Lecture 6: Finite difference methods

Habib Ammari

Department of Mathematics, ETH Zürich

- Finite difference methods: basic numerical solution methods for partial differential equations.
- Obtained by replacing the derivatives in the equation by the appropriate numerical differentiation formulas.
- Numerical scheme: accurately approximate the true solution.
- Basic finite difference schemes for the heat and the wave equations.

- Numerical algorithms for the heat equation
 Finite difference approximations
- Consider the heat equation

$$\begin{cases} \frac{\partial u}{\partial t} - \gamma \frac{\partial^2 u}{\partial x^2} = 0, & x \in [0, 1], t \ge 0, \\ u(t, 0) = u(t, 1) = 0, & t \ge 0, \\ u(0, x) = u_0(x), & x \in [0, 1], \end{cases}$$

 $\gamma > 0$: thermal conductivity.

- Numerical approximation to the solution u:
 - Rectangular mesh consisting of points (t_k, x_i) with

$$0 = t_0 < t_1 < t_2 < \dots$$
 and $0 = x_0 < x_1 < \dots < x_{N+1} = 1$.

Uniform time step and spatial mesh sizes:

$$\Delta t = t_{k+1} - t_k, \quad \Delta x = x_{j+1} - x_j = \frac{1}{N}.$$

• Numerical approximation of u at the mesh point (t_k, x_i) :

$$u_i^k \approx u(t_k, x_j)$$
 where $t_k = k\Delta t$, $x_j = j\Delta x$.

• Dirichlet boundary conditions $u(t,0) = u(t,1) = 0, t \ge 0 \Rightarrow$

$$u_0^k = u_{N+1}^k = 0$$
 for all $k > 0$.

- Finite difference approximations for the derivatives.
- Approximation of the second order space derivative:

$$\frac{\partial^{2} u}{\partial x^{2}}(t_{k}, x_{j}) \approx \frac{u(t_{k}, x_{j-1}) - 2u(t_{k}, x_{j}) + u(t_{k}, x_{j+1})}{(\Delta x)^{2}} + O((\Delta x)^{2})$$

$$\approx \frac{u_{j-1}^{k} - 2u_{j}^{k} + u_{j+1}^{k}}{(\Delta x)^{2}} + O((\Delta x)^{2}).$$

• Approximation of the time derivative:

$$\frac{\partial u}{\partial t}(t_k,x_j) \approx \frac{u(t_{k+1},x_j) - u(t_k,x_j)}{\Delta t} + O(\Delta t) \approx \frac{u_j^{k+1} - u_j^k}{\Delta t} + O(\Delta t).$$

• Explicit scheme:

$$\frac{u_j^{k+1} - u_j^k}{\Delta t} + \gamma \frac{-u_{j-1}^k + 2u_j^k - u_{j+1}^k}{(\Delta x)^2} = 0$$

for $k \geq 0$ and $j \in \{1, \dots, N\}$.

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$$\mu := \frac{\gamma \Delta t}{(\Delta x)^2};$$

 Vector whose entries are the numerical approximations to the solution values at time t_k at the interior nodes:

$$u^{(k)} := (u_1^k, u_2^k, \dots, u_N^k)^{\top} \approx (u(t_k, x_1), u(t_k, x_2), \dots, u(t_k, x_N))^{\top}.$$

• Matrix form:

$$u^{(k+1)} = Au^{(k)};$$

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$$A := \begin{pmatrix} 1 - 2\mu & \mu & & & & \\ \mu & 1 - 2\mu & \mu & & & \\ & \mu & 1 - 2\mu & \mu & & \\ & \ddots & \ddots & \ddots & \\ & & \mu & 1 - 2\mu & \mu \\ & & \mu & 1 - 2\mu \end{pmatrix}.$$

• A: symmetric and tridiagonal.

- Consistency, stability, and convergence
- General finite difference method:

$$F_{\Delta t, \Delta x}(\{u_{j+n}^{k+m}\}_{m^- \leq m \leq m^+, n^- \leq n \leq n^+}) = 0,$$

 m^{\pm} , n^{\pm} : width of the stencil of the scheme.

- DEFINITION: Consistency and order
 - Finite difference scheme: consistent with F(u) = 0 if, for any smooth solution u(x, t), truncation error:

$$F_{\Delta t, \Delta x}(\{u(t_{k+m}, x_{j+n})\}_{m^- \le m \le m^+, n^- \le n \le n^+}) \to 0$$

as Δt and $\Delta x \rightarrow 0$ independently.

