

Numerical Methods for Computational Science and Engineering

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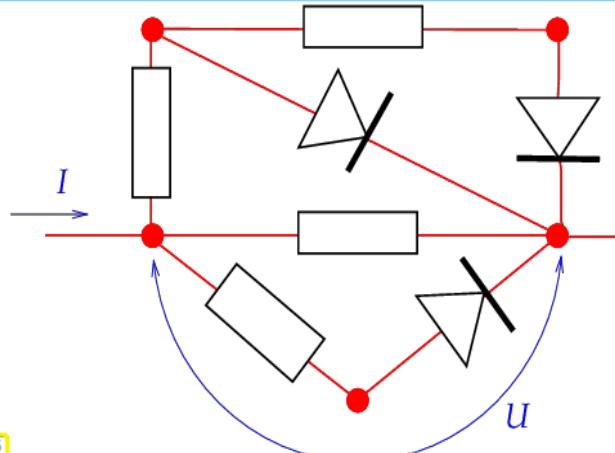
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URL: <http://www.sam.math.ethz.ch/~hiptmair/tmp/NumCSE/NumCSE16.pdf>

VI. Approximation of Functions in 1D

Case study: Model reduction in circuit simulation



↳ 2-port (non-linear) circuit element

$$I = I(U)$$

↳ available for any U through solving a system of equations (expensive!)

Goal: replace $I = I(U)$ with a function $U \rightarrow \tilde{I}(U)$
that allows fast point evaluation (also of derivative)

Approximation of functions: Generic view

Given: function $f : D \subset \mathbb{R}^n \rightarrow \mathbb{R}^d$ (often in procedural form `double f(double)`, Rem. 5.1.4)
↓ a function

Goal: Find a "SIMPLE" function $\tilde{f} : D \rightarrow \mathbb{R}^d$ such that the approximation error $f - \tilde{f}$ is "SMALL"

Here: $n = 1$ ↓ measured w.r.t. some norm

e.g. polynomials

- Supremum norm: $\|f\|_\infty = \max_{t \in D} |f(t)|$
- L^2 -norm: $\|f\|_2 = \sqrt{\int_D |f(t)|^2 dt}$

Policy: Approximation by interpolation

↳ Mapping functions → functions

Interpolation scheme + sampling → approximation scheme: $A : C^0(I) \rightarrow V$

$$f : I \subset \mathbb{R} \rightarrow \mathbb{K} \xrightarrow{\text{sampling}} (t_i, y_i := f(t_i))_{i=0}^m \xrightarrow{\text{interpolation}} \tilde{f} := I_T y \quad (\tilde{f}(t_i) = y_i).$$

free choice of nodes $t_i \in I$

New freedom: choice of nodes

②

6.1. Approximation by global Polynomials

Known: Approximation by Taylor polynomial

$$f \in C^{k+1} : f(t) \approx f(t_0) + f'(t_0)(t-t_0) + f''(t_0)\frac{1}{2}(t-t_0)^2 + \dots + f^{(k)}(t_0)\frac{1}{k!}(t-t_0)^k$$

↑
smoothness requirement

$\in \mathcal{P}_k$

4.1.1. Polynomial Approximation: Theory

① Uniform approximation = approx. in $\| \cdot \|_\infty = \| \cdot \|_{L^\infty(I)}$

Theorem 6.1.6. Uniform approximation by polynomials

For $f \in C^0([0,1])$, define the n -th Bernstein approximant as

$$p_n(t) = \sum_{j=0}^n f(j/n) \binom{n}{j} t^j (1-t)^{n-j}, \quad p_n \in \mathcal{P}_n. \quad (6.1.7)$$

Bernstein polynomials

It satisfies $\|f - p_n\|_\infty \rightarrow 0$ for $n \rightarrow \infty$. If $f \in C^m([0,1])$, then even $\|f^{(k)} - p_n^{(k)}\|_\infty \rightarrow 0$ for $n \rightarrow \infty$ and all $0 \leq k \leq m$.

$\rightarrow p_n \rightarrow f$ converges "slowly"

② Quantitative uniform best approximation

Theorem 6.1.15. L^∞ polynomial best approximation estimate

If $f \in C^r([-1,1])$ (r times continuously differentiable), $r \in \mathbb{N}$, then, for any polynomial degree $n \geq r$,

$$\inf_{p \in \mathcal{P}_n} \|f - p\|_{L^\infty([-1,1])} \leq (1 + \pi^2/2)^r \frac{(n-r)!}{n!} \|f^{(r)}\|_{L^\infty([-1,1])}.$$

(norm of) best approximation error ↑ smoothness requ.

- Asymptotics for $n \rightarrow \infty$: $O(n^{-r})$ *
- * = algebraic convergence (in degree) [with rate r]

Example for asymptotic behavior of family $\{A_n\}$ of approximation schemes:

How does $\|f - A_n f\|$ behave as a function of $n \rightarrow \infty$

- Note: Smoothness of f governs rate r of alg. conv.

$$f \in C^\infty \Rightarrow \forall r \in \mathbb{N} : \exists C = C(r)$$

$$\inf_{p \in \mathcal{P}_n} \|f - p\| \leq C(r) n^{-r}$$

$\uparrow \rightarrow \infty$ as $r \rightarrow \infty$
possible

③

Transformation to arbitrary intervals $[a, b]$:

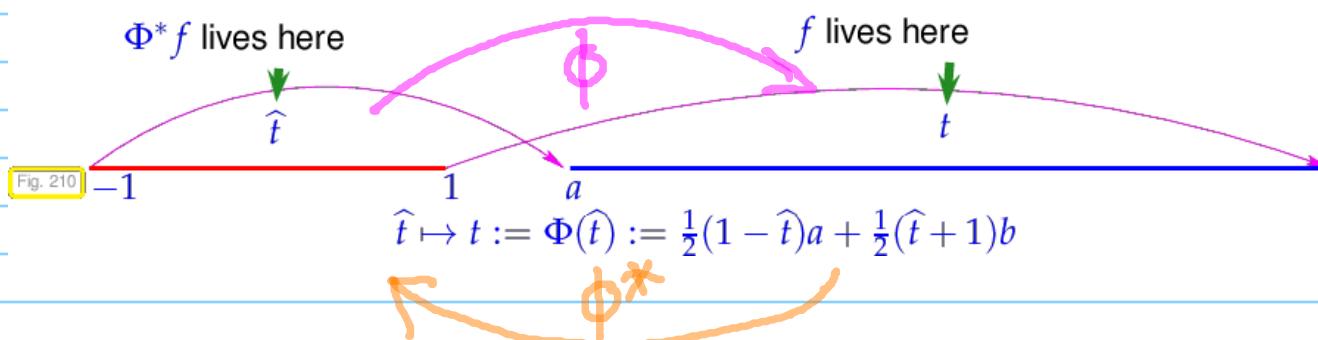
Tool: affine transformation $\phi: [-1, 1] \rightarrow [a, b]$

$$\phi(\hat{t}) = a + \frac{1}{2}(b-a)(\hat{t}+1), -1 \leq \hat{t} \leq 1$$

Pullback of functions: $(\phi^* f)(\hat{t}) := f(\phi(\hat{t}))$

for $f: [a, b] \rightarrow \mathbb{R}$

$$\Phi^*: C^0([a, b]) \rightarrow C^0([-1, 1]), \quad \Phi^*(f)(\hat{t}) := f(\Phi(\hat{t})), \quad -1 \leq \hat{t} \leq 1. \quad (6.1.20)$$



$$\Phi^* f := f \circ \phi$$

- $\phi^*: \mathcal{P}_n \rightarrow \mathcal{P}_n$ bijective

- $\|\phi^* f\|_{\infty, [-1, 1]} = \|f\|_{\infty, [a, b]}$

- " $\phi^* \leftrightarrow$ stretching/compressing"

$$(\phi^* f)' = \phi'(f') \circ \phi' = \frac{1}{2}(b-a) \phi^*(f')$$

[chain rule]

$$(\Phi^* f)^{(r)} = \left(\frac{b-a}{2}\right)^r \Phi^*(f^{(r)}). \quad (6.1.28)$$

