_{i_2}])$$

$$(W^l w_k)(x) = \alpha \sum_{i < j < k} (\lambda_i d_{ij} \wedge d_{ik} + \lambda_j d_{ik} \wedge d_{ji} + \lambda_k d_{ji} \wedge d_{ij}) w_k \text{ (basis } \omega\text{-form)}$$

(44)

$$(W^l w_k)(x) = l! \sum_{i_0 < i_1 < \dots < i_l} \left( \frac{l}{j=0} (-1)^j \lambda_{i_j} d_{i_0 i_1} \wedge d_{i_1 i_2} \wedge \dots \wedge d_{i_l i_0} \right) w_k(a_{i_0}, a_{i_1}, \dots, a_{i_l})$$

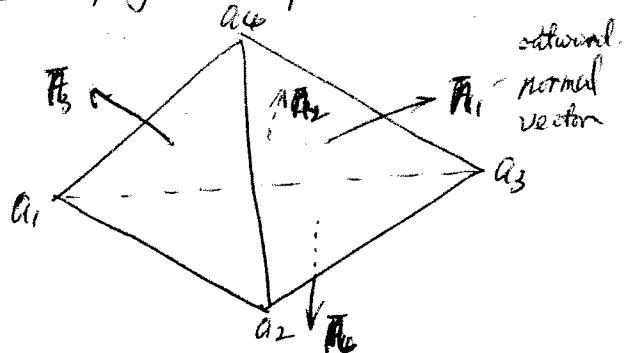
normalization factor      basis  $l$ -form  
for  $l$ -facet

Note:  $W^l$  commutes with trace  $\delta$  onto facets of a complex.

### 2.5.2 Simplicial Whitney finite elements.

Perspective: Vector proxies.

#### • Local polynomial spaces:



Recall:  $\lambda_i(x) = \frac{|F_i|}{3|T|} (x - a_j) \cdot n_i \quad \begin{cases} \text{linear} \\ \lambda_i(a_j) = \delta_{ij} \end{cases}$

$$\text{grad } \lambda_i(x) = \frac{|F_i|}{3|T|} \cdot n_i$$

$$l=0. \text{ VP } W^0 C^0(T) = \{x \mapsto a + b \cdot x \quad a \in R, b \in R^3\} \quad \dim = 4 = b(a) - C(ab)$$

$l=1$ . basis form associated with  $[a_i, a_j]$ .  $b_{ij} = \lambda_i \text{ grad } \lambda_j - \lambda_j \text{ grad } \lambda_i$ .

$$b_{ij} = \frac{|F_i| \cdot |F_j|}{9|T|^2} \left[ \underbrace{((x - a_k) \cdot n_i) n_j}_{(n_i \times n_j) \times (x - a_k)} - \underbrace{((x - a_k) \cdot n_j) n_i}_{(n_i \times n_j) \times (x - a_k)} \right]$$

$$= a + b \cdot x$$

$$\text{VP } W^1 C(T) = \{x \mapsto a + b \cdot x \quad a, b \in R^3\} \quad \dim = 6$$

$$(\nabla \times (b \cdot x)) =$$

$l=2$ .

basis  $\omega$ -form associated with  $[a_i, a_j, a_k]$ .

$$b_{ijk} = \lambda_i d_{jk} \wedge d_{ik} + \lambda_j d_{ik} \wedge d_{ji} + \lambda_k d_{ji} \wedge d_{kj}$$

$$= \frac{|F_i| |F_j| |F_k|}{27|T|^3} \cdot [((x - a_i) \cdot n_i) n_j \times n_k + ((x - a_i) \cdot n_j) n_k \times n_i + ((x - a_i) \cdot n_k) n_i \times n_j]$$

$$b_{ijk} = \frac{1}{27|T|^3} \frac{|F_i| |F_j| |F_k|}{\det(\mathbf{n}_i, \mathbf{n}_j, \mathbf{n}_k)} (x - \mathbf{a}_i) \det(\mathbf{n}_i, \mathbf{n}_j, \mathbf{n}_k) \quad (4)$$

$$= \frac{1}{6} \frac{|F_i|}{|T|} (x - \mathbf{a}_i)$$

V.P.  $W^2e^2(T) = \{x \rightarrow \mathbf{a} + \beta x, \mathbf{a} \in \mathbb{R}^3, \beta \in \mathbb{R}\}$ , dim = 4.