• Scheme: of order p in time and order q in space if truncation error: of the order of $O((\Delta t)^p + (\Delta x)^q)$ as Δt and $\Delta x \to 0$.

THFORFM:

- Explicit scheme: consistent with the heat equation, of order one in time and two in space.
- Moreover, if

$$(*) \qquad \frac{\gamma \Delta t}{(\Delta x)^2} = \frac{1}{6},$$

then, explicit scheme: of order two in time and four in space.

- PROOF:
 - Taylor expansion of $v(t,x) \in \mathcal{C}^6$ evaluated at (t,x),

$$\frac{v(t + \Delta t, x) - v(t, x)}{\Delta t} + \gamma \frac{-v(t, x - \Delta x) + 2v(t, x) - v(t, x + \Delta x)}{(\Delta x)^2}$$

$$= (\frac{\partial v}{\partial t} - \gamma \frac{\partial^2 v}{\partial x^2})(t, x) + \frac{\Delta t}{2} \frac{\partial^2 v}{\partial t^2}(t, x) - \frac{\gamma(\Delta x)^2}{12} \frac{\partial^4 v}{\partial x^4}(t, x)$$

$$+ O((\Delta t)^2 + (\Delta x)^4).$$

- v: solution of the heat equation ⇒ truncation error goes to zero as
 Δt, Δx → 0 ⇒ explicit scheme: consistent.
- Scheme: of order 1 in time and 2 in space.
- Suppose that (*) holds \Rightarrow terms in Δt and $(\Delta x)^2$ cancel out since

$$\frac{\partial^2 v}{\partial t^2} = \gamma \frac{\partial^3 v}{\partial t \partial x^2} = \gamma^2 \frac{\partial^4 v}{\partial x^4}.$$

• Explicit scheme: of order 2 in time and 4 in space.

- DEFINITION: Stability
 - Finite difference scheme: stable with respect to the norm $\| \cdot \|_r$ defined by

$$||u^{(k)}||_r := \left(\sum_{j=1}^N \Delta x |u_j^k|^r\right)^{\frac{1}{r}}, \quad 1 \le r \le +\infty,$$

 $u^{(k)}$, if there exists a positive constant C independent of Δt and Δx s.t.

$$||u^{(k)}||_r \le C||u^{(0)}||_r$$
 for all $k \ge 0$.

- DEFINITION: Linear scheme
 - Finite difference scheme: linear if scheme: linear with respect to its arguments u_{i+n}^{k+m} .
- Linear finite difference scheme:

$$u^{(k+1)} = Au^{(k)},$$

A: iteration matrix.

 $\bullet \Rightarrow$

$$u^{(k+1)} = A^{k+1}u^{(0)}.$$

Stability ⇔

$$\|A^k u^{(0)}\|_r \le C \|u^{(0)}\|_r$$
, for all $k \ge 0$ and $u^{(0)} \in \mathbb{R}^N$.

Matrix norm

$$||M||_r = \sup_{u \in \mathbb{R}^N, u \neq 0} \frac{||Mu||_r}{||u||_r}.$$

● Stability ⇔

$$||A^k||_r \le C$$
, for all $k \ge 0$.

- Stability in the L^{∞} norm
- L^{∞} -norm:

$$||u^{(k)}||_{\infty} := \sup_{1 \le j \le N} |u_j^k|.$$

• Implicit scheme:

$$\frac{u_j^{k+1} - u_j^k}{\Delta t} + \gamma \frac{-u_{j-1}^{k+1} + 2u_j^{k+1} - u_{j+1}^{k+1}}{(\Delta x)^2} = 0$$

for $k \geq 0$ and $j \in \{1, \dots, N\}$.

• Implicit scheme well defined: $u^{(k+1)}$ can be obtained from $u^{(k)}$ by inverting the definite positive matrix

$$\begin{pmatrix} 1+2\mu & -\mu & & & & \\ -\mu & 1+2\mu & -\mu & & & \\ & -\mu & 1+2\mu & -\mu & & \\ & \ddots & \ddots & \ddots & \\ & & -\mu & 1+2\mu & -\mu \\ & & & -\mu & 1+2\mu \end{pmatrix}.$$

• THFORFM:

(i) Explicit scheme: stable with respect to the L^{∞} norm iff the Courant-Friedrichs-Lewy (CFL) condition holds:

$$2\gamma\Delta t\leq (\Delta x)^2.$$

(ii) Implicit scheme: unconditionally stable with respect to the L[∞] norm.

