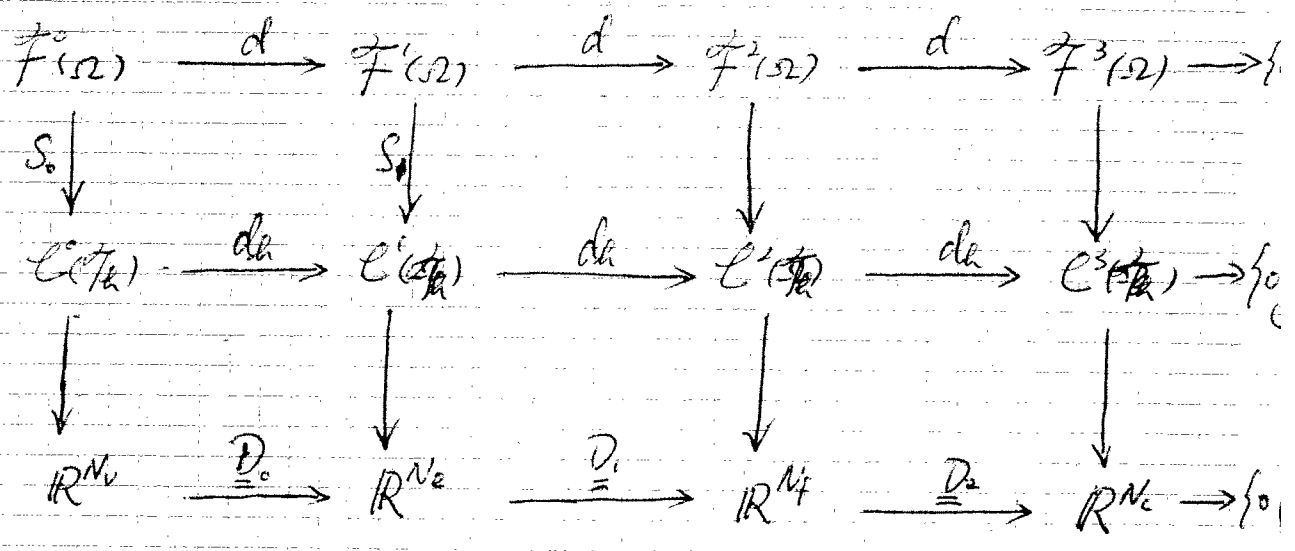


II. Co-chains and Whitney Forms

2.1. Meshes / Triangulations

2.2. Co-chains $C^l(\mathcal{T}_h)$ (Review)



2.3 Discrete Cohomology

2.3.1 Discrete potentials

If in Ω all ~~edges~~^{cycles} are boundaries, the sequence $(*)$ are exact.

2.3.2 Cohomology

$$\begin{array}{l}
 B_1(\mathcal{T}_h) \subsetneq Z_1(\mathcal{T}_h) \\
 B_1(\Omega) \subsetneq Z_1(\Omega)
 \end{array}$$

Ω : bidim. domain
 \mathcal{T}_h : mesh of Ω

set of boundaries
of all oriented
1+1-surfaces

set of l-dim
oriented surfaces $= \{ \Sigma \in S_l(\Omega), \partial \Sigma = \emptyset \}$
with empty boundary

Example: torus

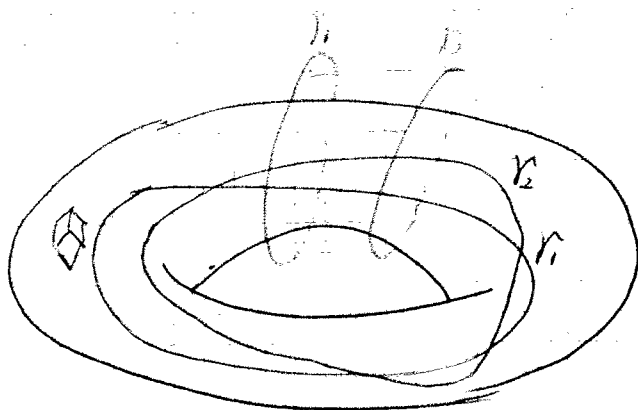


Define Equivalence relation of $Z_l(\Omega)$

$\gamma_1, \gamma_2 \in Z_l(\Omega) : \gamma_1 \sim \gamma_2 \iff \exists \text{ chain } \gamma_1 \pm \gamma_2 \in B_l(\Omega)$
more precisely