Lemma 6.1.24

$$\|(\Phi^* f)^{(r)}\|_{L^\infty([-1, 1])} = \left(\frac{b-a}{2}\right)^r \|f^{(r)}\|_{L^\infty([a, b])}, \quad f \in C^r([a, b]), r \in \mathbb{N}_0. \quad (6.1.29)$$

$$\inf_{p \in \mathcal{P}_n} \|f - p\|_{\infty, [a, b]} = \inf_{p \in \mathcal{P}_n} \|\phi^*(f - p)\|_{\infty, [-1, 1]}$$

$$[\Phi^*(\mathcal{P}_n) = \mathcal{P}_n] = \inf_{p \in \mathcal{P}_n} \|\phi^* f - \phi^* p\|_{\infty, [-1, 1]}$$

$$[\text{Thm 6.1.15}] \leq C n^{-r} \|(\Phi^* f)^{(r)}\|_{\infty, [-1, 1]}$$

$$\leq C n^{-r} \left(\frac{b-a}{2}\right)^r \|f^{(r)}\|_{\infty, [a, b]}$$

depends on ↑ length of interval

④

6.1.2. Error estimates for Polynomial Interpolation

Definition 6.1.32. Lagrangian (interpolation polynomial) approximation scheme

Given an interval $I \subset \mathbb{R}$, $n \in \mathbb{N}$, a node set $\mathcal{T} = \{t_0, \dots, t_n\} \subset I$, the Lagrangian (interpolation polynomial) approximation scheme $L_{\mathcal{T}} : C^0(I) \rightarrow \mathcal{P}_n$ is defined by

$$L_{\mathcal{T}}(f) := l_{\mathcal{T}}(\mathbf{y}) \in \mathcal{P}_n \quad \text{with} \quad \mathbf{y} := (f(t_0), \dots, f(t_n))^T \in \mathbb{K}^{n+1}.$$

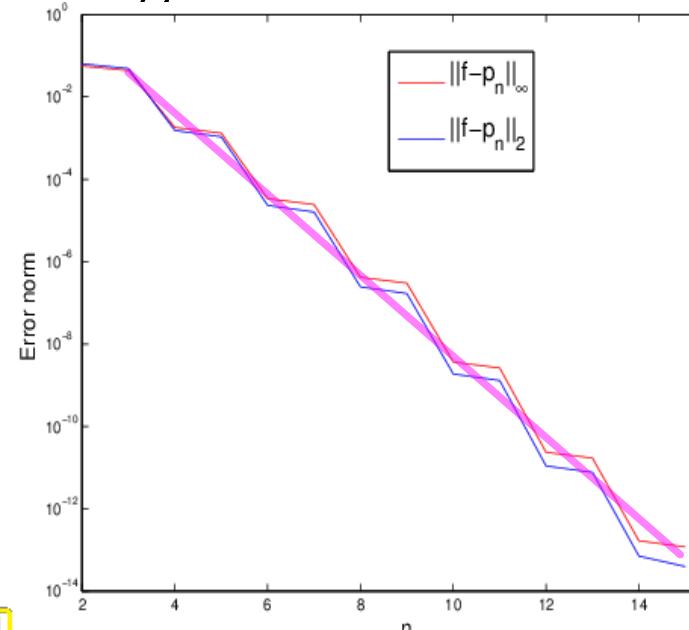
New: Consider families $\mathcal{J}_n = \{t_0^{(n)}, \dots, t_n^{(n)}\}$ of nodes, e.g.

$$\text{equidistant nodes } t_j^{(n)} = a + \frac{b-a}{n} j, \quad j = 0, \dots, n$$

\Rightarrow family of polynomial approx. schemes $\{A_n\}_{n \in \mathbb{N}}$

We study $\|f - A_n f\| \leq T(n)$ for $n \rightarrow \infty$

Ex:



$$f(t) = \sin(t)$$

$$I = [0, \pi]$$

equid. nodes

[lin-log plot!]

Fig. 211

$$\varepsilon_n := \|f - L_{\mathcal{T}_n} f\|$$

Observed:

$$\log \varepsilon_n \approx C - K n, \quad K > 0$$

$$\varepsilon_n \approx e^C (e^{-K})^n$$

$$\varepsilon_n = O(q^n) \quad \text{for } n \rightarrow \infty$$

for some $0 \leq q < 1$

\Rightarrow exponential conv. (in degree n)

rate ↓

Algebraic convergence:

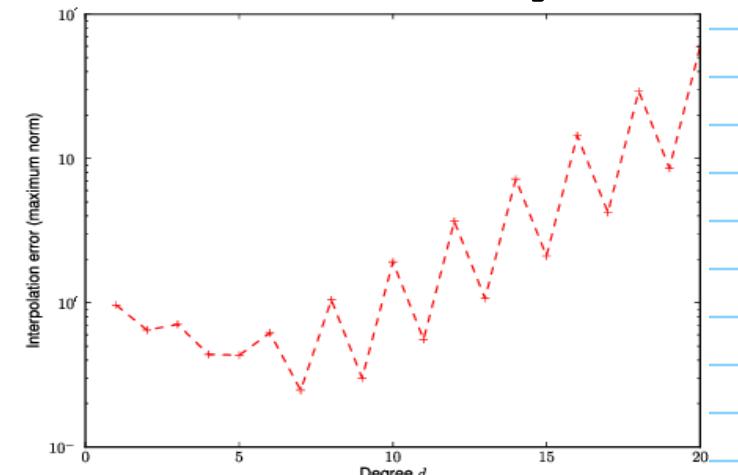
$$\|f - l_{\mathcal{T}} f\| = O(n^{-p})$$

Exponential convergence:

$$\|f - l_{\mathcal{T}} f\| = O(q^n)$$

for $n \rightarrow \infty$ ("asymptotic!")

$$\text{Ex: } f(t) = \frac{1}{1+t^2}, \quad t \in \mathbb{R}, \quad I = [-5, 5]$$



"Equidistant interpolation"