- Stability in the L² norm
- Consider the heat equation with the periodic boundary conditions

$$u(t,x+1)=u(t,x) \quad \text{for all } x\in [0,1], \quad t\geq 0.$$

• For any $u^{(k)}=(u_j^k)_{j=0,\dots,N}$, we associate a piecewise constant function $u^{(k)}(x)$, periodic with period 1, defined on [0,1] by

$$u^{(k)}(x) := u_j^k \quad \text{for } x_{j-\frac{1}{2}} < x < x_{j+\frac{1}{2}},$$

$$x_{j+\frac{1}{2}} = (j+\frac{1}{2})\Delta x, \quad j = 0, \dots, N, \quad x_{-\frac{1}{2}} = 0, x_{N+1+\frac{1}{2}} = 1.$$

• Fourier series of $u^{(k)}$:

$$u^{(k)}(x) = \sum_{n \in \mathbb{Z}} \hat{u}_n^{(k)} e^{2\pi i n x},$$

$$\hat{u}_n^{(k)} := \int_0^1 u^{(k)}(x) e^{-2\pi i n x} dx.$$

Plancherel's formula ⇒

$$\int_0^1 |u^{(k)}(x)|^2 dx = \sum_{n \in \mathbb{Z}} |\hat{u}_n^{(k)}|^2.$$

• Property of Fourier series of periodic functions:

$$v^{(k)}(x) = u^{(k)}(x + \Delta x) \Rightarrow \hat{v}_n^{(k)} = \hat{u}_n^{(k)} e^{2\pi i n \Delta x}.$$

• Explicit scheme:

$$\frac{u^{k+1}(x)-u^k(x)}{\Delta t}+\gamma\frac{-u^k(x-\Delta x)+2u^k(x)-u^k(x+\Delta x)}{(\Delta x)^2}=0.$$

Fourier transform ⇒

$$\hat{u}_n^{(k+1)} = \left(1 - \frac{\gamma \Delta t}{(\Delta x)^2} \left(e^{-2\pi i n \Delta x} + 2 - e^{2\pi i n \Delta x}\right)\right) \hat{u}_n^{(k)}.$$

Equivalently,

$$\hat{u}_n^{(k+1)} = \alpha(n)\hat{u}_n^{(k)} = \alpha(n)^{k+1}\hat{u}^{(0)}(n)$$

with

$$\alpha(n) := 1 - \frac{4\gamma \Delta t}{(\Delta x)^2} (\sin(\pi n \Delta x))^2.$$

• $\Rightarrow \hat{u}_n^{(k)}$: bounded as $k \to +\infty$ iff the amplification factor $\alpha(n)$ satisfies

$$|\alpha(n)| \le 1$$
 for all $n \in \mathbb{Z}$.

Plancherel's formula ⇒

$$\|u^{(k)}\|_2^2 = \int_0^1 |u^{(k)}(x)|^2 dx = \sum_{n \in \mathbb{Z}} |\hat{u}_n^{(k)}|^2 \le \sum_{n \in \mathbb{Z}} |\hat{u}_n^{(0)}|^2 = \|u^{(0)}\|_2^2,$$

- \Rightarrow Conditional stability with respect to the L^2 norm.
- CFL condition:

$$\frac{2\gamma\Delta t}{(\Delta x)^2} \leq 1.$$



Implicit scheme:

$$\frac{u^{k+1}(x) - u^k(x)}{\Delta t} + \gamma \frac{-u^{k+1}(x - \Delta x) + 2u^{k+1}(x) - u^{k+1}(x + \Delta x)}{(\Delta x)^2} = 0.$$

Fourier transform ⇒

$$\hat{u}_n^{(k+1)} = \beta(n)\hat{u}_n^{(k)} = \beta(n)^{k+1}\hat{u}^{(0)}(n),$$

$$\beta(n) := \left(1 + \frac{4\gamma \Delta t}{(\Delta x)^2} (\sin(\pi n \Delta x))^2\right)^{-1}.$$

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 Plancherel's formula ⇒ Unconditional stability with respect to the L² norm.

• THEOREM:

(i) Explicit scheme: stable with respect to the L^2 norm iff the CFL condition

$$2\gamma \Delta t \leq (\Delta x)^2$$

holds.

(ii) Implicit scheme: unconditionally stable with respect to the L^2 norm.