$\sum_i \gamma_i + \sum_j \gamma_j \in B_l(\Omega)$

$\sum_i \gamma_i \in \bar{Z}$ $\sum_i \gamma_i \neq \sum_j \gamma_j$
(Chain equivalence)



\Rightarrow Equivalence Class $[Z_l(\Omega)]_N$

$\dim [Z_l(\Omega)]_N = \underline{l\text{-th Betti number of } \Omega}$

$\beta_l(\Omega)$: finite & topologically invariant.

torus:
 $\beta_0(\Omega) = 1$ $\beta_0(A_3|\Omega) = 1$ # of connected component.

$\beta_1(\Omega) = 1$ $\beta_1(A_3|\Omega) = 1$ # of

$\beta_2(\Omega) = 0$ $\beta_2(A_3|\Omega) = 0$ #

Theorem = $\beta_l(T_2) = \beta_l(\Omega)$ if T_2 triangulates Ω

Def: Cohomology - space = $H_l(\Omega) = \text{kernel}(d|_{\mathcal{F}^l(\Omega)}) / \text{image}(d|_{\mathcal{F}^{l-1}(\Omega)})$
l-cohomology space of Ω quotient space

Theorem: $\dim H_l(\Omega) = \beta_l(\Omega)$

$l = 1$. if $\beta_1(\Omega) > 0 \iff \exists$ closed curves with no boundary

Find a representatives, $\dots \gamma_1, \dots \gamma_M$. $M = \beta_1(\Omega)$ of equivalence class.
in $[Z_1(\Omega)]_N$.

Find $\xi_i \in \mathcal{F}^1(\Omega)$ s.t. $d\xi_i = 0$ & $\int_{\gamma_j} \xi_i = \delta_{ij}$

Pick $\omega \in \mathcal{F}(\Omega)$. $d\omega = 0$

(35)

$$\tilde{\omega} = \omega - \sum_{j=1}^N \left(\int_{\gamma_j} \omega \right) \xi_j \Rightarrow \int_{\gamma_j} \tilde{\omega} = 0 \quad \forall j$$

Consider a general cycle $\gamma \in \mathcal{Z}_1(\Omega)$

$$\exists \beta_j \in \mathcal{B} : \gamma + \sum_{j=1}^M \beta_j \gamma_j \in \mathcal{B}_1(\Omega)$$

$$d\tilde{\omega} = 0 = 0 \Rightarrow 0 = \int_{\gamma + \sum_{j=1}^M \beta_j \gamma_j} \tilde{\omega} = \int_{\gamma} \tilde{\omega}$$

(lack of rigor)

Then $\exists \eta \in \mathcal{F}(\Omega)$ $d\eta = \tilde{\omega}$

$$d\eta - \omega \in \text{span} \{ \xi_1, \dots, \xi_M \} \hat{=} \mathcal{H}_1 \quad \#$$

Note: $\dim \mathcal{H}_1(\mathcal{T}_\Omega) = \dim \mathcal{H}_1(\Omega)$

$$\Rightarrow \dim \mathcal{H}_1(\mathcal{T}_\Omega) = \dim \mathcal{B}_1(\mathcal{T}_\Omega) = \dim \left(\frac{\ker(D_1)}{\text{Range}(D_0)} \right)$$

Def: Cohomology space of l -cochains

$$\mathcal{H}_l(\mathcal{T}_\Omega) = \ker(d_l |_{\mathcal{C}^l(\mathcal{T}_\Omega)}) / \text{Image}(d_l |_{\mathcal{C}^{l-1}(\mathcal{T}_\Omega)})$$

2.3.3 Relative cohomology (taking into account boundaries)

Skip

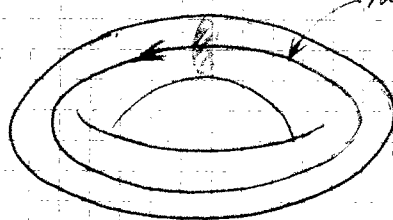
2.3.3 Representative of cohomology spaces

\Rightarrow we seek closed l -cochains / l -forms that do not have a potential

\exists no vanishing integral for some cycle!