$\ell=3$ , V.P.  $W^3e^3(T) = \{x \rightarrow \mathbf{c}, \mathbf{c} \in \mathbb{R}^3\}$

• Degrees of freedom For local polynomial space  $W^\ell = \text{V.P. } W^\ell e^\ell(T)$

$\ell=0$ : point evaluation  $u \rightarrow u(a_i)$

$\ell=1$ : edge path integral  $u \rightarrow \int_e u \cdot d\vec{s}$  e. edge of T.

$\ell=2$ : face flux integral  $u \rightarrow \int_F u \cdot \mathbf{n} dS$  f. face of T.

$\ell=3$ : cell mass integral  $u \rightarrow \int_T u dV$

Check validity of defns.?

(i) unisolvence:  $\text{def} = 0 \Rightarrow$

$\int_T w = 0$  for  $w \in W^\ell(T) \Rightarrow \sum_I \int_{T_i} w_i = 0$

$$\Rightarrow w_i = 0 \Rightarrow w = 0$$

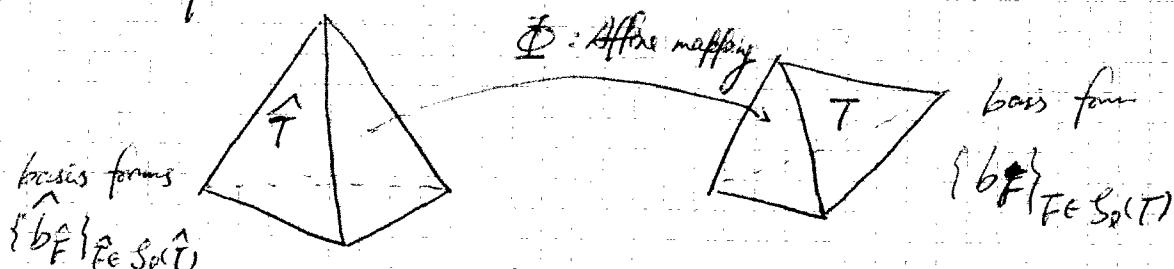
(ii) trace fixing: to show if all def associated with  $f \in S_\ell(T)$

vanishes  $\Rightarrow w = 0$  for  $w \in W^\ell e^\ell(T)$

(1-dim lower unisolvence condition)

▷ unique trace of Whitney forms on shared faces of two adjacent tetrahedra with the same d.o.f.

• pullback transform



## 2.6. Whitney form Galerkin Discretization

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Recall: variational formulation of Sect. 1.7.

Galerkin discretization: replace  $\mathcal{F}^l(\Omega)$  with  $\overset{\uparrow}{W^l(\mathcal{T}_h)}$   
mesh over  $\Omega$ .

R.K. ① For strong B.C.s  $\longleftrightarrow$  trial space  $\{w \in \mathcal{F}^l(\Omega), w|_{\partial\Omega} = 0 \}$

$\Rightarrow$  replace  $\mathcal{F}^l$  with  $\{w_h \in W^l(\mathcal{T}_h), \text{ basis functions associated with boundary facets are dropped}\}$

$$\textcircled{2} \quad W^l(\mathcal{T}_h) \cong \mathcal{C}^l(\mathcal{T}_h) \cong \mathbb{R}^{N_e}$$