- Convergence
- THEOREM: Lax theorem
 - *u*: smooth solution of the heat equation.
 - Suppose that the finite difference scheme for computing the numerical solution u_j^k: linear, consistent, and stable with respect to the norm || ||_r.
 - Let $e_j^k := u_j^k u(t_k, x_j)$ and $e^{(k)} = (e_1^k, e_2^k, \dots, e_N^k)^{\top}$.
 - Assume that $u_j^0 = u_0(x_j)$.

Then,

$$\lim_{\Delta t, \Delta x \to 0} \big(\sup_{t_k \le T} \|e^{(k)}\|_r \big) = 0 \quad \text{for all } T > 0.$$

Moreover, if the scheme: of order p in time and q in space, then there
exists a constant C_T > 0 s.t.

$$\sup_{t_k \le T} \|e^{(k)}\|_r \le C_T ((\Delta t)^p + (\Delta x)^q).$$

- PROOF:
 - $u^{(k+1)} = Au^{(k)}$; A: iteration matrix; $\widetilde{u}_i^k = u(t_k, x_j)$.
 - Consistency \Rightarrow there exists $e^{(k)}$ s.t.

$$\widetilde{u}^{(k+1)} = A\widetilde{u}^{(k)} + (\Delta t)\epsilon^{(k)} \quad \text{and} \quad \lim_{\Delta t, \Delta x \to 0} \|\epsilon^{(k)}\|_r = 0,$$

uniformly in k.

• Scheme: of order *p* in time and *q* in space ⇒

$$\|\epsilon^{(k)}\|_r \leq C((\Delta t)^p + (\Delta x)^q).$$

• ⇒

$$e^{(k+1)} = Ae^{(k)} - \Delta t \epsilon^{(k)}.$$

• By induction,

$$e^{(k)} = A^k e^{(0)} - \Delta t \sum_{l=1}^k A^{k-l} \epsilon^{(l-1)}.$$

• Stability ⇒

$$||A^k||_r \leq C'$$

for some positive constant C'.

ullet \Rightarrow

$$\|e^{(k)}\|_r \leq (\Delta t)kCC'((\Delta t)^p + (\Delta x)^q) \leq TCC'((\Delta t)^p + (\Delta x)^q).$$

• Numerical algorithms for the one-way wave equation

$$\begin{cases} \frac{\partial u}{\partial t} = c \frac{\partial u}{\partial x}, \\ u(0, x) = u_0(x), \end{cases}$$

- c > 0: wave speed.
- Solution given by $u(t,x) = u_0(x+ct)$.
- Identity:

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}.$$

• There are three finite difference approximations of the solution:

$$\frac{u_j^{k+1}-u_j^k}{\Delta t} = \left\{ \begin{array}{ll} c\frac{u_{j+1}^k-u_j^k}{\Delta x} & \text{upwind scheme}, \\ \\ c\frac{u_j^k-u_{j-1}^k}{\Delta x} & \text{downwind scheme}, \\ \\ c\frac{u_{j+1}^k-u_{j-1}^k}{2\Delta x} & \text{centered scheme}. \end{array} \right.$$

• Taylor expansions of a smooth solution *u*:

$$\begin{split} \frac{u(t+\Delta t,x)-u(t,x)}{\Delta t} &= \frac{\partial u}{\partial t}(t,x) + \frac{\Delta t}{2} \frac{\partial^2 u}{\partial t^2}(t,x) + O((\Delta t)^2), \\ \frac{u(t,x+\Delta x)-u(t,x)}{\Delta x} &= \frac{\partial u}{\partial x}(t,x) + \frac{\Delta x}{2} \frac{\partial^2 u}{\partial x^2}(t,x) + O((\Delta x)^2), \\ \frac{u(t,x+\Delta x)-u(t,x-\Delta x)}{\Delta x} &= \frac{\partial u}{\partial x}(t,x) + O((\Delta x)^2), \end{split}$$

- \Rightarrow truncation error in the upwind scheme is $O(\Delta t + \Delta x)$.
- Analogously, the truncation error in the downwind scheme is $O(\Delta t + \Delta x)$, while the one in the centered is $O(\Delta t + (\Delta x)^2)$.
- If

$$c = \frac{\Delta x}{\Delta t}$$

then the truncation error in the upwind scheme is $O((\Delta t)^2 + (\Delta x)^2)$.