Consider 3D: Ω with triangulation \mathcal{T}_Ω

Example: torus

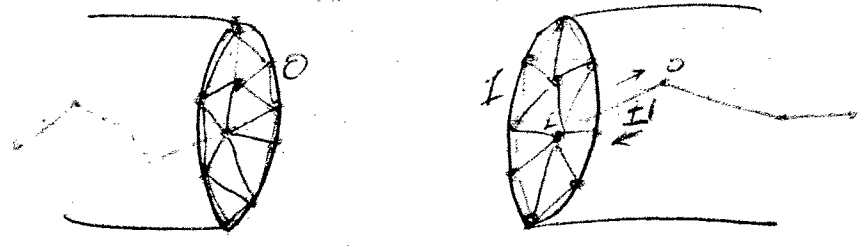


- Find* dual "cut" Σ

- ① surface consisting of α -facets.
- ② $\partial\Sigma \subset \partial\Omega$
- ③ Σ does not split Ω into two

* Poincaré duality theorem; (difficult proof)

Consider \mathcal{T}_h as a triangulation of $\Omega \setminus \Sigma$



- Define $\eta \in \mathcal{C}^0(\mathcal{T}_h)$ \mathcal{T}_h : divide faces on Σ into "two"
- $\eta(x) = 0$ \forall vertices of \mathcal{T}_h and not on cut.
 - $\eta(x) = 0$ on left side of \mathcal{T}_h of the cut Σ
 - $\eta(x) = 1$ on right side of \mathcal{T}_h of the cut Σ

Consider $d\eta$:

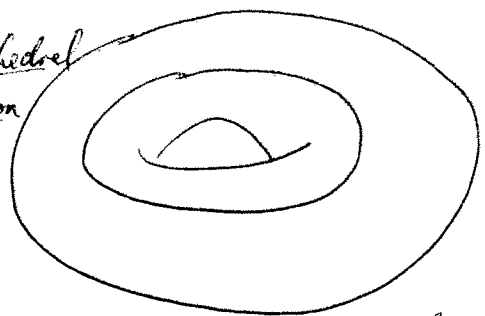
- $d\eta(e) = 0$ $\forall e$ on either sides on Σ
(constant on left (0) or on right (1))

$\Rightarrow d\eta \in \mathcal{C}^1(\mathcal{T}_h)$ ~~$d\eta(e) =$~~
 * is a well-defined 1-cochain before \mathcal{T}_h is cut into \mathcal{T}_h .

$\Rightarrow \int_{\gamma} d\eta = \pm 1$

$\Rightarrow d_h(d\eta) = 0$ first considered as $\mathcal{C}^1(\mathcal{T}_h)$, also as $\mathcal{C}^1(\mathcal{T}_h)$.

Ex. 3 $\Omega \triangleq$ complement of torus; $\mathcal{T}_h \triangleq$ tetrahedral
 inside a big ball; triangulation



Find closed α -cochain that is not the derivative of 1-cochain

Hint: Poincaré's Duality: "cut" \leftrightarrow path connecting the torus and the surface of the big ball

2.4. Finite Volume Discretization

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Recall: discrete topological electromagnetic laws (Sect 2.2)
also called "Network Equation"

$$\left. \begin{aligned} (2.4.a) \quad d_h \underline{e}_h &= - d_h \underline{b}_h \\ (2.4.b) \quad d_h \underline{h}_h &= d_h \underline{d}_h + \underline{j}_h \end{aligned} \right\} \text{"disconnected"}$$