Approximate $\|f - L_{\mathcal{T}_n} f\|_{\infty}$ on $[-5, 5]$

Fig. 213

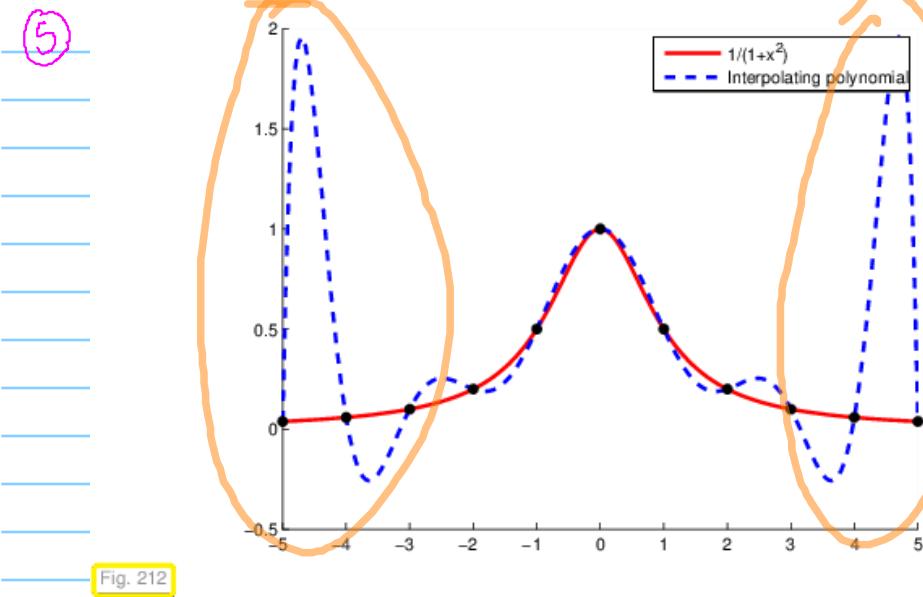


Fig. 212

Interpolating polynomial, $n = 10$ **Theorem 6.1.44. Representation of interpolation error** [?, Thm. 8.22], [?, Thm. 37.4]

We consider $f \in C^{n+1}(I)$ and the Lagrangian interpolation approximation scheme (\rightarrow Def. 6.1.32) for a node set $T := \{t_0, \dots, t_n\} \subset I$. Then,

for every $t \in I$ there exists a $\tau_t \in [\min\{t, t_0, \dots, t_n\}, \max\{t, t_0, \dots, t_n\}]$ such that

smoothness requirement

$$\underbrace{f(t) - L_T(f)(t)}_{\text{interpolation error in } t} = \frac{f^{(n+1)}(\tau_t)}{(n+1)!} \cdot \prod_{j=0}^n (t - t_j). \quad (6.1.45)$$

\downarrow $n \stackrel{?}{=} \text{degree}$

$=: w(t)$ [nodal polynomial]

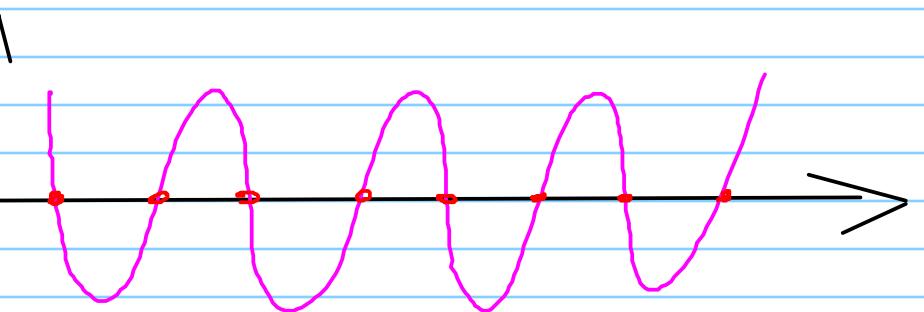
Proof: fix $t \in I \setminus T$

choose $c \in \mathbb{R}$ s.t. $f(t) - L_T f(t) - c w(t) = 0$

$$\varphi(x) := f(x) - L_T f(x) - c w(x) \in C^{n+1}$$

$\in \mathcal{P}_n$

$\varphi(t_j) = 0$ by interpolation conditions
 $\varphi(t) = 0$ by choice of c
 \hookrightarrow has $n+2$ distinct zeros



$\rightarrow \varphi'$ has $n+1$ zeros

φ'' has n zeros

:
:
:
:

$\varphi^{(n+1)}$ has at least 1 zero τ_t

$$\varphi^{(n+1)}(x) = f^{(n+1)}(x) - 0 - c(n+1)!$$

$\varphi^{(n+1)}(\tau_t) = 0$ gives the formula

$$c = \frac{f^{(n+1)}(\tau_t)}{(n+1)!}$$

□

⑥

Take sup over $t \in [t_0, t_n]$ in (6.1.45)

$$\text{Thm. 6.1.44} \Rightarrow \|f - L_T f\|_{L^\infty(I)} \leq \frac{\|f^{(n+1)}\|_{L^\infty(I)}}{(n+1)!} \max_{t \in I} |(t - t_0) \cdots (t - t_n)|. \quad (6.1.50)$$

- $f(t) = \sin(t) \quad \Rightarrow \quad \|f^{(n)}\|_\infty \leq 1 \quad \forall n \in \mathbb{N}$

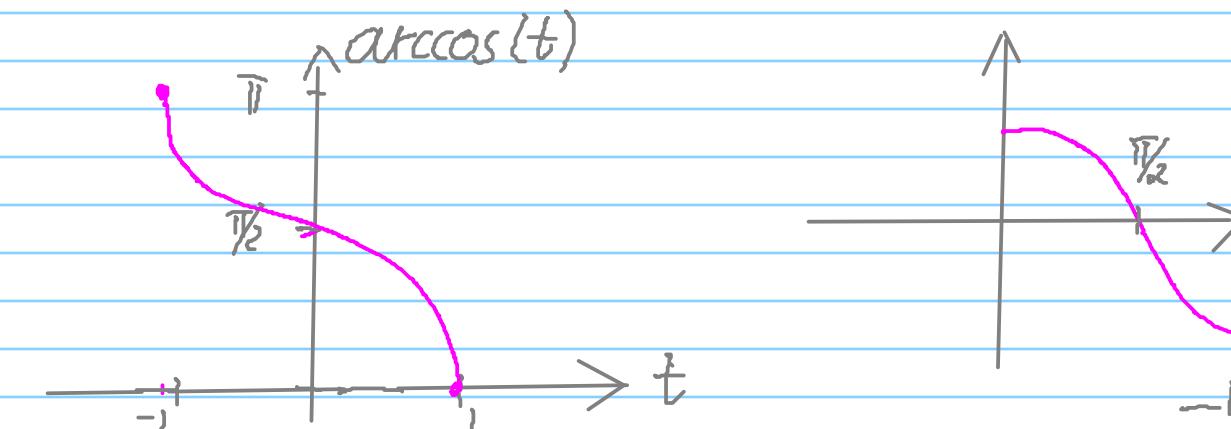
$$\begin{aligned} \|f^{(k)}\|_{L^\infty(I)} &\leq 1, \quad \Rightarrow \quad \|f - p\|_{L^\infty(I)} \leq \frac{1}{(1+n)!} \max_{t \in I} |(t-0)(t-\frac{\pi}{n})(t-\frac{2\pi}{n}) \cdots (t-\pi)| \\ &\leq \frac{1}{n+1} \left(\frac{\pi}{n}\right)^{n+1}. \quad \text{External for } t \approx \frac{\pi}{2n} \end{aligned}$$

$$I = [0, \pi]$$

$$\text{exp. conv. } \| \text{error} \| = O(q^n)$$

- $f(t) = \frac{1}{1+t^2} \Rightarrow \|f^{(n)}\|_\infty \sim 2^n n! \quad \text{for } n \rightarrow \infty$

\rightarrow Exponential blow-up of bound in (6.1.50)



4.1.3. Chebyshev Interpolation

Goal: n/f -independent *a priori* "optimal" choice of J
 ↳ beyond our control

$$\text{Thm. 6.1.44} \Rightarrow \|f - L_T f\|_{L^\infty(I)} \leq \frac{\|f^{(n+1)}\|_{L^\infty(I)}}{(n+1)!} \max_{t \in I} |(t - t_0) \cdots (t - t_n)|. \quad (6.1.50)$$

$w \in \mathcal{P}_{n+1}$, w/ leading coeff = 1 $= \|w\|_\infty \leftarrow$ make this as small as possible