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 Stability analysis: one can easily see that the upwind scheme is stable with respect to the L² norm provided that the following CFL condition holds:

$$\frac{c\Delta t}{\Delta x} \le 1.$$

- Downwind and the centered schemes are unstable.
- One way to fix the stability issue for the centered scheme is to add diffusion. One replaces the centered scheme with

$$\frac{u_{j}^{k+1}-u_{j}^{k}}{\Delta t}=c\frac{u_{j+1}^{k}-u_{j-1}^{k}}{2\Delta x}+\theta\frac{u_{j+1}^{k}-2u_{j}^{k}+u_{j-1}^{k}}{(\Delta x)^{2}},$$

where $\theta > 0$, or equivalently, with

$$\frac{u_{j}^{k+1} - \left(\frac{\lambda}{2}u_{j+1}^{k} + (1-\lambda)u_{j}^{k} + \frac{\lambda}{2}u_{j-1}^{k}\right)}{\Delta t} = c\frac{u_{j+1}^{k} - u_{j-1}^{k}}{2\Delta x}.$$

Here, λ is defined by

$$\lambda = \frac{2\Delta t}{(\Delta x)^2} \theta.$$

- Numerical algorithms for the wave equation
- Consider the wave equation

$$\left\{ \begin{array}{l} \displaystyle \frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < 1, \quad t \geq 0, \\ \\ \displaystyle u(t, x+1) = u(t, x), \quad 0 < x < 1, \quad t \geq 0, \\ \\ \displaystyle u(0, x) = u_0(x), \quad 0 < x < 1, \\ \\ \displaystyle \frac{\partial u}{\partial t}(0, x) = u_1(x), \quad 0 < x < 1, \end{array} \right.$$

c > 0: wave speed.

Suppose

(**)
$$\int_0^1 u_1(x) \, dx = 0.$$

- Similar to the numerical schemes for the heat equation, we can use differentiation formulas to arrive at a numerical scheme for the wave equation.
- Since both time and space derivatives are of second order, we use centered differences to approximate them:

$$\begin{array}{ll} \frac{\partial^2 u}{\partial t^2}(t_k,x_j) & \approx & \frac{u(t_{k-1},x_j)-2u(t_k,x_j)+u(t_{k+1},x_j)}{(\Delta t)^2} + O((\Delta t)^2) \\ \\ & \approx & \frac{u_j^{k-1}-2u_j^k+u_j^{k+1}}{(\Delta t)^2} + O((\Delta t)^2). \end{array}$$

• Then up to an error of order $O((\Delta x)^2 + (\Delta t)^2)$ the solution to the wave equation can be approximated by the following explicit finite difference scheme:

$$\frac{u_j^{k+1} - 2u_j^k + u_j^{k-1}}{(\Delta t)^2} = c^2 \frac{u_{j+1}^k - 2u_j^k + u_{j-1}^k}{(\Delta x)^2}.$$

• One can prove that the scheme is stable in the L^2 norm provided that $c(\Delta t)/(\Delta x) < 1$.

Another standard finite difference scheme for solving the wave equation:
 θ-centered scheme

$$\begin{cases} \frac{u_j^{k+1} - 2u_j^k + u_j^{k-1}}{(\Delta t)^2} + \theta c^2 \frac{-u_{j-1}^{k+1} + 2u_j^{k+1} - u_{j+1}^{k+1}}{(\Delta x)^2} \\ + (1 - 2\theta)c^2 \frac{-u_{j-1}^k + 2u_j^k - u_{j+1}^k}{(\Delta x)^2} + \theta c^2 \frac{-u_{j-1}^{k-1} + 2u_j^{k-1} - u_{j+1}^{k-1}}{(\Delta x)^2} = 0, \end{cases}$$

$$0 \le \theta \le 1/2$$
.

- If $\theta = 0$, then the scheme: explicit;
- Scheme: implicit if $\theta \neq 0$.
- Initial conditions expressed by

$$u_j^0 = u_0(x_j)$$
 and $\frac{u_j^1 - u_j^0}{\Delta t} = \int_{x_{j-1/2}}^{x_{j+1/2}} u_1(x) dx;$

• ⇒ (**): satisfied by the numerical solution.

THFORFM:

- If $1/4 \le \theta \le 1/2$, then the θ -centered scheme: unconditionally stable with respect to the L^2 norm.
- If $0 \le \theta < 1/4$, scheme: stable provided that the CFL condition

$$\frac{c\Delta t}{\Delta x} < \sqrt{\frac{1}{1 - 4\theta}}$$

holds and unstable if $c\Delta t/\Delta x > 1/\sqrt{1-4\theta}$.