\uparrow \uparrow
 1 -cochain 2 -cochain

Material Laws: connect $\underline{e}_h \leftrightarrow \underline{d}_h$ $\underline{h}_h \leftrightarrow \underline{b}_h$ (bijective)

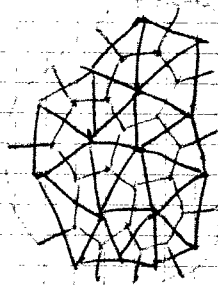
But: $\dim(\mathcal{C}^1(\mathcal{T}_h)) \neq \dim(\mathcal{C}^2(\mathcal{T}_h))$

Idea: Consider (2.4.a) (2.4.b) on different triangulations \mathcal{T}_h , $\hat{\mathcal{T}}_h$
for which: $N_e = \hat{N}_e - 1$ $N_e = \# \mathcal{E}_1(\mathcal{T}_h)$
 $\hat{N}_e = \# \mathcal{E}_1(\hat{\mathcal{T}}_h)$

Special tool: (dual mesh technique)

Choose \mathcal{T}_h , $\hat{\mathcal{T}}_h$ as dual meshes.

2D example:



cell count: $\hat{N}_c = N_c$ (# of cells)

edge count: $\hat{N}_e = N_e$ (# of edges)

\mathcal{T}_h $\hat{\mathcal{T}}_h$ - interior of dual mesh
(excluding all green ones)

$$\dim(\mathcal{C}^1(\mathcal{T}_h)) = \dim(\mathcal{C}^{2-l}(\hat{\mathcal{T}}_h))$$

$\mathcal{C}^1: \mathcal{T}_h \rightarrow \hat{\mathcal{T}}_h$ $2-l$ -cochains with vanishing traces

Compute incidence matrix

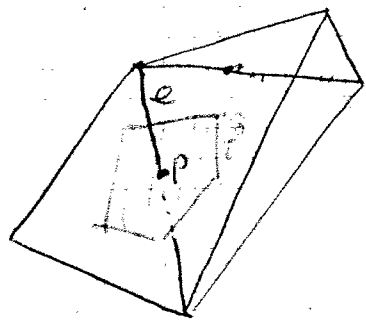
for \mathcal{T}_h , $\hat{\mathcal{T}}_h$. Check $\underline{D}_0 = \pm \hat{\underline{D}}^T \underline{d}_l$

Discrete Material Laws: on dual meshes?

Assumption: Consider linear isotropic material laws. $\underline{d} = \underline{\underline{\epsilon}} \underline{e}$

d_h
 defined on interior
 facets of dual mesh \hat{T}_h

d_h
 defined on edges
 of primal mesh T_h



$$\underline{e}_h(e) = \int_e \underline{e} \cdot d\vec{s} \quad \underline{e} \text{ - tangential component of } \underline{e}$$

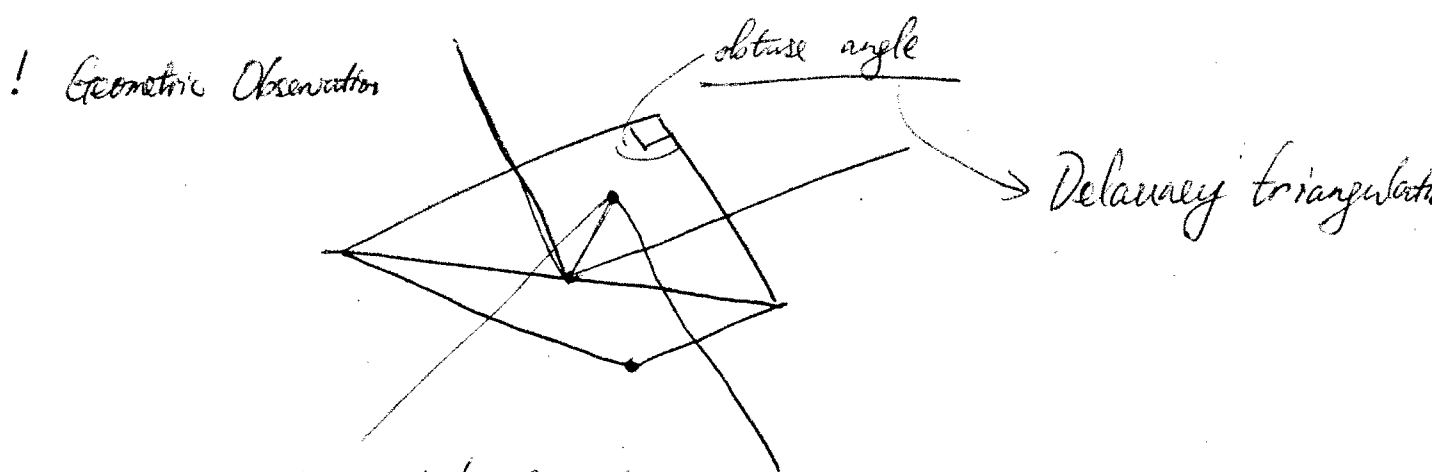
$$\underline{d}_h(\hat{f}) = \int_f \underline{d} \cdot \underline{n} \, dS \quad \underline{f} \text{ - normal component of } \underline{d}$$