$\uparrow$      $\uparrow$   
isomorphism

$$\begin{cases} \mathbb{R}^{N_e} & \longrightarrow W^l(\mathcal{T}_h) \\ (\alpha_i)_{i=1}^{N_e} & \longrightarrow w_i = \sum_j \alpha_i b_i^j \end{cases}$$

$i$ -th facet  
basis form associated with

$\rightarrow$  Matrix representation of  $d =$  matrix representation of  $d\ell = \underline{D}^\ell$

$$(d b_i^\ell = \sum_{j=1}^{N_{e+1}} (\underline{D}^\ell \mathbf{P}_{ji} b_j^{\ell+1})) \text{ Ex: verify in terms of V.F.s}$$

$$\ell=1.$$



Example: ( $\underline{C}$ -based V.F., PEC, local linear material law)

$\underline{C}_h \in W^l(\mathcal{T}_h) \leftarrow$  use only basis forms of interior edges

$$\int_{\Omega} \underline{\mu}^{-1} \operatorname{curl} \underline{e} \cdot \operatorname{curl} \underline{e}' dx + \underline{\sigma}^2 \int \underline{e} \cdot \underline{e}' dx = - \operatorname{div} \int_{\partial\Omega} \underline{g} \cdot \underline{e}' dx$$



Assume ordering of basis 1-forms  
— basis functions

$$\underline{C}_h = \sum_{e \in \mathcal{E}_1(\mathcal{T}_h)} g_e b_e$$

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$b_F^* = \Phi^* b_F$  : Whitney Finite elements are affine equivalent

prof: i)  $\beta_K = \Phi^* \alpha_K$

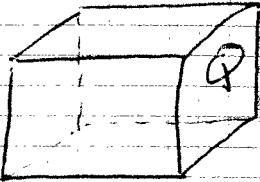
ii)  $\Phi^* d = d \circ \Phi^*$

### 2.5.3 Non-simplicial discrete differential forms

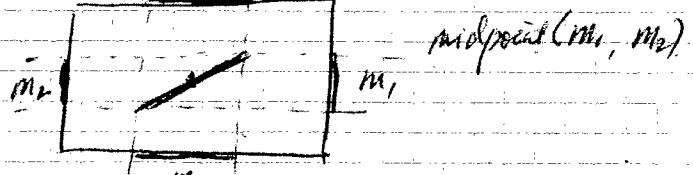
#### • Hexahedral Whitney forms

$$l=0, W(Q) = \{ x \mapsto \sum_{i=1}^3 (\alpha_i + \beta_i x) \quad \alpha_i, \beta_i \in \mathbb{R} \}$$

(trilinear polynomial)  $\dim = 8$  (#vertices)



$l=1$ . (follow simplicial case)



in 3D: / project onto face

/ → onto boundary edges with midpoint  $(m_1, m_2, m_3)$

→ for basis function with edge  $[0, 1] \times [0, 1] \times [0, 1]$

$$b(x) = \begin{pmatrix} (1-x_1)(1-x_2) \\ 0 \\ 0 \end{pmatrix}$$

$$W(Q) = \begin{pmatrix} P_0 \otimes P_1 \otimes P_2 \\ P_1 \otimes P_0 \otimes P_2 \\ P_2 \otimes P_0 \otimes P_1 \end{pmatrix} \quad \dim = 12.$$

$l=2$

$$W(Q) = \begin{pmatrix} P_0 \otimes P_0 \otimes P_0 \\ P_0 \otimes P_1 \otimes P_1 \\ P_0 \otimes P_2 \otimes P_1 \end{pmatrix} \quad \dim = 6$$

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$$\int_{\Omega} D^T \underline{M}_E + D^T \vec{\xi} + \partial_t^2 \underline{M}_E \vec{\xi} = - \partial_t \vec{\varphi}$$