Optimal choice of interpolation nodes independent of interpoland

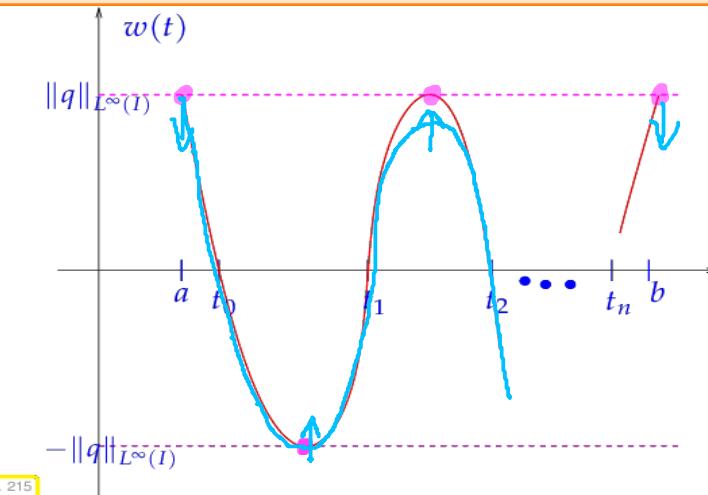


Idea: choose nodes t_0, \dots, t_n such that $\|w\|_{L^\infty(I)}$ is minimal!

This is equivalent to finding a polynomial $q \in \mathcal{P}_{n+1}$

- with leading coefficient = 1,
- such that it minimizes the norm $\|q\|_{L^\infty(I)}$.

Then choose nodes t_0, \dots, t_n as zeros of q (caution: t_j must belong to I).
 ↳ fix q already!



Heuristic demands:

- t^* extremal point of $q \rightarrow |q(t^*)| = \|q\|_{L^\infty(I)}$,
- q has $n+1$ zeros in I (*),
- $|q(-1)| = |q(1)| = \|q\|_{L^\infty(I)}$.

$|q| = \|q\|_\infty \text{ at all extrema}$

7 Solution polynomials:

Definition 6.1.75. Chebychev polynomials → [?, Ch. 32]

The n^{th} Chebychev polynomial is $T_n(t) := \cos(n \arccos t)$, $-1 \leq t \leq 1, n \in \mathbb{N}$.

$$\triangleright |T_n(t)| \leq 1 \quad \forall -1 \leq t \leq 1$$

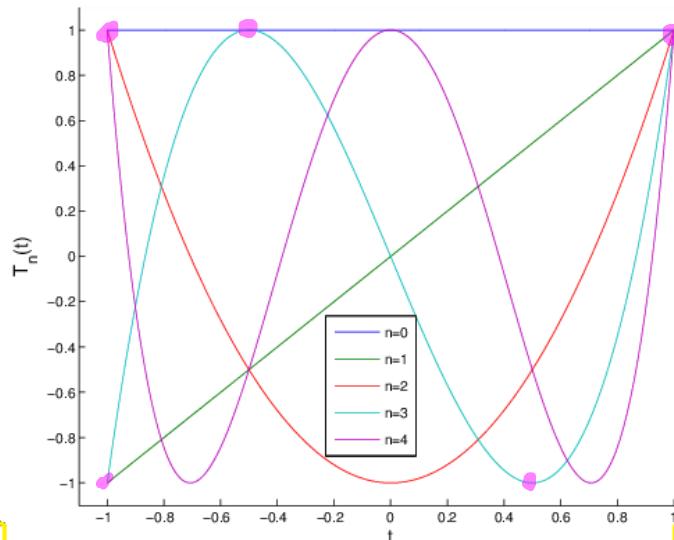
Theorem 6.1.76. 3-term recursion for Chebychev polynomials → [?, (32.2)]

The function T_n defined in Def. 6.1.75 satisfy the 3-term recursion

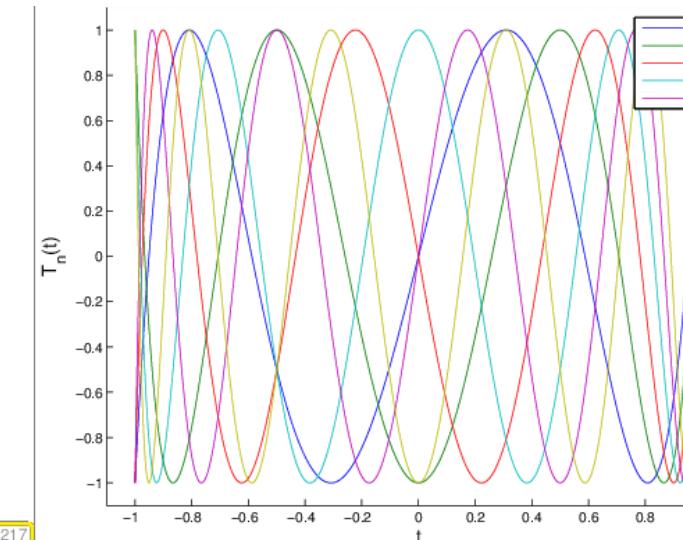
$$T_{n+1}(t) = 2t T_n(t) - T_{n-1}(t), \quad T_0 \equiv 1, \quad T_1(t) = t, \quad n \in \mathbb{N}. \quad (6.1.77)$$

$\triangleright T_n \in \mathcal{P}_n$ with leading coeff. 2^{n-1}

$$[\cos((n+1)x) = 2\cos nx \cdot \cos x - \cos(n-1)x]$$



Chebychev polynomials T_0, \dots, T_4



Chebychev polynomials T_5, \dots, T_9

\triangleright Choose t_j s.t. $w := \frac{1}{2^n} T_{n+1}$

$$\cos x = 0 \iff x \in (2N+1)\frac{\pi}{2}$$

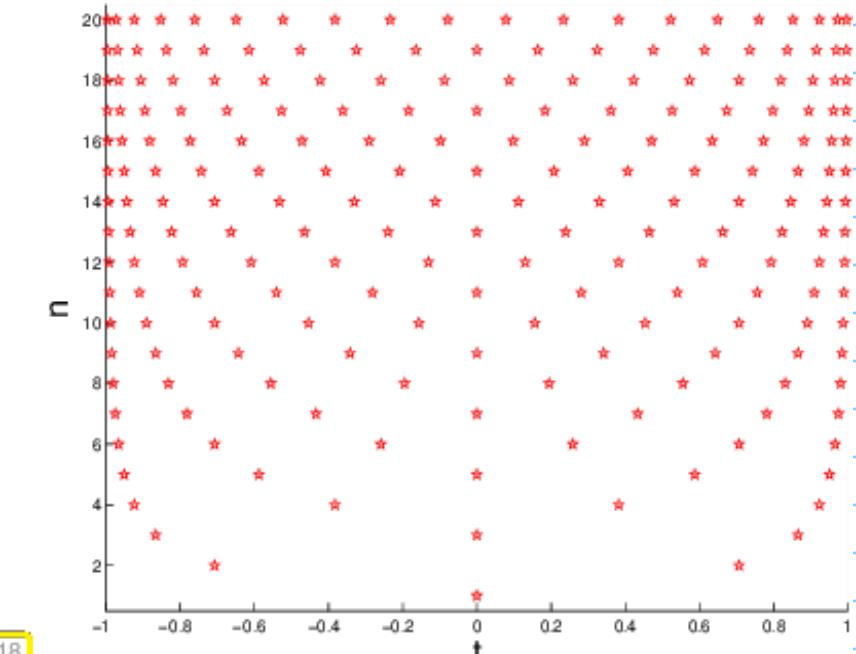
$$\triangleright t_j = \cos \frac{(2j+1)\pi}{2n} \quad [\text{Chebychev nodes}] \quad j = 0, \dots, n$$