☺ = \underline{e}_t match \underline{d}_n if $\boxed{e \perp \hat{f}}$

(2.4.c)
$$\underline{d}_h(\hat{f}) = \frac{|\hat{f}|}{|e|} \varepsilon(p) \cdot \underline{e}_h(e)$$

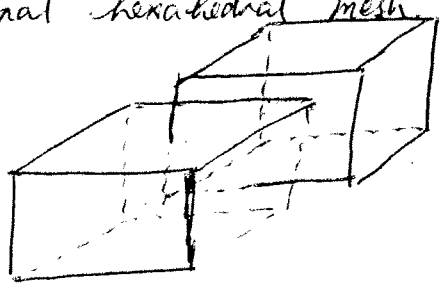
Conclusion: orthogonal dual mesh is required.

For tetrahedral T_h : vertices of \hat{T}_h = centers of circumscribed sphere of cells of T_h



Extreme simple mesh/dual mesh

Orthogonal hexahedral mesh



⇒ Yee's Scheme (FIT)
 (finite integration technique)

▷ Discrete Maxwell equation: (FVM approach on dual meshes)

$$\underline{D}_i \underline{e} = -\partial_t \underline{b}$$

$$\underline{D}_i \underline{h} = \partial_t \underline{d} + \underline{j}$$

$$\underline{b} = \underline{M}_\mu \underline{h} \quad \underline{M}_\mu \in \mathbb{R}^{N_{\text{cell}} \times N_{\text{cell}}} \text{ diagonal}$$

$$\underline{d} = \underline{M}_\epsilon \underline{e} \quad \underline{M}_\epsilon \in \mathbb{R}^{N_{\text{cell}} \times N_{\text{cell}}}$$

$$\Rightarrow \underline{D}_i (\underline{M}_\mu)^{-1} \underline{D}_i \underline{e}_0 = -\partial_t^2 \underline{M}_\epsilon \underline{e} - \partial_t \underline{j}$$

For dual meshes $\searrow \underline{D}_i^T (\underline{M}_\mu) \underline{D}_i \underline{e} = -\partial_t^2 \underline{M}_\epsilon \underline{e} - \partial_t \underline{j}$

$$\underline{D}_i \underline{e} = \underline{\hat{D}}_i^T \underline{e} \quad n: \text{dim of space}$$

$$\mathbb{R}^{N_{\text{cell}} \times N_{\text{cell}}}$$

$$\in \mathbb{R}^{\hat{N}_{\text{cell}} \times \hat{N}_{\text{cell}}-1}$$

$$(\because \underline{\hat{D}}_{i, \mu} \in \mathbb{R}^{\hat{N}_{\text{cell}}(\mu) \times \hat{N}_{\text{cell}}(\mu)})$$

2.5. Whitney Forms (Geometry Integration Theory) $\mathcal{T}_h \rightarrow \mathcal{P}_3 \rightarrow \mathcal{P}_8 \leftarrow \begin{matrix} \text{Bossavit} \\ \text{Wedec} \end{matrix}$