$\in \mathbb{R}^{N_2 \times N_2}$  ( $N_2 = \# \text{ of interior faces}$ )

$$\underline{M}_{\text{eff.}} = \int \underline{M}^{-1} b_f^T b_f$$

↑ material matrix

$$\underline{M}_{e,e'} = \int_{\Omega} \underline{\varepsilon} b_e^T b_{e'} \quad (\vec{\varphi})_e = \int_{\Omega} \vec{\varphi} \cdot b_e$$

$$\vec{\xi}, \vec{\varphi} \in \mathbb{R}^{N_1} : N_1 = \# \text{ of interior edges}$$

• Computation of  $\underline{M}_E$ . say  $\underline{\varepsilon} = \underline{\varepsilon} \underline{I} =$

$$(\underline{M}_E)_{ee'} = \sum_{T \in \mathcal{T}_E} \underline{\varepsilon} b_e^T b_{e'}$$

$\underline{M}_E^T$  ↗ local cell

① Compute element material matrix  $\left( \int_T \underline{\varepsilon} b_e^T b_{e'} dx \right)_{e,e' \in \mathcal{E}_i(T)} \in \mathbb{R}^{6 \times 6}$

② Assemble  $\underline{M}_E$  following local-to-global edge index mapping with relative orientation.

$$\int_T \underline{\varepsilon}_0 \underbrace{(\lambda_i \partial_j - \lambda_j \partial_i) \cdot (\lambda_k \partial_l - \lambda_l \partial_k)}_{(\text{quadratic})} dx =$$

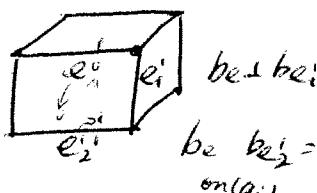
$$\int_T \lambda_i \lambda_j = |T| \cdot \frac{1}{(3+2)!} \begin{cases} 1 & i \neq j \\ 2 & i=j \end{cases} \begin{cases} \frac{1}{120} \\ \frac{1}{60} \end{cases}$$

RK:  $\underline{\varepsilon} = \underline{\varepsilon}(x)$  uses numerical quadrature to evaluate  $\underline{M}_E^T$  (at least exact for linear functions)

• Mass lumping:

• Consider  $Q \triangleq \text{cube}$ .

$$\int_Q f(x) dx \approx \frac{|Q|}{8} \sum_{i=1}^8 f(a_i) \quad a_i \text{ eight vertices}$$



$$(\underline{M}_E)_{ee'} = \frac{|Q|}{8} \sum_{i=1}^8 b_e(a_i) b_{e'}(a_i) = \begin{cases} 0 & \text{for all } e \neq e' \\ ? & (6x) \end{cases}$$

▷  $\underline{M}_E$  is diagonal; when computed with vertex-based quadrature

$\triangleright FVM \Rightarrow$  Whitney form (constant discretization + local numerical quadrature)

$\circ$  consider  $T =$  element mass lumping (open elusive?)

$$\int_T b_f \cdot b_{f'} dx = \begin{cases} 0 & \text{if } f \neq f' \\ ? & \end{cases}$$

integration by means of numerical quadrature.

Constraint: to this Mass lumping quadrature has to be exact for linear p's

$$\int_T \underline{c}_1 \cdot \underline{c}_2 = \int_T \underline{c}_1 \cdot \underline{c}_2 dx \quad \forall \underline{c}_1, \underline{c}_2 \in \mathbb{R}^3$$

$$\Rightarrow \int_T \underline{c}_{\text{curl}} \cdot \underline{\text{curl}} b_{e_i} dx = \int_T \underline{\text{curl}} \underline{c}_{\text{curl}} b_{e_i} dx, \quad \forall e, e' \in \mathcal{S}(T)$$

const      const

(Ex: find gen curl. that it is gen  
for  $e, e'$  opposite to it.)

? mass-lumping for  $L^2$ -forms is open

Ex: mass-lumping holds for  $L^2$ -forms at least exact for  
constants. (open problem)

RK: Diagonal material matrices are important for explicit time-stepping