Optimal, because

Theorem 6.1.81. Minimax property of the Chebychev polynomials [?, Section 7.1.4.], [?, Thm. 32.2]

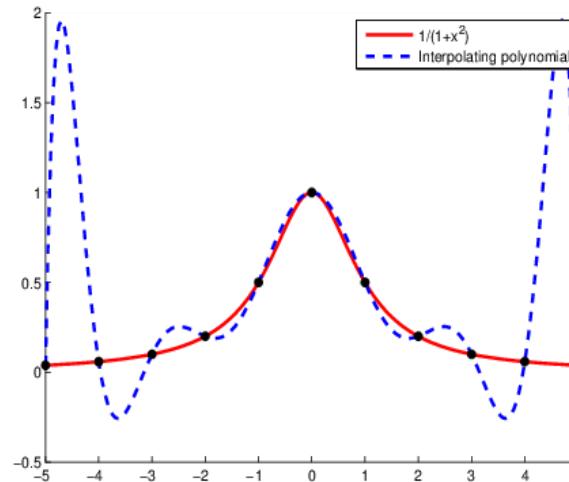
The polynomials T_n from Def. 6.1.75 minimize the supremum norm in the following sense:

$$\|T_n\|_{L^\infty([-1,1])} = \inf\{\|p\|_{L^\infty([-1,1])} : p \in \mathcal{P}_n, p(t) = 2^{n-1}t^n + \dots\}, \quad \forall n \in \mathbb{N}.$$

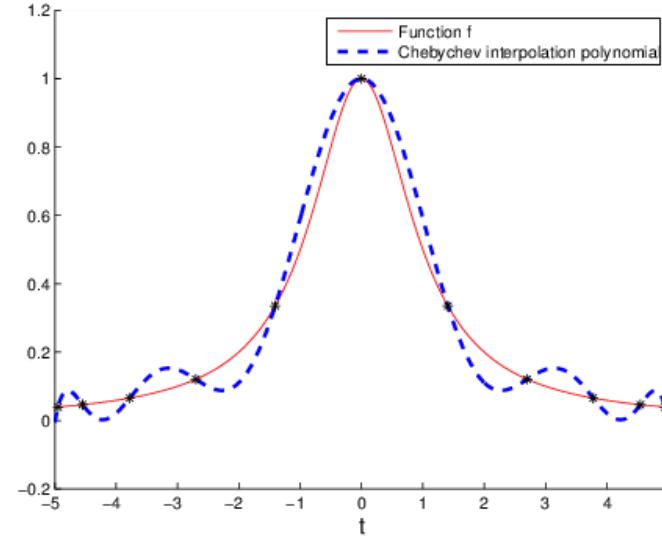


Q Chebychev nodes, cluster at endpoints

⑧ Example: $f(t) = \frac{1}{1+t^2}$ on $I = [-5, 5]$



Equidistant nodes



Chebychev nodes

On $[a, b]$: transform nodes by $\tilde{t} \rightarrow a + \frac{1}{2}(b-a)(\tilde{t}+1)$

The Chebychev nodes in the interval $I = [a, b]$ are

$$t_k := a + \frac{1}{2}(b-a) \left(\cos\left(\frac{2k+1}{2(n+1)}\pi\right) + 1 \right), \quad (6.1.86)$$

$$k = 0, \dots, n.$$

For Chebychev interpolation

$$w = \frac{1}{2^n} T_n$$

$$\Delta \|w\|_\infty = \frac{1}{2^n}$$

$$\begin{aligned} \text{D} \|f - I_T(f)\|_{L^\infty(I)} &= \|\widehat{f} - I_{\widehat{T}}(\widehat{f})\|_{L^\infty([-1,1])} \leq \frac{2^{-n}}{(n+1)!} \left\| \frac{d^{n+1}\widehat{f}}{dt^{n+1}} \right\|_{L^\infty([-1,1])} \\ &\leq \frac{2^{-2n-1}}{(n+1)!} |I|^{n+1} \|f^{(n+1)}\|_{L^\infty(I)}. \end{aligned} \quad (6.1.87)$$

$$\hookrightarrow |I| = |b-a| \text{ for } I = [a, b]$$

Interpolation error estimates and Lebesgue constant

$$\begin{aligned} I_J &\stackrel{?}{=} \text{polynomial interpolation operator for } J = \{t_0, \dots, t_n\} \\ \lambda_J &:= \sup_{x \in R^n} \frac{\|I_J x\|_\infty}{\|x\|_\infty} \\ [I_J : R^{n+1} \rightarrow P_n] \end{aligned}$$

$L_J \stackrel{?}{=} \text{approximation scheme based on } I_J$

$$[L_J : C^0(I) \rightarrow P_n : L_J = I_J [f(t_0), \dots, f(t_n)]^T]$$

$$\begin{aligned} \text{Note: } \|L_J g\|_\infty &= \|I_J [g(t_0), \dots, g(t_n)]^T\|_\infty \\ &\leq \lambda_J \max_j |g(t_j)| \\ &\leq \lambda_J \|g\|_\infty \end{aligned}$$

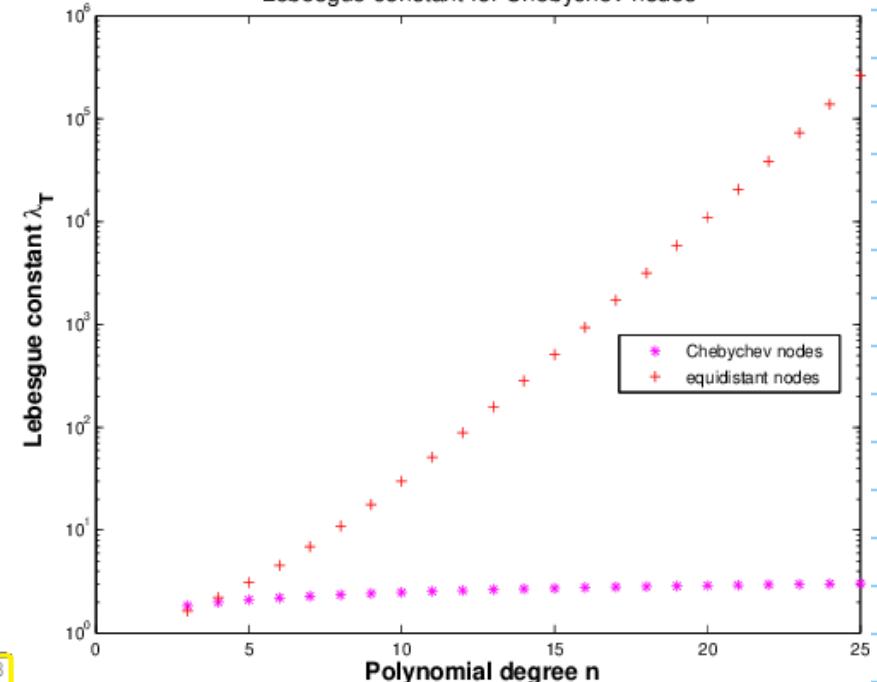
$$\begin{aligned} \|f - L_J f\|_\infty &= \|(f - p) - (L_J f - L_J p)\|_\infty, \quad p \in P_n \\ \text{interpolation error} &= \|(f-p) - L_J(f-p)\|_\infty \quad \text{by linearity} \end{aligned}$$

$$\begin{aligned} \text{Note: } L_J p &= p \\ &\leq \|f-p\|_\infty + \|L_J(f-p)\|_\infty \\ &\stackrel{(*)}{\leq} (1 + \lambda_J) \|f-p\|_\infty \end{aligned}$$

$$\|f - L_J f\|_{L^\infty(I)} \leq (1 + \lambda_J) \inf_{p \in P_n} \|f - p\|_{L^\infty(I)} \quad \forall f \in C^0(I), \quad (6.1.61)$$