Goal: from cochains \rightarrow forms

\rightarrow seek linear Whitney maps $W^l: \mathcal{C}^l(\mathcal{T}_h) \rightarrow \mathcal{F}^l(\Omega)$
 ($\mathcal{T}_h \hat{=} \text{mesh of } \Omega$)

Requirements of such maps:

(2.5.a) $S_\Omega \circ W^l = \text{Id} \iff \int_\Omega W^l w_k = w_k(\Omega) \quad \forall \Omega \in \mathcal{S}_\Omega(\mathcal{T}_h)$
 W^l is a right inverse of S_Ω
 $\forall w_k \in \mathcal{C}^l(\mathcal{T}_h)$

(2.5.b) $d \circ W^{l+1} = W^{l+1} \circ d_k$

(2.5.c) Strict locality

$$W_k(f) = 0 \quad \forall f \in \mathcal{S}_\Omega(\mathcal{T}_h), f \in \overline{T} \text{ (star-shaped)}$$

$$\Rightarrow W^l w_k|_T = 0 \quad T: \text{cell of } \mathcal{T}_h \text{ in } \mathcal{S}_\Omega(\mathcal{T}_h)$$

$l=1$. $[x, y] \subset T$ line segment.

$$\begin{aligned}
 [x, y] &= \{ tx + (1-t)y, 0 \leq t \leq 1 \} \\
 &= \left\{ t \sum_{i=1}^4 \lambda_i(x) a_i + (1-t) \sum_{j=1}^4 \lambda_j(y) a_j, 0 \leq t \leq 1 \right\} \\
 &= \left\{ t \sum_{i=1}^4 \sum_{j=1}^4 \lambda_i(x) \lambda_j(y) a_i + (1-t) \sum_{j=1}^4 \sum_{i=1}^4 \lambda_j(y) \lambda_i(x) a_j, 0 \leq t \leq 1 \right\} \\
 &= \left\{ \sum_{i=1}^4 \sum_{j=1}^4 \lambda_i(x) \lambda_j(y) [t a_i + (1-t) a_j], 0 \leq t \leq 1 \right\}
 \end{aligned}$$

▷ Suggests

$$\int_{[x,y]} W^1 \omega_2 = \sum_{i=1}^4 \sum_{j=1}^4 \omega_2([a_i, a_j]) \lambda_i(x) \lambda_j(y)$$

$$\leq \sum_{1 \leq i < j \leq 4} \omega_2(\lambda_i(x) \lambda_j(y) - \lambda_j(x) \lambda_i(y)) \omega_2([a_i, a_j])$$

Definite of W^1

For $f \in T$ face $f = [a_1, a_2, a_3]$ $\lambda_4(x) = 0$ on f .

▷ $\omega_2([a_k, a_{k+1}]) = 0 \quad \forall k=1,2,3$.

⇒ $W^1 \omega_2|_f$ determined by $\omega_2([a_i, a_j]) \quad 1 \leq i < j \leq 3$

⇒ $W^1 \omega_2|_f$ is independent to tetrahedra adjacent to face f . (continuity, across faces)

▷ $W^1 \omega_2$ with edges patch together indeed defines global 1-forms.

(2.5.a) (2.5.c) ✓

(2.5.b) \mathbb{Z}_x To show: $\int_{\partial [x,y]} W^0 \omega_2 = \int_{[x,y]} W^1 (d\omega_2)$

$$\begin{aligned}
 \Rightarrow \text{LHS} &= W^0 \omega_2(y) - W^0 \omega_2(x) = \sum_{i=1}^4 (\lambda_i(y) - \lambda_i(x)) a_i \\
 &= \sum_{1 \leq i < j \leq 4} \sum_{j=1}^4 \lambda_i(x) \lambda_j(y) (d\omega_2([a_i, a_j])) = \sum_i \sum_j \lambda_i(x) \lambda_j(y) (\omega_2(a_j) - \omega_2(a_i))
 \end{aligned}$$