⑨

Lebesgue constant for Chebychev nodes



Equidistant nodes

$$\lambda_J \geq C e^{\frac{n}{2}}$$

Chebychev nodes

$$\lambda_T \leq \frac{2}{\pi} \log(1+n) + 1$$

combine with Jackson estimates
Thm 6.1.5

$$\|f - L_T f\|_{L^\infty([-1,1])} \leq (2/\pi \log(1+n) + 2)(1 + \pi^2/2)^r \frac{(n-r)!}{n!} \|f^{(r)}\|_{L^\infty([-1,1])}. \quad (6.1.91)$$

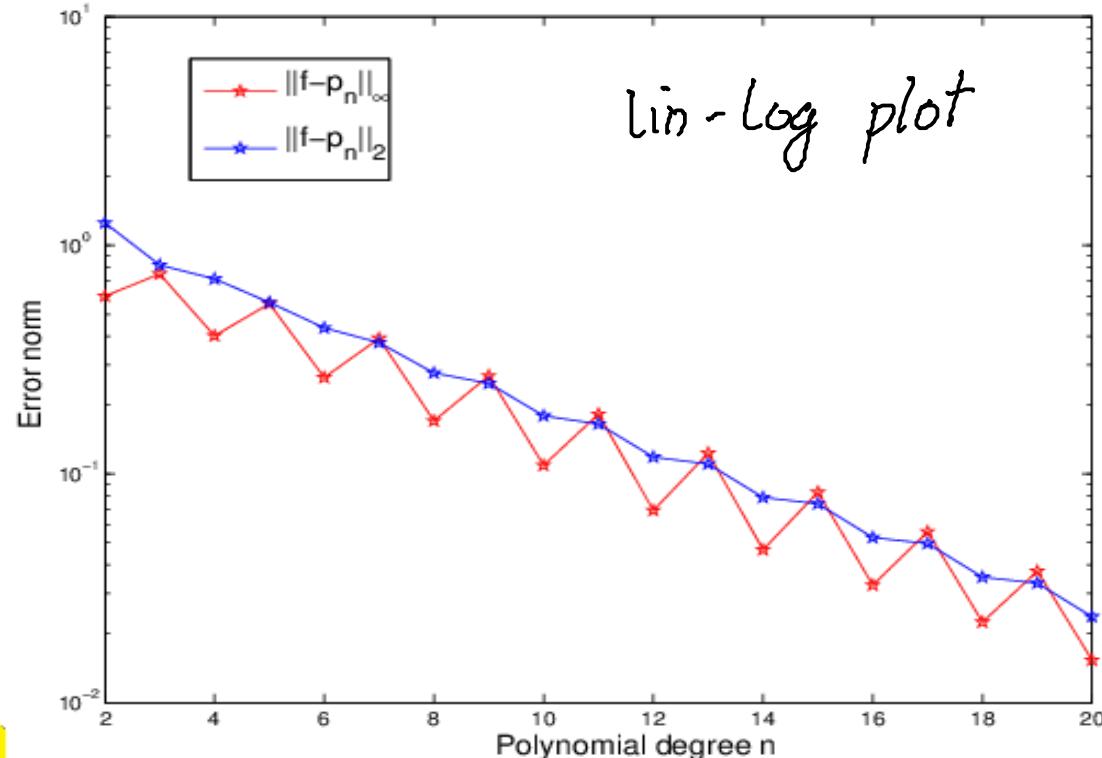
▷ Applies to $f \in C^r \Rightarrow$ obtain n -asymptotics

$$\begin{aligned} \|f - I_T(f)\|_{L^\infty(I)} &= \|\hat{f} - I_{\hat{T}}(\hat{f})\|_{L^\infty([-1,1])} \leq \frac{2^{-n}}{(n+1)!} \left\| \frac{d^{n+1}\hat{f}}{dt^{n+1}} \right\|_{L^\infty([-1,1])} \\ &\leq \frac{2^{-2n-1}}{(n+1)!} |I|^{n+1} \|f^{(n+1)}\|_{L^\infty(I)}. \end{aligned} \quad (6.1.87)$$

(usually) prevents us from extracting behavior for $n \rightarrow \infty$

Experiments : "n-cvg"

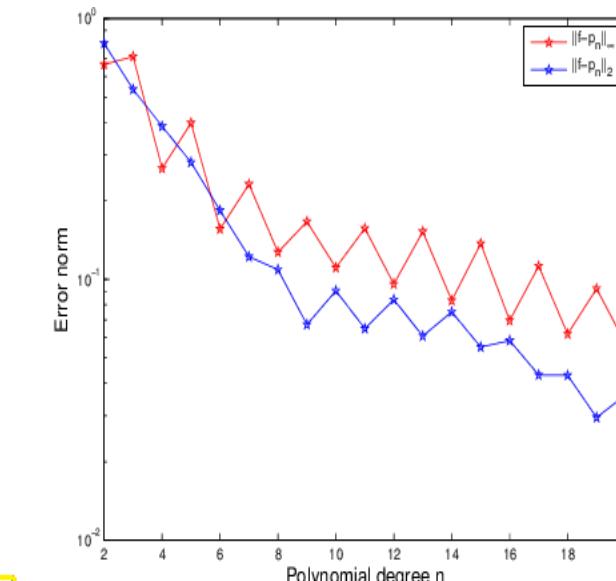
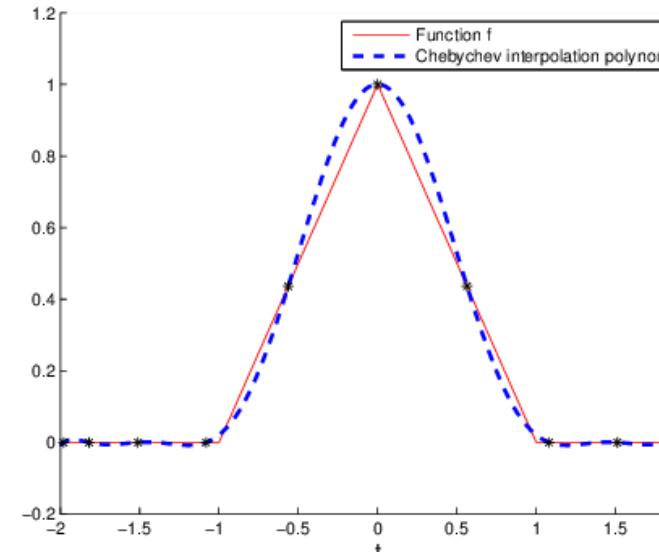
$$(i) f(t) = \frac{1}{1+t^2}, I = [-5, 5]$$



⇒ exp. cvg.