\mathbb{Z}_x : $l=1$ $\int_{\partial [x,y]} W^1 \omega_2 = \int_{[x,y]} W^2 (d\omega_2)$

★ $\int_{\Delta[x,y,z]} W^2 \omega_k \cong \sum_i \sum_j \sum_k \lambda_i(x) \lambda_j(y) \lambda_k(z) \omega_k(\Gamma a_i, a_j, a_k)$
 $\omega_k \in \mathcal{C}^2(\mathcal{T}_k)$

★ $\int_{\Delta[w,x,y,z]} W^3 \omega_k \cong \lambda_i(w) \lambda_j(x) \lambda_k(y) \lambda_l(z) \omega_k(\Gamma a_i, a_j, a_k, a_l)$
 $\omega_k \in \mathcal{C}^3(\mathcal{T}_k)$

$= \text{sgn}(i,j,k,l) (\lambda_i(w) \lambda_j(x) \lambda_k(y) \lambda_l(z)) \omega_k(\Gamma a_i, a_j, \dots, a_l)$

$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 \\ y_1 & y_2 & y_3 & y_4 \\ z_1 & z_2 & z_3 & z_4 \end{pmatrix} = \det \begin{pmatrix} \lambda_1(w) & \lambda_1(x) & \lambda_1(y) & \lambda_1(z) \\ \lambda_2(w) & \lambda_2(x) & \lambda_2(y) & \lambda_2(z) \\ \lambda_3(w) & \lambda_3(x) & \lambda_3(y) & \lambda_3(z) \\ \lambda_4(w) & \lambda_4(x) & \lambda_4(y) & \lambda_4(z) \end{pmatrix} \omega_k(\Gamma a_i, a_j, \dots, a_l)$

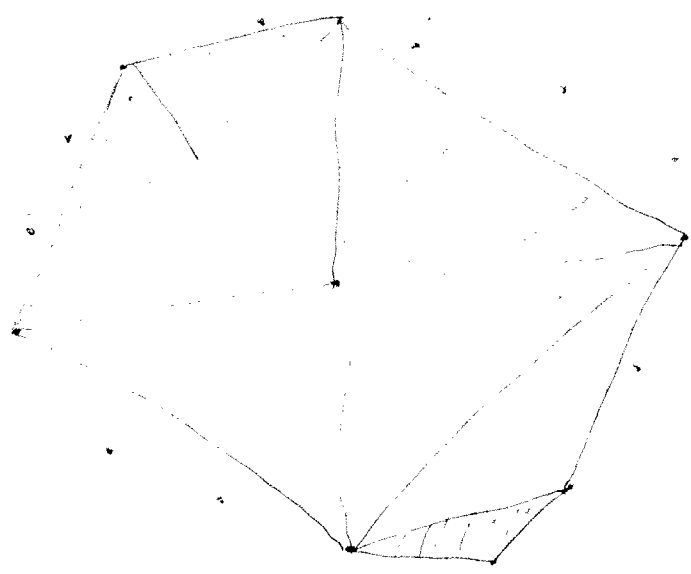
$|T| = \det(A) = \pm \frac{\Delta[w,x,y,z]}{B}$ (\pm determined by relative orientation of $\Delta[w,x,y,z]$ and T)

$A^T B = \begin{pmatrix} 1 & 1 & 1 & 1 \\ x_w & x_x & x_y & x_z \\ y_w & y_x & y_y & y_z \\ z_w & z_x & z_y & z_z \end{pmatrix} \Rightarrow \det(A^T B) = |\Delta[w,x,y,z]|$

★ Answer II: find a surface with a boundary given by a closed loop in a 3d mesh \mathcal{T}_k of Ω (simply-connected)

< Divide + Conquer >
 nested mesh \mathcal{T}_i

$\mathcal{T}_0 = (\text{coarse}) \subset$
 very deep knowledge of Graph theory.



- 1. closed loops can be represented at different level of mesh
- 2. Multilevel idea!
- 3. Minimum spanning tree Algo. (Prim's Algo)