("rather generally true" for $f \in C^\infty$)

(1D) "Tent function"



Fast evaluation: "Chebychev Homer scheme"

Idea: Use 3-term recursion

$$T_j(x) = 2x T_{j-1}(x) - T_{j-2}(x)$$

$$p(x) = \sum_{j=0}^{n-1} \alpha_j T_j(x) + \alpha_n T_n(x)$$

$$(6.1.77) \sum_{j=0}^{n-1} \alpha_j T_j(x) + \alpha_n (2x T_{n-1}(x) - T_{n-2}(x))$$

$$= \sum_{j=0}^{n-3} \alpha_j T_j(x) + (\alpha_{n-2} - \alpha_n) T_{n-2}(x) + (\alpha_{n-1} + 2x\alpha_n) T_{n-1}(x)$$

another Cheb. - exp. \Rightarrow recursion

6.1.3.3. Algorithms for Chebychev interpolation

C++11 code 6.1.99: Definition of class for Chebychev interpolation

```

1 class ChebInterp {
2     private:
3         // various internal data describing Chebychev interpolating
4         // polynomial p
5     public:
6         // Constructor taking function f and degree n as arguments
7         template <typename Function>
8             PolyInterp(const Function &f, unsigned int n);
9         // Evaluation operator: y_j = p(x_j), j = 1, ..., m (m "large")
10        void eval(const vector<double> &x, vector <double> &y) const;
11    };

```

↓ Cheb. interp. polynomial

Chebychev expansion: $p(t) = \sum_{j=0}^n \alpha_j T_j(t)$

C++11 code 6.1.103: Recursive evaluation of Chebychev expansion (6.1.100)

```

2     // Recursive evaluation of a polynomial p = \sum_{j=1}^{n+1} a_j T_{j-1} at point x
3     // based on (6.1.102)
4     // IN : Vector of coefficients a
5     // evaluation point x
6     // OUT: Value at point x
7     double recclenshaw(const VectorXd& a, const double x) {
8         const VectorXd::Index n = a.size() - 1;
9         if (n == 0) return a(0); // Constant polynomial
10        else if (n == 1) return (x*a(1) + a(0)); // Value a_1 * x + a_0
11        else {
12            VectorXd new_a(n);
13            new_a << a.head(n - 2), a(n - 2) - a(n), a(n - 1) + 2*x*a(n);
14            return recclenshaw(new_a, x); // recursion
15        }
16    }

```

 \Rightarrow Cost = $O(n)$

10

Computing α_j :

$$\text{I.C.} \Leftrightarrow p(t_k) = f(t_k), \quad k = 0, \dots, n, \quad \text{for } t_k := \cos\left(\frac{2k+1}{2(n+1)}\pi\right). \quad (6.1.106)$$

$\hookrightarrow (n \times 1) \times (n+1) \text{ LSE}$

Trick: Periodize p : $T_n(t) = \cos(n \cos^{-1}(t))$

$$\begin{aligned} q(s) &:= p(\cos 2\pi s) = \sum_{j=0}^n \alpha_j T_j(\cos 2\pi s) \stackrel{\text{Def. 6.1.75}}{=} \sum_{j=0}^n \alpha_j \cos(2\pi j s) \\ &= \sum_{j=0}^n \frac{1}{2} \alpha_j (\exp(2\pi i j s) + \exp(-2\pi i j s)) \quad [\text{by } \cos z = \frac{1}{2}(e^z + e^{-z})] \end{aligned} \quad (6.1.107)$$

$$= \sum_{j=-n}^{n+1} \beta_j \exp(-2\pi i j s), \quad \text{with } \beta_j := \begin{cases} 0 & \text{, for } j = n+1, \\ \frac{1}{2} \alpha_j & \text{, for } j = 1, \dots, n, \\ \alpha_0 & \text{, for } j = 0, \\ \frac{1}{2} \alpha_{n-j} & \text{, for } j = -n, \dots, -1. \end{cases}$$

[trigonometric polynomial]

I.C. for $q \Rightarrow$ I.C. for q at nodes

$$t = \cos(2\pi s) \longrightarrow$$

$$t_k = \cos\left(\frac{2k+1}{4(n+1)}2\pi\right) \longrightarrow S_k = \frac{2k+1}{4(n+1)}$$

[equidistant nodes]

► FFT-based alg. for comp. $\beta_j \Rightarrow \alpha_j$
Cost $O(n \log n)$

MATLAB-code 6.1.111: Efficient computation of Chebychev expansion coefficient of Chebychev interpolant

```

2 // efficiently compute coefficients  $\alpha_j$  in the Chebychev expansion
3 //  $p = \sum_{j=0}^n \alpha_j T_j$  of  $p \in \mathcal{P}_n$  based on values  $y_k$ ,
4 //  $k = 0, \dots, n$ , in Chebychev nodes  $t_k$ ,  $k = 0, \dots, n$ 
5 // IN: values  $y_k$  passed in  $y$ 
6 // OUT: coefficients  $\alpha_j$ 
7 VectorXd chebexp(const VectorXd& y) {
8     const int n = y.size() - 1; // degree of polynomial
9     const std::complex<double> M_I(0, 1); // imaginary unit
10    // create vector  $z$ , see (6.1.109)
11    VectorXcd b(2*(n + 1));
12    const std::complex<double> om = -M_I * (M_PI*n) / ((double)(n+1));
13    for (int j = 0; j <= n; ++j) {
14        b(j) = std::exp(om*double(j))*y(j); // this cast to double is
15        // necessary!!
16        b(2*n+1-j) = std::exp(om*double(2*n+1-j))*y(j);
17    }
18    // Solve linear system (6.1.110) with effort  $O(n \log n)$ 
19    Eigen::FFT<double> fft; // EIGEN's helper class for DFT
20    VectorXcd c = fft.inv(b); // ->  $c = \text{ifft}(z)$ , inverse fourier
21    // transform
22    // recover  $\beta_j$ , see (6.1.110)
23    VectorXd beta(c.size());
24    const std::complex<double> sc = M_PI_2 / (n + 1) * M_I;
25    for (unsigned j = 0; j < c.size(); ++j)
26        beta(j) = (std::exp(sc*double(-n+j))*c[j]).real();
27    // recover  $\alpha_j$ , see (6.1.107)
28    VectorXd alpha = 2*beta.tail(n); alpha(0) = beta(n);
29    return alpha;
}

```

II

6.5. Approximation by piecewise polynomials

For Chebychev interpolation:

$$\begin{aligned} \|f - I_T(f)\|_{L^\infty(I)} &= \|\widehat{f} - I_{\widehat{T}}(\widehat{f})\|_{L^\infty([-1,1])} \leq \frac{2^{-n}}{(n+1)!} \left\| \frac{d^{n+1}\widehat{f}}{dt^{n+1}} \right\|_{L^\infty([-1,1])} \\ &\leq \frac{2^{-2n-1}}{(n+1)!} |I|^{n+1} \|f^{(n+1)}\|_{L^\infty(I)}. \end{aligned} \quad (6.1.87)$$

▷ reduce interpolation by shrinking the interval

Idea: piecewise interpolation on $I := [a, b]$

Tool: $\mathcal{M} = \{a = x_0 < x_1 < \dots < x_m = b\}$

Terminology:

- ◆ $x_j \hat{=} \text{nodes of the mesh } \mathcal{M}$,
- ◆ $[x_{j-1}, x_j] \hat{=} \text{intervals/cells of the mesh}$,
- ◆ $h_{\mathcal{M}} := \max_j |x_j - x_{j-1}| \hat{=} \text{mesh width}$,
- ◆ If $x_j = a + jh \hat{=} \text{equidistant (uniform) mesh}$ with meshwidth $h > 0$



Then: (local) Lagrange interpolation on cells

General local Lagrange interpolation on a mesh

- ① Choose local degree $n_j \in \mathbb{N}_0$ for each cell of the mesh, $j = 1, \dots, m$.
- ② Choose set of local interpolation nodes

$$\mathcal{T}^j := \{t_0^j, \dots, t_{n_j}^j\} \subset I_j := [x_{j-1}, x_j], \quad j = 1, \dots, m,$$

for each mesh cell/grid interval I_j .

- ③ Define piecewise polynomial interpolant $s : [x_0, x_m] \rightarrow \mathbb{K}$:

$$s_j := s|_{I_j} \in \mathcal{P}_{n_j} \quad \text{and} \quad s_j(t_i^j) = f(t_i^j) \quad i = 0, \dots, n_j, \quad j = 1, \dots, m. \quad (6.5.5)$$

Owing to Thm. 5.2.14, s_j is well defined.

p.w. linear interp.: $n_j = 1$, $t_0^j = x_{j-1}$
 $t_1^j = x_j$

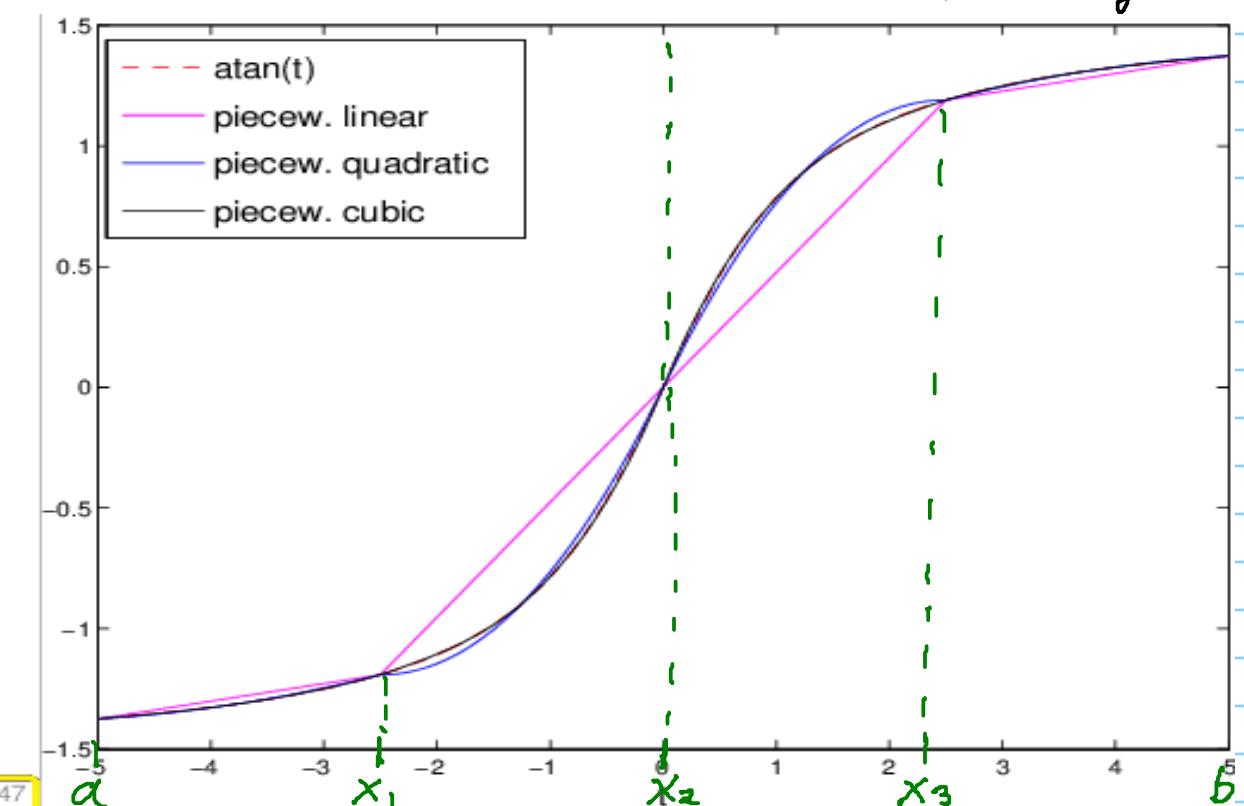


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$$\text{p.w. quadr: } n_j = 2 : t_0^j = x_{j-1}$$

$$t_1^j = \frac{1}{2}(x_{j-1} + x_j)$$

$$t_2^j = x_j$$

C^0 -p.w. interpolant guaranteed if all x_j 's are interpolation nodes!

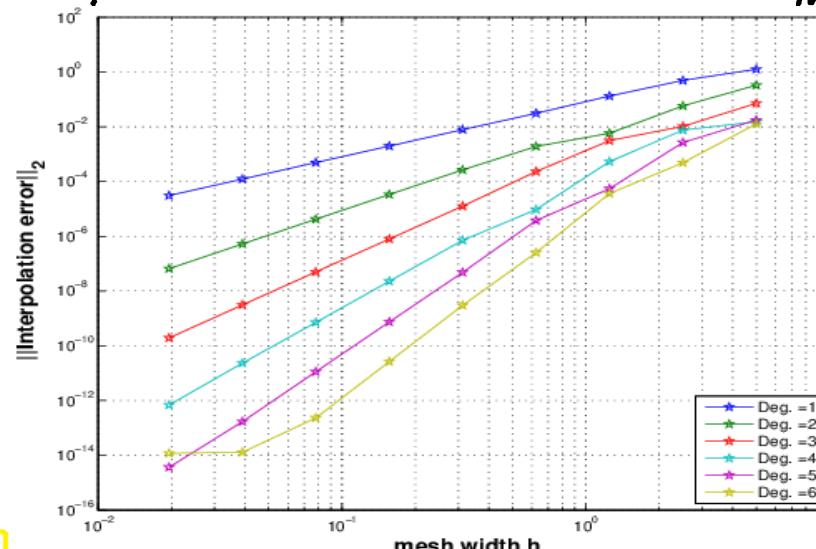
[No C' interpolant, though!]

Error estimates for special case $n_j = n$ (fixed):

Improve accuracy by $h_m \rightarrow 0$ [**h -convergence**]

Example: $f(t) = \text{atan}(t)$ on $[-5, 5]$

Equidistant mesh with $\frac{10}{h_m}$ cells, equid int. nodes



log-log plot &
linear error curves

▷ alg. conv. in h_m

Theory: Apply on $I := [x_{j-1}, x_j]$, $x_{j-1} \leq t_j \leq x_j$

$$\text{Thm. 6.1.44} \Rightarrow \|f - L_T f\|_{L^\infty(I)} \leq \frac{\|f^{(n+1)}\|_{L^\infty(I)}}{(n+1)!} \underbrace{\max_{t \in I} |(t - t_0) \cdots (t - t_n)|}_{\leq h_m^{n+1}}. \quad (6.1.50)$$

then max over all cells:

$$\Gamma \quad (6.1.50) \Rightarrow \|f - s\|_{L^\infty([x_0, x_m])} \leq \frac{h_M^{n+1}}{(n+1)!} \|f^{(n+1)}\|_{L^\infty([x_0, x_m])}, \quad (6.5.12)$$

with mesh width $h_M := \max\{|x_j - x_{j-1}| : j = 1, \dots, m\}$.

↓
Alg. conv. in h_m with rate $n+1$!

Advantage: (I) Poor smoothness of f still guarantees alg. conv. in h_m

(II) Suitable also for merely piecewise smooth functions

(III) Locality \Rightarrow update friendly

(IV) simple & cheap : cost = $O(m)$

Drawback: "Slow" algebraic convergence

(13)

p.w. quadratic ($n = 2$)

